Joint Collaborative Team on 3D Video Coding Extensions of ITU-T SG 16 WP 3 and ISO/IEC JTC 1/SC 29/WG 11
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ABSTRACT

Ed.Notes (Draft 8)

- --------- Release v5 ----------
- Accepted all change marks.
- --------- Release v4 ----------
- (Review JC00)
- (Review YK04)
- (Review GT04)
- (Review YK03)
- #29 (ED.FIX/Q0116/Recovery point SEI) , consider adding a note regarding how random accessibility is affected by the recovery point SEI message
- #27 (ED.FIX/Q0146/HandleCraAsBlaFlag and EOS) proposal 1.2, consider adding a NOTE and check if usage of HandleCraAsBlaFlag and EOS behavior is clearly described
- (Review v4_MH01): A note added on invocation of decoding processes
- (PPS/reserved flag): Add a flag in PPS for SHVC color gamut scalability
- #26 (ED.FIX/Q0091/NAL, AU) It was noted that editorial improvements are needed for the association of NAL units with an access unit, and access unit boundary detection, independent from this proposal. The language in this contribution may be useful to study.
- #1 (ED.FIX/Q0081/alpha channel persist) On reuse of alpha planes in auxiliary pictures. It was asked why there would not be a presumption that the alpha channel content would simply persist, without needing the flag to indicate it. Decision (Ed.): Delegated to editors to clarify, as necessary, that the alpha channel content persists until cancelled or updated in output order.
- #53 (SEI/Revised MV view position SEI) Revised to match HEVC draft.
- #53 (SEI/Added Multiview view position SEI message) Plain copy from AVC.
- --------- Release v3 ----------
- #44 (AUX/Q0078/concepts) Auxiliary picture concepts:
- (Review v3_MH03)
- #40 (AUX/NODOC/primary pic) Clarify that an auxiliary picture can be associated with more than one primary picture. Consider if the language associating an alpha auxiliary picture with a primary picture in the semantics of dimension_id[ ][ ] near the AuxId derivation could be moved to the alpha SEI message.
- #50 (PROF/Monochrome) Add Monochrome 8-bit profile
- (Review YK02)
- #31 (PROF/NODOC/Profile constraint) Add a profile constraint to the Scalable Main, Scalable Main 10, and Stereo Main profiles against allowing layers with duplicate values of DependencyId (or ViewOrderIdx) when AuxId equal to 0.
- #4 (HRD/Q0101/Bitstream part buffer) On Bitstream Partition Buffer. Decision (BF/Cleanup): Adopt (sub-proposals 1–11, refined as described).
- (Review GT03)
- (Review AR3)
- #47 (MISC/Q0177/EOS NAL) proposal 2: clarification of description of end of sequence NAL unit
- #23 (GEN/Q0183/SEI clean-ups) numerous small clean-ups on SEI messages.
- #9 (HRD/Q0102/NoOutputOfPriorPicsFlag) It was suggested that also the separate_colour_plane_flag should affect inference of NoOutputOfPriorPicsFlag. Decision (Ed.): Agreed (affects RExt text).
- (Review YK01)
- (Review JB0)
- #52 (SEI/Revised MV acquisition SEI) Revised to match HEVC draft.
- #52 (SEI/Added Multiview acquisition information SEI) Plain copy from AVC.
- #51 (SEI/Added Multiview scene information SEI message)
- #5 (HRD/Q0182/Bitstream part buffer) Decision (BF/Cleanup/Ed): Adopted (such that we use the main proposal for sub-proposal 1, and alternative 1 for sub-proposal 2).
- #6 (HRD/Q0182/hrd_parameters) Sub-proposal 2 Alternative 1: Clarify that the VPS hrd_parameters( ) syntax structure that applies to the layer set which is associated with the bitstream partition initial arrival time SEI message is used to determine the lengths of the nal_initial_arrival_delay[i] and vcl_initial_arrival_delay[i] syntax elements. Decision (BF/Cleanup/Ed): Adopted alternative 1 for sub-proposal 2
- (Review v3_MH01)
- (Review GT02)
- #3 (HS/Q0041/hybrid scalability) The proposed text was endorsed, with non-editorial open issues considered as follows …:

- --------- Release v2 ----------
- (Review MH01)
- (Review YK0)
- #45 (PROF/H0126/Stereo main) Phrasing used in specifying the Stereo Main profile.
- #39 (AUX/Q0078/conformance): mechanism for signaling a profile/tier/level conformance point for auxiliary pictures
- #49 (MISC/Q0247/frame-field information SEI message)
- #24 (MISC/Q0078/scan and pic type) , Items 3 b,c and 4, clarifying which pictures in an output layer sets are applied the values of general_progressive_source_flag, general_interlaced_source_flag, general_non_packed_constraint_flag and general_frame_only_constraint_flag.
- #25 (ED.FIX/Q0055/Set TargetOutputLayerSetIdx) Third Proposal; Modification of TargetOutputLayerSetIdx setting procedure. Refer to editors to improve C.1 description of setting the value of TargetOutputLayerSetIdx
- #38 (DBP/Q0154/VPS DPB) Proposal in C.5.2.1: Add in the decoding process that when a new VPS is activated, all pictures in the DPB are marked as unused for reference
- #10 (HRD/Q0154/DPB Flushing and parameters) On picture flushing and DPB parameters Decision: Adopted (some details to be discussed further in BoG).
- (Review AR2)
- #33 (PROF/Q0160/alt_output_flag) v2: Add constraint to stereo main profile that it must contain exactly two texture views, and add a note to state that the constraint implies a restriction that alt_output_flag equal to 0.
- #35 (SEI/Q0189/SEI message for indicating constraints on TMVP) Proposal 2.3, SEI message for indicating constraints on TMVP
- #2 (AUX/Q0081/primary) Decision: Remove the constraint that an alpha picture must be accompanied by a primary picture.
- #48 (SPS/PPS extension cleanups) Alignment with RExt
- (Review JB2) Modify syntax for selectable overlays to avoid mention of DependencyId
- #34 (MISC/Q0189/slice temporal mvp enabled flag) Proposal 2.2, clarification of semantics of slice temporal mvp enabled flag
- (Added semantics of slice_temporal_mvp_enabled_flag)
- (Review GT1)
- #42 (DBP/NODOC/sharing) Remove sub-DPB sharing and processes that mark inter-layer reference pictures as "unused for reference"
- (Review AR1)
- (Review JB1)
- #36 (RPS/Q0100/constraint to semantics) v3, add constraint to RPS semantics
- (Added num_negative_pics and num_positive_pics sem.)
- #32 (POC/Q0142/poc_lsb_not_present_flag) v2: Add semantic constraints to poc_lsb_not_present_flag.
- #8 (HRD/Q0102/sps_max_dec_pic_buffering_minus1) Sub-proposal 2: A semantics bug fix is proposed for sps_max_dec_pic_buffering_minus1 as a bug-fix. In discussion, the first option was preferred. Decision (BF/Cleanup/Ed.): Adopt.
- #30 (MISC/Q0102/loop index) proposal 3, change the max loop index for signaling bit rate and pic rate info to MaxSubLayersInLayerSetMinus1
- (Moved MaxSubLayersInLayerSetMinus1[i] derivation)
- (Review GT0)
- #13 (GEN/Q0108/STSA TemporalId) Agreed to remove restriction from proposal 2, to allow STSA pics of non-base layers to have TemporalId equal to 0.
- (Add nuh_temporal_id_plus1 semantics)
- #37 (SEI/Q0253/layer not present), modified semantics of layers not present SEI message to correct bug introduced during editing
- #11 (SEI/Q0045/Overlay) Proposal for an SEI message on selectable overlays. Decision: Adopt (modified for variable-length strings).
- (Review JB0) Bug fixes to vps_vui_present_flag and vps_vui_offset
- --------- Release v1 ----------
- (Review AR0)
- #21 (PS/Q0195/constraint update_ref_format_flag) proposal 2: add a semantic constraint on the value of update_ref_format_flag
- #20 (PS/Q0195/syntax table rep format) proposal 1: restructure syntax table for sending of rep_format_idx_present_flag and vps_num_ref_formats_minus1
- #22 (MISC/Q0177/inference sps_temporal_id_nesting_flag) proposal 1: modify inference rule for sps_temporal_id_nesting_flag when it is not present
- #28 (Ed.Fix/Q0054/vps_profile_present_flag) proposal bug fix in the semantics of vps_profile_present_flag

- #19 (PS/Q0165/presence of num_add_output_layer_sets) proposal 2. change condition for presence of num_add_output_layer_sets to avoid sending it when there is only one layer set.
- #18 (PS/Q0165/disallow an empty layer set) proposal 1.a), add a constraint to disallow an empty layer set
- #17 (RPS/Q0060/condition refLayerPicIdc) Proposal 2: Add a condition to the derivation of refLayerPicIdc of (TemporalId == 0)
- #46 (Ed.Fix/Q0146/slice_segment_header_extension_data_bit) proposal 1.3 specification bug fix
- #15 (IRAP,POC/Q0146/inference of poc_msb_val_present_flag) Proposal 1.1: Change inference rule in semantics of poc_msb_val_present_flag
- #16 (IRAP,POC/Q0146/inference poc_reset_info_present_flag) Proposal 1.4, Add an inference value of 0 when poc_reset_info_present_flag is not present
- #14 (GEN/Q0158/Highest Tid Annex C) In proposal 2 a modification is proposed to the range of values for HighestTid in Annex C. Proposal 2 is asserted to reduce the number of tests than an encoder has to make for conformance. Agreed to Proposal 2.
- #12 (GEN/Q0108/TSA,STSA alignment) Agreed to remove restriction from 1, to no longer require TSA or STSA alignment of dependent layers with the current layer.
- #25 (ED.FIX/Q0055/Rename TargetOutputLayerSetIdx) Second proposal, substitute ‘TargetOptLayerSetIdx’ with ‘TargetOutputLayerSetIdx’

Ed.Notes (Draft 7)

- --------- Release v8 ----------
- Accepted all change marks.
- --------- Release v7 ----------
- (Review GT08)
- (Review AR4)
- --------- Release v6 ----------
- (Review GT07)
- (Editorial cleanups) merged from SHVC draft 5_v4.
- --------- Release v5 ----------
- (Added SEI headings)
- (Review GT07)
- (Review AR03)
- (Review GS02) Pluralization, extra spaces, extra brackets, spaces before opening brackets, spaces missing before closing brackets, non-breaking spaces versus ordinary spaces, parentheses around equation numbers in text cross-references, changing "have to" to "need to", changing "re-calculated" to "recalculated", removing hyphen in "no-reference picture", removing hyphen in "stereo-pair", removing hyphen in "line-segment approximation", note numbering fixes, changing "described" to "specified", changing value ranges in table from, e.g. "3-127" to "3..127".
- --------- Release v4 ----------
- (Review JB06)
- (Review GT06)
- (Fix sps_max_dec_pic_buffering_minus1 infer.)
- (Review AR02)
- (Review JC02)
- (From Review GJS01 in P1008_v1_g2) Note numbering fixes and typographical issues. Maybe not all.
- (Review JB04)
- (ED.FIX/P0181/PPS activation) #33 Proposed to constrain the values of nuh_layer_id, TemporalId and pps_pic_parameter_set_id of picture parameter set NAL units to ensure that picture parameter set can be uniquely identified during PPS activation process. It was remarked that if a slice with nuh_layer_id > 0 refered to a PPS_id which had been sent with a higher value of nuh_layer_id, that would be a non-conforming bitstreams.It was suggested that the current specification already disallows some of the use cases described in the contribution as problematic. It was suggested that the editors study the text to see if clarity could be improved.
- (Review AR0)
- (SEI/P0133/Merge other modifications to 3.8)
- (SEI/P0133/Recovery point SEI) #28 Decision: Adopt change to recover point semantics only (-v3)
- (CopyFromBaseSpec/Reovery Point SEI)
- (Fix P0192)
- (Review JO02)
- (HRD/P0138/HRD parameters for bitstreams excluding) #6 Decision: Adopt (as revised in updated contribution, with the specification of a flag in the BP SEI message).
- --------- Release v3 ----------
- (Review GT05)
- (Review JB03)

- (HRD/P0192/sub-DPB) #12 Establish sub-DPBs based on the representation format indicated at the VPS level. It was suggested that the expressed shared capacity limit would need to be less than or equal to the sum of the individual capacity limits. Decision: Adopt as modified. Further study is encouraged on profile/level constraint selections.
- (Review JO)
- (SEI/P0123/Alpha channel info) #25 Add alpha channel information SEI message Decision: Adopt. Constrain the bit depth indicated to be equal to the coded bit depth of the aux picture.
- (SPS/P0312/SHVC reserved flag) The flag will be used for the syntax vert_phase_position_enable_flag in SHVC draft
- (VPS/O0215/SHVC reserved flag): this flag will be used for the syntax cross_layer_phase_alignment_flag in SHVC draft.
- (VPS VUI/O0199,P0312/SHVC reserved flags) the 3 reserved bits will be used for the syntaxes single_layer_for_non_irap_flag, higher_layer_irap_skip_flag and vert_phase_position_not_in_use_flag in SHVC draft.
- (Review JC01) SHVC bug trac No. 10.
- (MISC/P0182/BL PS Compatibility flag) #13 Define the flag (in VPS VUI) with the proposed semantics, without specifying an associated extraction process. Editors to select the position in the VPS VUI.
- (MISC/P0079/NumActiveRefLayerPics) #18 Modification of derivation of variable NumActiveRefLayerPics.
- (MISC/P0068/all irap idr flag) #21 Add flag in VUI to indicate that all IRAP pictures are IDRs and that all layer pictures in an AU are IDR aligned, from JCTVC-P0068 proposal 1.
- (SEI/P0204/sub-bitstream SEI) #26 Add sub-bitstream property SEI message. Decision: Adopt
- --------- Release v2 ----------
- (Review JB02)
- (POC/P0041/Fixes) For each non-IRAP picture that has discardable_flag equal to 1 to have NUT value indicating that it is a sub-layer non-reference picture.
- (POC/P0056/layer tree poc) #4 Proposal 1: If the POC reset approach is adopted as the basis for multi-layer POC derivation, it is proposed to derive the POC anchor picture from the previous TID0 picture (that is not a RASL picture, a RADL picture or a sub-layer non-reference picture and not with discardable_flag equal to 1) of the current layer or any of its reference layer. This is asserted to improve loss resilience and reduce bit rate overhead. Decision: Adopt Proposal 1 (with the suggested modifications – with text provided as P0297).
- (POC/P0041/POC reset) #3 It was remarked that we should require each non-IRAP picture that has discardable_flag equal to 1 to have NUT value indicating that it is a sub-layer non-reference picture. This was agreed. Decision: Adopt (with constraint for discardable_flag as described above)
- (Review GT05)
- (VPS/P0300/alt output layer flag) #27 Change alt output layer flag to be signalled within the loop of output layer sets, from JCTVC-P0300-v2. Decision: Adopt.
- (VPS/P0125/VPS extension offset) #24 Decision: Keep it as a reserved FFFF value.
- (VPS/P0307/VPS VUI extension) #23 Decision: Adopt modification in P0307.
- --------- Release v1 ----------
- (Review GT04)
- (Review CY01)
- (Review JB01) Improvements to PPS extension type flags semantics
- (VPS/P0306/ue(v) coded syntax elements) #22 Several minor modifications to the VPS syntax, consistent with eliminating the previous intention to avoid ue(v) parsing in the VPS
- (VPS/P0156/Num of output_layer_flag) #10 Proposal 3: The output_layer_flag[i][j] is signalled for j equal to 0 to NumLayersInIdList[lsIdx] inclusive. It was remarked that we might be able to just assume that the top layer is always output; however, this was not entirely clear , so the safe thing to do may be to also send the flag for this layer.
- (HRD/P0156/MaxSubLayersInLayerSetMinus1) #7 Proposal 1: signal, in the VPS extension, the DPB parameters for an output layer set for sub-DPBs only up to the maximum temporal sub-layers in the corresponding layer set
- (OTHER/P0187/NoOutputOfPriorPicsFlag) #1 Inference of NoOutputOfPriorPicsFlag and proposes to take into account colour format and bit depth for the inference in addition to spatial resolution
- (ED.FIX/P0130/il ref pic set no reference pic) #34 For proposal 5, delegated to editors
- (ED.FIX/P0052/Inf. sub_layer_dpb_info_present_flag) #30 Proposal 3. Semantics of sub_layer_dpb_info_present_flag in dpb_size( ) syntax structure. Seems to be editorial. Delegate to the editors
- (MISC/P0130/discardable not in inter-layer RPS) #20 Add constraint restricting pictures marked as discardable from being present in the temporal or inter-layer RPS,
- (MISC/P0130/EOS NAL layer id) #19 Require that end of bitstream NAL unit shall have nuh_layer_id equal to 0, from JCTVC-P0130. Decoders shall allow an end of bitstream NAL unit with nuh_layer_id > 0 to be present, and shall ignore the NAL unit.

- (GEN/P0166/pps_extension) #17 Add PPS extension type flags for conditional presence of syntax extensions per extension type, aligned with the SPS extension type flags, from JCTVC-P0166. Further align the SPS extension type flags syntax between REext and MV-HEVC/SHVC
- (SPS/P0155/sps_sub_layer_ordering_info) #16, #32 Not signal the sps_max_num_reorder_pics[], sps_max_latency_increase_plus1[], and sps_max_dec_pic_buffering_minus1[] syntax elements in the SPS when nuh_layer_id > 0.
- (SPS sub layer ordering info) Added sps sub-layer info from base spec.
- (Reorder semantics in SPS) to match order in syntax table.
- (VPS/P0076/video signal info move) #15 Move video signal information syntax structure earlier in the VPS VUI.
- (VPS/P0048/profile_ref_minus1 rem) #14 Remove profile_ref_minus1 from the VPS extension, from JCTVC-P0048
- (VPS/P0295/Default output layer sets) #5 Discussion from (P0110). Decision: Three-state approach (text in P0295, decoder shall allow 3 to be present and shall treat 3 the same as the value 2).

Ed. Notes (Further corrections)
- (Review GT03) #11 Further fixes on output layer sets.
- (Review GT02) Minor typo corrections.
- (Review GT01) .#8 #9 #31 Corrections related to output layer sets

Ed.Notes (Draft 6)
- --------- Release v6 ----------
- Accepted all change marks.
- --------- Release v5 ----------
- (Review GT05)
- (Review GT04)
- (Review YK01)
- --------- Release v4 ----------
- (Review MH05)
- (Review YK00)
- (Review MH04)
- (HRD/O0164/Multilayer HRD) #15 Decision: Adopt, modified as follows: It was suggested to constrain the stalling based on the relative cpb removal times, which must be in decoding order. The "du_based_bpb_sync_flag" is not needed, in view of this. SEI in the highest layer of the layer set or (inclusive "or") VPS VUI is used to carry the parameters (at encoder discretion). SEI in higher layer and SEI in VUI do not need to repeat information available in some lower layer. Shall be after APS SEI and buffering period SEI and before all other SEI of all layers except other HRD related SEI.
- Merged the specifications of DPB operations in subclause F.13 and its subclauses to Annex C and its subclauses.
- Unification of active layer SPS and active SPS.
- (HRD/O0217/Sub-DPB based DPB operations) #13 Decision: Adopt – Specify a separate DPB capacity for each layer – no sharing of capacity across layers – each layer has its own parameters (max pictures, max latency, max reordering). This proposal would specify distinct parameters for each "output layer set" and to change the definition of an operation point to be specific to an output layer set instead of a 'layer set". Decision: Adopted this aspect as well.
- (HRD/O0266/Flushing decoded picture) #14 Decision: Adopt (harmonize with O0149 proposal 3 and supply text in a revision of O0266).
- (Fix MV-HEVC trac 47) Missing a close-bracket on slice_pic_order_cnt_lsb
- (Fix MV-HEVC trac 48) Wrong element name of poc_lsb_present_flag[] on slice_segment_header( ).
- --------- Release v3 ----------
- (Review MH03)
    - Modified the integration of "(RALS/O0139/Prop4) #8 layer initialization picture (LIP)" to support also layer-wise start-up where not all pictures are present in the initial IRAP access unit.
    - Modified the integration of "(POC/O0117/Modify PicOrderCntVal of prevTid0Pic) #35" to differentiate between PrevPicOrderCnt values of different layers
    - Added editor's notes related to "(POC/O0211/Fix ambiguity) #38" on contraints that the approach imposes.
- (POC/O0140,O0213/Ed. Note) #39 Decision (Non-Normative): Add a note to explain what an encoder needs to do to avoid the problem – MMH to provide the wording.
- (RALS/O0139/Prop4) #8 layer initialization picture (LIP): A picture that is an IRAP picture with NoRaslOutputFlag equal to 1 or that is contained in an initial IRAP access unit, of which LayerInitializedFlag[refLayerId] is equal to 1 for all values of refLayerId equal to RefLayerId[nuh_layer_id][j], where j is in the range of 0 to NumDirectRefLayers[nuh_layer_id] − 1, inclusive. Decision (Ed.): Agreed in spirit. Editors to determine exact phrasing.

- (RALS/O0139/Prop2/SPS activation) #7 Decision (Ed): Agreed in spirit that we should not allow activation of a new SPS by an enhancement layer non-IRAP picture that is not the first picture in the bitstream in that enhancement layer (that is not an LIP picture) and should not allow a "normal" CRA in an enhancement layer to activate a different SPS than what was already referred to by the preceding pictures in decoding order in that enhancement layer. (Editors to figure out how to phrase this in specification language.)
- (POC/O0117/Modify PicOrderCntVal of prevTid0Pic) #35 Modification of the PicOrderCntVal of prevTid0Pic and modification to the decoding process for reference picture set, to address problems found for cross-layer POC alignment.
- (POC/O0211/Fix ambiguity) #38 Modify POC derivation to correct an ambiguity in the spec.
- --------- Release v2 ----------
- (Review GT03) Removal of clarified editor's comments.
- (Review MH02): review of scaled reference layer offsets, (SHVC/O0098/Scaled ref layer offset) #36.
- (SHVC/O0098/Scaled ref layer offset) #36 Modify signalling of scaled reference layer offsets to allow signalling of any lower layer, rather than just a direct reference layer, in order to enable alignment of auxiliary pictures. In further JCT-VC and JCT-3V discussion, it was also agreed to use the same offset signalling for MV-HEVC as well as SHVC
- (Review JB02) Move location of chroma_and_bit_depth_vps_present_flag
- (PS/O0179/Rep. Format) #18 Add flag in rep_format( ) syntax structure to control sending of chroma and bit depth related parameters, as proposed in the v2 version of JCTVC-O0179.
- (Review GT02) Minor cleanups, mainly related to F0169.
- (SEI/F0169/depth rep info SEI) #40 Depth representation information SEI message for auxiliary pictures.
- (AUX/O0358/Reserved range) #16 Decision: Define a range of values of auxiliary picture types, the values 0x80-0x8F, for which the interpretation is specified externally or by other information in the bitstream (e.g., some SEI message to be defined later).
- (AUX/O0135/default_one_target_output_flag) #2 Carriage of auxiliary pictures. Decision: Relating to section 6, regarding auxiliary picture ID as part of the definition of the semantics of default_one_target_output_flag, adopt first variant.
- (AUX/O0041/HLS auxiliary picture layers) #1 Decision: Use nuh_layer_id to identify auxiliary pictures and map them to an interpretation (roughly per O0041, as clarified below). Do not make a blanket constraint that prohibits dependencies for auxiliary picture, but impose that constraint for the specific ones listed in O0041 Decision: Adopted the general structure and alpha and depth types. It was agreed that the terminology should be rephrased to not directly link the concepts auxiliary/primary to the concepts of normative/supplemental.
- --------- Release v1 ----------
- (Review JB01)
  - O0142: Added restriction on sps_extension_type_flag[i] in stereo main profile
  - O0096: Modified restriction on number of rep formats to apply to VPS syntax element, not SPS
  - O0120: Renamed sub_layers_vps_max_minus1_present_flag to vps_sub_layers_max_minus1_present_flag
  - O0062: Changed poc_lsb_present_flag to poc_lsb_not_present_flag.
  - O0096: Introduced variables VpsInterLayerSamplePredictionEnabled[i][j] and VpsInterLayerMotionPredictionEnabled[i][j]
- (Review MH01):
  - Typo: the first syntax element in vps_vui( ) is cross_layer_pic_type_aligned_flag in the syntax table.
  - The integration of JCTVC-O0220/Prop2 fixed to refer to the correct decoding process for generating unavailable reference pictures.
  - The integration of JCTVC-O0149/Prop1 moved from F.8.3.2 to 8.3.2.
  - Subclause 8.3.2 corrected to not cause marking of all pictures (with any nuh_layer_id) as "unused for reference" when the base layer contains an IDR picture with cross_layer_bla_flag equal to 0.
- (Review GT01)
- (Review YY01)
- (PS/O0096/rep format syntax element length) #20 Modification of length to 8 bit as decided later in trac.
- (Gen/O0153/output highest layer) #28 Add a flag in the VPS to indicate if startup process should output the highest available layer if the target output layer is not available.
- (RALS/O0139/Prop5) #9 Problem: It is asserted that if cross_layer_irap_aligned_flag is equal to 1 and two pictures having no dependency on each other in an access unit have different nal_unit_type values, the POC value alignment cannot be guaranteed. Decision (Ed): Agreed. The drafted intent was to enforce alignment by the flag only within each dependency tree. Editors to correct the text as necessary.
- (RALS/O0139/Prop1) #6 Proposal: Invoke the layer-wise start-up process for a base-layer CRA picture with HandleCraAsBlaFlag equal to 1. Decision (Ed): Check/clarify text as necessary if not already addressed (intent agreed in spirit).

- (RALS/O0220/Prop2) #5 Invoke the decoding process for generating unavailable reference pictures (subclause F.8.1.3) again when the current picture is the IRAP picture with NoRaslOutputFlag equal to 1. Decision (Ed BF): Check/clarify text as necessary if not already addressed (intent agreed in spirit).
- (RALS/O0220/Prop1 Alt2) #4 NoRaslOutputFlag is set to equal to 1 when the current picture is an IRAP picture, LayerInitializedFlag[k] = 0, and LayerInitializedFlag[refLayerId]=1 for all values of refLayerId equal to RefLayerId[k][j], where j is in the range of 0 to NumDirectRefLayers[k]−1, inclusive. In this solution, LayerInitializedFlag[k] is set equal to 1 after setting NoRaslOutputFlag to 1. Decision (Ed. BF): Adopted
- (RALS/O0149/Prop1) #10 Proposal: A base-layer IRAP picture that initiates the layer-wise start-up process (i.e. has NoClrasOutputFlag equal to 1) causes marking of all pictures in the DPB as "unused for reference". Decision (Ed): Agreed.
- Rejected changes erroneously integrated under label (RALS/O0149/Prop2), since they are related to Prop1 and Prop3 of O0149.
- (Gen/O0137,O0200,O0223,Layer id) #32 Add (editorial equivalent of) "The value of nuh_layer_id shall be in the range of 0 to 62. The value of 63 for nuh_layer_id is reserved for future use by ITU-T | ISO/IEC. Decoders shall ignore all data that follow the value 63 for nuh_layer_id in a NAL unit." and specify that vps_max_layers_minus1 shall not be equal to 63, but decoders shall allow that value to appear in the bitstream. Specify that the value 63 is interpreted the same as the value 62 (e.g., MaxLayersMinus1 = Min(62, vps_max_layers_minus1) and subsequently refer to MaxLayersMinus1 instead of vps_max_layers_minus1)
- (PS/O0109/default_one_target_output_layer_idc) #25 To change default_one_target_output_layer_flag to a two-bit default_one_target_output_layer_idc, and reserve the values 2 and 3
- (VUI/O0226/Mod tile WPP) #37 Modifications to the VUI indicators of tile and WPP alignment related syntax elements, from the r1.
- (Misc/O0062/POC LSB present condition) #31 Modification as decided later in trac.
- (RALS/O0149/Prop2): #11 Proposal: A new slice_reserved_flag is taken into use to indicate if a base-layer IDR picture initiates the layer-wise start-up process. Decision: Adopt (the bit should not be required to be present; if present should be the bit after the discardable_flag, and discardable_flag should be the first one of the three, and the poc reset flag is not required to be present).
- (Fix missing "!" before all_ref_layers_active_flag)
- (PSEM/O0142/Conditional extension syntax) #3 Adopt JCTVC-O0142 (as a structure to be used to switch whatever extensions we define in SPS, not necessarily committing to having these extensions be separate for each extension, but the current plan unless decided otherwise is to use one flag for range extensions syntax presence and one flag for SHVC+MV-HEVC extension syntax presence)
- (PS/O0118/visual signal info in vui per layer) #33 Add visual signal information (video_format, video_full_range_flag, colour_primaries, transfer_characteristics, matrix_coeffs) per layer to the VPS VUI, from v2 version of JCTVC-O0118.
- (Misc/O0062/POC LSB present) #31 The proposal's "option 3" is to add a flag in the VPS for each EL to control whether these LSBs are present or not (for IDR pictures), and when not present, the LSBs are inferred to be equal to 0. Decision: Adopted (as described herein).
- (ILDSD/O0225/signal max_tid_il_ref_pics per layer) #30 2nd proposal of JCTVC-O0225 regarding signalling of max_tid_il_ref_pics per layer, based upon relation to SCE2 on single loop decoding. Decision: Adopted.
- (ILDSD/O0225/max_tid_il_ref_pics RPL const.) #27 Change derivation of NumActiveRefLayerPics to consider max_tid_il_ref_pics.
- (ILDSD/O0120/sub_layers_vps_max_minus1 RPL const) #34 Modify inter-layer reference picture list default construction to incorporate max temporal sub-layers per layer syntax elements in VPS extension, from r2 version of JCTVC-O0120.
- (ILDSD/O0120/sub_layers_vps_max_minus1) #26 Add syntax elements to signal max temporal sub-layers for each layer in the VPS, with a gating flag, from JCTVC- option 2.
- (PS/O0223/Cross layer alignment type) #29 Add a flag in VPS VUI to indicate cross layer pic type alignment. Move cross_layer_irap_aligned_flag to VPS VUI and make presence condition on added flag
- (PS/O0092/Sharing SPS PPS) #17 Restrict sharing of SPS and PPS across layers to avoid creating problems during sub-bitstream extraction, based on modification of proposals in JCTVC-O0059 and JCTVC-O0092, reflected in the v2 version of O0092.
- (PS/FIX/N0092/Rep. Format) #19 Inferences.
- (PS/O0096/rep format) #20 Modify the SPS syntax for layers with nuh_layer_id > 0 to signal a reference to a rep_format index in the VPS, rather than signalling explicit representation format data in the SPS, from the v2 version of JCTVC-O0096.
- (PS/O0096/direct_dependency_type gating flag) #21 Add a gating flag in VPS extension to condition the presence of direct dependency type, with a default type signalled, from JCTVC-O0096
- (PS/O0109/view_id_len) #22 Modify the VPS extension syntax and semantics to replace view_id_len_minus1 with view_id_len, always signal that syntax element, add a constraint that (1<<view_id_len) >= NumViews, and modify view_id_val semantics to infer value of 0 when not present, from discussion of JCTVC-O0109

- (PS/O0109/profile_ref_minus1 constraint) #23 Modify the semantics of profile_ref_minus1[i] to replace "shall be less than i" with "shall be less than or equal to i", from discussion of JCTVC-O0109
- (PS/O0109/vps_vui_present_flag move) #24 Move the vps_vui_present_flag to precede vps_vui_offset, and make vps_vui_offset conditional on that flag, from JCTVC-O0109
- (Fix misspelled LayerInitialisedFlag)
- (Fix MV-Trac Layers Present renaming) Incomplete renaming of "layers present" SEI.

Ed. Notes (Draft 5)

- --------- Release v5 ----------
- (Revised instructions) related to base spec.
- (Review GT04)
- (Review YK)
- (Removal unused variables)
- (Review GT03)
- (RA LSS CLA/E0306/TSA STSA align) If a higher layer pic is a TSA/STSA, lower layer inter-layer reference layer pictures in the same access unit shall also be TSA/STSA.
- (RA LSS CLA/E0306/picture marking) It was asked whether IDR/BLA in base layer but not in EL, the IDR in the BL causes marking of the EL pics as unused for reference (in other layers)? No, but need to figure out how/whether this is expressed in the text.
- (PS/N0085/Req. vui_timing_info_present_flag) No timing and HRD information in VUI for SPS with nuh_layer_id > 0: Require the flag in the SPS VUI to indicate that this data is not present.
- (Added VUI syntax to Annex F)
- (Comment E0102)
- (Moved F.8.3.4) Moved decoding process for reference picture lists construction to Annex G
- (Review GT02)
- (Review JC01)
- --------- Release v4 ----------
- (Review YK)
- ---------- Release v3 ----------
- (Revision scaling list)
- (Review JO01)
- (Review Editor's comments) Removed resolved and old comments, minor fixes related to scalability ids. constraints.
- (T PP/N0160/ilp_restricted_ref_layers_flag) #19 Move num_ilp_restricted_ref_layers and related offset delay syntax elements from SPS VUI to VPS VUI, and change to a num_ilp_restricted_ref_layers flag per direct dependent layer for each layer.
- (T PP/N0199/N0160/move tile boundaries alignment) #20 Adopt proposal 2 variant 2 (also in JCTVC-N0160) to move tile boundaries alignment flag from the SPS VUI to the VPS VUI, and also signal the flag per direct dependent layer for each layer.
- (PS/N0085/VPS VUI) #18 Add a VPS VUI section and put bit rate and picture rate information in it.
- (PS/N0085/ SPS,PPS IDs) #31 To establish that SPS/PPS IDs with different values of nuh_layer_id share the same "value space" such that different layers may share the same SPS/PPS. It is proposed to let them share the same value space.
- ---------- Release v2 ----------
- (Review CY02)
- (Review GT01) Simplification interlayer L0, L1 split
- (Review JB01)
- (GEN/JCTVC-N0244/POC), #27 Adopt to use a reserved slice header bit for a POC reset flag, plus signal POC LSB in enhancement layer IRAP pictures from JCTVC-N0065, to maintain POC alignment between layers when IRAP pictures are not aligned.[During joint session discussion, decided to align with (JCTVC-N0147/VPS IRAP aligned flag), and only require inclusion of the slice flag when the VPS alignment flag indicates non-aligned IRAPs possible.]
- (Review CY01)
- (RA LSS CLA/JCTVC-N0147/VPS IRAP aligned flag) #25 Add a flag in VPS extension to indicate if all IRAP pictures are aligned in set of dependent layers.
- (SEI/JCTVC-N0383/Add inter-layer constrained tile sets) #24
- (3D/E0038/View_id) #16 Adopt (merge with E0057). Revisions to integration of E0057
- (3D/Res. Constraint) #28 Support different spatial resolutions for different views but disable inter-view prediction in such a case.
- (3D/E0310/Levels) #29 Preliminary level definitions for stereo profile.
- (RA LSS CLA/JCTVC-N0066/layerwise startup) #26 Adopt version 2 layer-wise start up decoding process.

- (3D/E0240/3D reference display information SEI) #22 Persistence scope On 3D reference displays information SEI Decision
- ---------- Release v1 ----------
- (3D/E0057/ViewId) #16 Adopt (similar to E0038)
- (3D/E0104/Swap scalability dimensions) #15 Adopt, only portion that swaps multiview and depth flag in scalability dimension
- (3D/E0101/stereo profile avc_base_layer_flag) #14 Stereo profile definition the avc_base_flag which exists should be disabled.
- (TMVP COL//N0107/Col ind) #13 On collocated picture indication and inter_layer_sample_pred_only_flag) Remove the slice header syntax elements alt_collocated_indication_flag, collocated_ref_layer_idx, and inter_layer_sample_pred_only_flag.
- (RF/N0092/Rep. format information in VPS) #12 Adopt (with the u(4) adjustment)
- (SL ILP/N0120/max_tid_il_ref_pics_plus1_present_flag) #11 BoG Adopt with a minor editorial change to move location of inference.
- (RPLC/N0316/L0 L1 inter-layer rps) #10 BoG Exact decoding process might require slight modification based upon review of contributions related to view_id.
- (IL RPS/N0195/splitting_flag constraint) #9 Add constraint when splitting_flag is used, that the sum of the lengths be less than or equal to 6, from JCTVC-N0195 5th proposal.
- (SEI/N0173/Remove Layer Dependency SEI) #8 Layer dependency change SEI message be removed from specification. If the SEI message does remain, to adopt JCTVC-N0174 (with some editorial improvements).
- (IL RPS/N0195/ilp_slice_signaling_flag) #7 Adopt an Inter Layer Reference Picture (ILRP) presence flag in the VPS, conditioning the presence of ILRP syntax elements in the slice segment header, similar to JCTVC-N0195 proposal 2.
- (IL RPS/N0081,N0195,N0154,N0217/inter_pred_layer_idc) #6 Adopt a condition on signalling inter_layer_pred_layer_idc[i], to avoid sending when NumDirectRefLayers equals NumActiveRefLayerPics, and instead infer values.
- (Incl. PPS RBSP syntax) Included from base spec.
- (EPSPS/N0371/Scaling list prediction) #5 Adopting scaling list prediction in SPS and PPS (harmonization of JCTVC-N0162 and JCTVC-N0200 variant 3)
- (RPLC/N0082/Init RPL) #4 The BoG recommends adopting initialization process of reference picture lists.
- (PS/N0085/Editorial suggestions) #3 Editorial changes – delegated to editors for consideration.
- (PS/N0085/vps nuh_layer_id) #2 Add a restriction "The value of nuh_layer_id of a VPS NAL unit shall be equal to 0." (for bitstreams conforming to specified proposals, and decoder shall ignore VPS NALUs with other values of nuh_layer_id.
- (PS/N0085/vps_extension_offset) #1 Semantics of vps_extension_offset: It is proposed to clearly specify that emulation prevention bytes are counted.

Ed. Notes (JCT3V-E0100)

- (Cleanup GT01) Fixed references and scope of restructered Annexes.
- (Restructured Annexes) Moved clauses from Annex G to Annex F
- (Incorporated General SEI message syntax)
- (Changed semantics order in slice header) to match syntax table.
- (Review GT01) Review, typo corrections, editorial improvement, clean ups.
- (Moved RPS decoding process) Removed RPS decoding process for reference picture set of the same layer and added changes to base spec.

Ed. Notes (Draft 4)

- ---------- Release v4 ----------
- Accepted all change marks.
- ---------- Release v3 (d2) ----------
- (Version numbering) Changed document numbering from zero-based to one-based. (_d2 becomes -v3)
- (Review GT08) Review, typo corrections, editorial improvement, clean ups.
- (Review GT07) Review, typo corrections, editorial improvement, clean ups.
- (Update note 3D Display SEI) Updated note in 3D reference display SEI based on new text provided of the proponent.
- (Review GT06) Review, typo corrections, editorial improvement, clean ups.
- (M0457): Bug fix to use the information indicated through the inter-layer reference picture set in alt_collocated syntax elements rather than the VPS information directly. Previously, the semantics of inter_layer_pred_enabled, num_inter_layer_ref_pics_minus1 and inter_layer_pred_layer[i] concerned all types of inter-layer prediction but actually only affected sample prediction and it was possible to use motion prediction from a reference layer not listed in inter_layer_pred_layer_idc[i]. Now the inter-layer motion prediction is also constrained to take place among layers indicated by inter_layer_pred_layer_idc[i].

- (Review MH02): Review, clean ups, editor's notes.
- (Review JB02) Review, clean ups, add editors notes, definitions, and missing contstraint
- (Joint/M0264 and M0208) AU definition and other editorial improvements
- (Review GT05) Review, typo corrections, editorial improvement, clean ups.
- (SHVC, Reserved) Changed SHVC syntax and semantics to reserved values (To be discussed).
- (SF/M0040/single_layer_for_non_irap_flag) Adaptive resolution change and efficient trick
- (PP/M0463/Parallel processing delay indication) Incorporated improved version provided by the editors.
- (3D/D0220/ViewId) Adopt view id aspect.
- ---------- Release d1 ----------
- (PP/M0464/Tile alignment flag) Adopt first aspect (tile boundary alignment flag). Editorial improvement needed.
- (Copied text from HEVC version 1) VUI related. .
- (Removed AltCollocatedIndicationFlag)
- (SF/M0309/Extended spatial scalability) Signalling of extended spatial scalability.
- (Review JB01) Move direct_dependency_flag semantics to correct location, improvements to M0458.
- (PS/M0268/Output Layer Sets, Profile Tier) #7 Section 3 of the v2 document; An alternative method for signalling of profile, tier, and level information and output layer sets
- (Added stereo main profile scalable restriction) as suggested by Miska for consideration.
- (Added inference SPS syntax elements) for sps_max_sub_layers_minus1 sps_temporal_id_nesting_flag.
- (Copied text from HEVC version 1) sps_max_sub_layers_minus1 sps_temporal_id_nesting_flag.
- (Fix bit length for num_inter_layer_ref_pics_minus1)
- (Move if-statement in 8.1.1) after "When the current picture is an IRAP picture, the following applies:" to 8.1.
- (Renamed max_sublayer_for_ilp_plus1) to max_tid_il_ref_pics_plus1.
- (Renamed LayerIdInVps) to LayerIdxInVps.
- (Removal InterLayerMfmEnableFlag) and related notes. Should be incorporated in SHVC draft.
- (Review GT04) Review, typo corrections, editorial improvement, clean ups.
- ---------- Release d0 ----------
- (Removed old marking) Removed old spec text of Marking process for sub-layer non-reference pictures not needed for inter-layer prediction.
- (Removed LayerSetPresentFlag) Removed LayerSetPresent as discussed.
- (Review GT03) Review, typo corrections, editorial improvement, clean ups.
- (Review MH01) Review, typo corrections, editorial improvement, clean ups.
- (Review JB + YW) Review, typo corrections, editorial improvement, clean ups.
- (Review GT02) Review, typo corrections, editorial improvement, clean ups.
- (RPSM/M0458/Active inter-layer ref pics in slice header) #18 1.) max_one_active_ref_layer_flag in VPS, 2.) slice segment header indicates inter-layer ref. pics, 3.) Change IL-RPS and ref pic list construction. Have a semantic constraint that inter_layer_idc[i] shall be increasing. Editorial notes that further improvements related to aspect 3 are encouraged. Also agreed to let the editors to combine text of JCTVC-M0457 and JCTVC-M0458. Includes resolution of editorial issue identified under SILP/M0209/IL RPS decoding.
- (SILP/M0457/Dependency type, Alt coll. ref. idx., TMVP change) #16 Signalling of inter layer prediction type (motion/sample), alternative collocated picture, flags for kind of enabled inter-layer prediction per slice, modified TMVP)
- (PS/D0311/Dim. ID not when SplittingFlag) #9 Replaces a semantic constraint on dimension_id with an inference when splitting flag is equal to 1. Ed. improvement needed to handle setting default values for scalability type dimensions that are not present.
- (SEI/D0218/3DRefDispSEI) #23 3D reference displays information SEI message.
- (SEI/M0043/Layers present SEI message) #22 Agreed with the following change: the persistence scope of the SEI message should be further restricted to be within a CVS.
- (SILP/M0162/discardable_flag dependent marking) #15 A picture that has nuh_layer_id greater than 0 and discardable_flag equal to 1 is marked as "unused for reference" after its decoding.
- (SILP/M0152/discardable_flag) #14 One reserved flag in the slice header, when equal to 1, indicates that the picture is not used for inter-layer prediction and not used for inter prediction.
- (Ed. Add slice segment header) Added slice segment header syntax table from HEVC 1.
- (SILP/M0209/IL RPS decoding) #13 Decoding of inter-layer reference picture set and reference picture list construction based on TemporalId. An editorial improvement is needed regarding the deviation of a variable NumInterLayerRpsPics that is currently in the decoding process.
- (SILP/M0209/marking non ref temp sub layer) #12 Marking of certain pictures as "unused for reference" base on max_sublayer_for_ilp_plus1.
- (SILP/M0203/max_sublayer_for_ilp_plus1) #11 Signalling of maximum TemporalId used in inter-layer prediction.. Agreed with a change "<=" to "<" in the loop of the added syntax.
- (PS/M0163/No sig.last dimension_id_len_minus1) #10 No signalling of the last dimension_id_len_minus1[i], when splitting_flag is equal to 1.

- (PS/M0268/SPS Flag signalling) #8 Don't signal sps_max_sub_layers_minus1 and sps_temporal_id_nesting_flag when nuh_layer_id_> 0.
- (PS/M0268/output_layer_set_idx) #6 Change the syntax element output_layer_set_idx[i] to output_layer_set_idx_minus1[i].
- (PS/M0268/PositionDirectDependencyFlags) #5 Move the direct dependency flag syntax section to directly follow the dimension_id syntax (ahead of profile/tier/level) signalling.
- (Joint/M0208/NumPocTotalCurr) Clarify that the value of NumPocTotalCurr shall be equal to 0 for a BLA or CRA picture if nuh_layer_id is equal to 0.
- (Joint/M0045/Stereo Main/no mixed scal.) The principle not to support mixed scalability types for now. Concrete language to be worked.
- (Joint/M0168/AUD Layer Id) #1 The allowed layer ID value for the AUD should correspond to the lowest VCL NAL unit layer ID in the AU.
- (Joint/M0168/SPS activation) An IRAP NAL unit of each layer with NoRaslOutputFlag equal to 1 may activate a new SPS for the corresponding layer
- (Review GT01) Review, typo corrections, editorial improvement, clean ups.

Ed. Notes (Draft 3) (changes to JCT3V-B1004)

- ---------- Release d2 ----------
- (Review GT3) Editorial clean-ups.
- (Update 2 to latest HEVC spec) Update to JCTVC-L1003_v33.doc.
- (Fix SPS profile_tier_level) Fixed signalling of profile_tier_level syntax structure in SPS.
- (SPS to Annex F) Moved SPS syntax and semantics from Annex G to Annex F.
- (Ed. note on pic size) Added editor's note on picture size restriction.
- (Fix bit masking for splitting) Corrected of erroneous bit shift.
- ---------- Release d1 ----------
- (Review GT2)
- (Review MH2)
- (JCT3V-C0238 Marking Process) Replace targetDecLayerIdList by TargetDecLayerIdList in F.8.1.2.1.
- (Ed. Notes 01) Incorporated and removed editor's notes as discussed.
- (JCT3V-0059) Update to new terminology and simplification of text.
- (Fix References) Fix of references and numbering.
- (JCTVC-L0363) Fixed byte alignment corrupted when re-introduction of profilePresentFlag in profile_tier_level for JCTVC-L0180.
- (JCTVC-L0180) Updated of semantics and modified profile_tier_level syntax structure.
- (Review GT01)
- (JCT3V-C0078) Incorporated disparity vector constraints.
- (Update to latest HEVC spec), Updated to JCTVC-L1003_v19.doc.
- (Review Miska01)
- (MVC-CY01) Review, typo corrections, editorial improvement and alignment with B1004.
- (JCT3V-C0085) Integration of JCT3V-C0085: slice type constraint.
- ---------- Release d0 ----------
- (JCT3V-C0238) Incorporated common specification text for scalable multi-view extensions.

Ed. Notes (WD2) (based on JCT3V-A1004)

- ---------- Release d0 ----------
- (MVC-MH) Review, typo corrections, editorial improvement, and editor's notes
- (MVE-06) Incorporated introductory paragraph for view dependency change SEI message.
- (MVE-05) Incorporated invocation of sub-bitstream extraction process in general decoding process
- (MVE-04) Fixed construction of layerId list in general decoding process
- (MVC-KW) Review, typo corrections, editorial improvement.
- (MVE-03) Replacement of changes marks related to base spec by highlighting
- (MVE-01/JCT3V-B00046) Incorporated editorial note
- (MVC-GT) Review, typo corrections, editorial improvement.
- (MVC-CY) Review, typo corrections, editorial improvement.
- (MVE-02) Incorporated initial version of HRD text.
- (MVN-01/JCT3V-B0063) Incorporated view dependency change SEI.

Ed. Notes (WD1) (based on : JCT3V-A0012)

- ---------- Release d0 ----------
- (Rev3, KW) Review and small corrections

- (Rev2, GT) Review and text improvement
- Missing part in general decoding process
- (Replacement view_id by layer_id)
- Font issue fix.
- (Fix: picture marking)
- (Rev1, CY), Review and small corrections
- (MV07) Fix references
- (MV06) Improvement and update of interview prediction text.
- (MV02,MV03) Update of high level syntax and definitions
- (MV09) general HEVC decoding process
- (MV08) Additional sections/placeholders
- (MV04, MV05) Removal of low-level and depth tools
- (MV01) Removed HEVC spec
- Update of low level specification to match HEVC text specification 8(d7)

Remarks:

- Modifications in long sections copied from the HEVC spec are highlighted in turquoise. Open issues and editor's notes are highlighted in yellow.

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Replace the definition of access unit in clause 3 with the following:

3.X **access unit:** A set of *NAL units* that are associated with each other according to a specified classification rule, are consecutive in *decoding order*, and contain the *VCL NAL units* of all *coded pictures* associated with the same output time and their *associated non-VCL NAL units*.

NOTE X – Pictures in the same access unit are associated with the same picture order count.

Add the following definitions to clause 3:

3.X **base bitstream partition**: A *bitstream partition* that is also a conforming *bitstream* itself.

3.X **bitstream partition**: A sequence of bits, in the form of a *NAL unit stream* or a *byte stream*, that is a subset of a *bitstream* according to a *partitioning*.

3.X **output layer**: A *layer* of an *output layer set* that is output when TargetOlsIdx is equal to the index of the *output layer set*.

3.X **output layer set (OLS)**: A set of *layers* consisting of the *layers* of one of the specified *layer sets*, where one or more *layers* in the set of layers are indicated to be output layers.

3.X **output operation point**: A bitstream that is created from another *bitstream* by operation of the *sub-bitstream extraction process* with the another *bitstream*, a target highest TemporalId, and a target *layer identifier list* as inputs, and that is associated with a set of *output layers*.

3.X **picture unit:** A set of *NAL units* that are associated with each other according to a specified classification rule, are consecutive in *decoding order*, and contain the *VCL NAL units* of a *coded picture* and their *associated non-VCL NAL units*.

3.X **target output layer set**: The *output layer set* for which the index is equal to TargetOlsIdx.

Add the following abbreviations to clause 4:

OLS Output Layer Set

Add the definition of the following mathematical function to subclause 5.8:

$$\text{GetCurrMsb(cl, pl, pm, ml)} = \begin{cases} pm + ml & ; \quad pl - cl >= ml/2 \\ pm - ml & ; \quad cl - pl > ml/2 \\ pm & ; \quad otherwise \end{cases}$$

Replace subclauses 7.4.2.4.2 with the following (with differences indicated in turquois):

7.4.2.4.2 Order of VPS, SPS and PPS RBSPs and their activation

This subclause specifies the activation process of VPSs, SPSs, and PPSs.

NOTE 1 – The VPS, SPS, and PPS mechanism decouples the transmission of infrequently changing information from the transmission of coded block data. VPSs, SPSs, and PPSs may, in some applications, be conveyed "out-of-band".

A PPS RBSP includes parameters that can be referred to by the coded slice segment NAL units of one or more coded pictures. Each PPS RBSP is initially considered not active for any layer at the start of the operation of the decoding process. At most one PPS RBSP is considered active for each layer at any given moment during the operation of the decoding process, and the activation of any particular PPS RBSP for a particular layer results in the deactivation of the previously-active PPS RBSP for the particular layer (if any).

One PPS RBSP may be the active PPS RBSP for more than one layer. When not explicitly specified, the layer a PPS RBSP is active for is inferred to be the current layer in the context where the active PPS RBSP is referred to.

When a PPS RBSP (with a particular value of pps_pic_parameter_set_id) is not active for a particular layer and it is referred to by a coded slice segment NAL unit (using a value of slice_pic_parameter_set_id equal to the pps_pic_parameter_set_id value) of the particular layer, it is activated for the particular layer. This PPS RBSP is called the active PPS RBSP for the particular layer until it is deactivated by the activation of another PPS RBSP for the particular layer. A PPS RBSP, with that particular value of pps_pic_parameter_set_id, shall be available to the decoding

process prior to its activation, included in at least one access unit with TemporalId less than or equal to the TemporalId of the PPS NAL unit or provided through external means.

Any PPS NAL unit containing the value of pps_pic_parameter_set_id for the active PPS RBSP for a coded picture (and consequently for the layer containing the coded picture) shall have the same content as that of the active PPS RBSP for the coded picture, unless it follows the last VCL NAL unit of the coded picture and precedes the first VCL NAL unit of another coded picture.

NOTE 2 – All PPSs, regardless of their values of nuh_layer_id or TemporalId, share the same value space for pps_pic_parameter_set_id. In other words, a PPS with nuh_layer_id equal to X, TemporalId equal to Y, and pps_pic_parameter_set_id equal to A would update the previously received PPS with nuh_layer_id not equal to X, and/or TemporalId not equal to Y, and pps_pic_parameter_set_id equal to A.

An SPS RBSP includes parameters that can be referred to by one or more PPS RBSPs or one or more SEI NAL units containing an active parameter sets SEI message. Each SPS RBSP is initially considered not active for any layer at the start of the operation of the decoding process. At most one SPS RBSP is considered active for each layer at any given moment during the operation of the decoding process, and the activation of any particular SPS RBSP for a particular layer results in the deactivation of the previously-active SPS RBSP for the particular layer value of nuh_layer_id (if any).

One SPS RBSP may be the active SPS RBSP for more than one layer. When not explicitly specified, the layer an SPS RBSP is active for is inferred to be the current layer in the context where the active PPS RBSP is referred to.

When an SPS RBSP (with a particular value of sps_seq_parameter_set_id) is not already active for a particular layer and it is referred to by activation of a PPS RBSP (in which pps_seq_parameter_set_id is equal to the sps_seq_parameter_set_id value) referred to by the particular layer or is referred to by an SEI NAL unit containing an active parameter sets SEI message (in which one of the active_seq_parameter_set_id[i] values is equal to the sps_seq_parameter_set_id value), it is activated for the particular layer. This SPS RBSP is called the active SPS RBSP for the particular layer until it is deactivated by the activation of another SPS RBSP for the particular layer. An SPS RBSP, with that particular value of sps_seq_parameter_set_id, shall be available to the decoding process prior to its activation, included in at least one access unit with TemporalId equal to 0 or provided through external means. An activated SPS RBSP for the base layer shall remain active for the entire CVS.

NOTE 3 – Because an IRAP access unit with NoRaslOutputFlag equal to 1 begins a new CVS and an activated SPS RBSP must remain active for the entire CVS, an SPS RBSP can only be activated by an active parameter sets SEI message when the active parameter sets SEI message is part of an IRAP access unit with NoRaslOutputFlag equal to 1.

Any SPS NAL unit containing the value of sps_seq_parameter_set_id for the active SPS RBSP for the base layer for a CVS shall have the same content as that of the active SPS RBSP for the base layer for the CVS, unless it follows the last access unit of the CVS and precedes the first VCL NAL unit and the first SEI NAL unit containing an active parameter sets SEI message (when present) of another CVS.

NOTE 4 – All SPSs, regardless of their values of nuh_layer_id, share the same value space for sps_seq_parameter_set_id. In other words, an SPS with nuh_layer_id equal to X and sps_seq_parameter_set_id equal to A would update the previously received SPS with nuh_layer_id not equal to X and sps_seq_parameter_set_id equal to A.

A VPS RBSP includes parameters that can be referred to by one or more SPS RBSPs or one or more SEI NAL units containing an active parameter sets SEI message. Each VPS RBSP is initially considered not active at the start of the operation of the decoding process. At most one VPS RBSP is considered active at any given moment during the operation of the decoding process, and the activation of any particular VPS RBSP results in the deactivation of the previously-active VPS RBSP (if any).

When a VPS RBSP (with a particular value of vps_video_parameter_set_id) is not already active and it is referred to by activation of an SPS RBSP (in which sps_video_parameter_set_id is equal to the vps_video_parameter_set_id value), or is referred to by an SEI NAL unit containing an active parameter sets SEI message (in which active_video_parameter_set_id is equal to the vps_video_parameter_set_id value), it is activated. This VPS RBSP is called the active VPS RBSP until it is deactivated by the activation of another VPS RBSP. A VPS RBSP, with that particular value of vps_video_parameter_set_id, shall be available to the decoding process prior to its activation, included in at least one access unit with TemporalId equal to 0 or provided through external means. An activated VPS RBSP shall remain active for the entire CVS.

NOTE 5 – Because an IRAP access unit with NoRaslOutputFlag equal to 1 begins a new CVS and an activated VPS RBSP must remain active for the entire CVS, a VPS RBSP can only be activated by an active parameter sets SEI message when the active parameter sets SEI message is part of an IRAP access unit with NoRaslOutputFlag equal to 1.

Any VPS NAL unit containing the value of vps_video_parameter_set_id for the active VPS RBSP for a CVS shall have the same content as that of the active VPS RBSP for the CVS, unless it follows the last access unit of the CVS and precedes the first VCL NAL unit, the first SPS NAL unit, and the first SEI NAL unit containing an active parameter sets SEI message (when present) of another CVS.

NOTE 6 – If VPS RBSP, SPS RBSP, or PPS RBSP are conveyed within the bitstream, these constraints impose an order constraint on the NAL units that contain the VPS RBSP, SPS RBSP, or PPS RBSP, respectively. Otherwise (VPS RBSP, SPS

RBSP, or PPS RBSP are conveyed by other means not specified in this Specification), they must be available to the decoding process in a timely fashion such that these constraints are obeyed.

All constraints that are expressed on the relationship between the values of the syntax elements and the values of variables derived from those syntax elements in VPSs, SPSs, and PPSs and other syntax elements are expressions of constraints that apply only to the active VPS RBSP, the active SPS RBSP for the base layer, and the active PPS RBSP for the base layer. If any VPS RBSP, SPS RBSP, and PPS RBSP is present that is never activated in the bitstream, its syntax elements shall have values that would conform to the specified constraints if it was activated by reference in an otherwise conforming bitstream.

During operation of the decoding process (see clause 8), the values of parameters of the active VPS, the active SPS for the base layer, and the active PPS RBSP for the base layer are considered in effect. For interpretation of SEI messages, the values of the active VPS RBSP, the active SPS RBSP for the base layer, and the active PPS RBSP for the base layer for the operation of the decoding process for the VCL NAL units of the coded picture in the same access unit are considered in effect unless otherwise specified in the SEI message semantics.

Replace subclauses 7.4.2.4.4 with the following (with differences indicated in turquois):

7.4.2.4.4 Order of NAL units and coded pictures and their association to access units

This subclause specifies the order of NAL units and coded pictures and their association to access units for CVSs that conform to one or more of the profiles specified in Annex A and that are decoded using the decoding process specified in clauses 2 through 10.

NOTE 1 – The association of NAL units to access units may differ depending on which profiles the CVSs conform to or which decoding process is used for decoding the bitstream.

An access unit consists of one coded picture with nuh_layer_id equal to 0, zero or more VCL NAL units with nuh_layer_id greater than 0, and zero or more non-VCL NAL units. The association of VCL NAL units to coded pictures is described in subclause 7.4.2.4.5.

The first access unit in the bitstream starts with the first NAL unit of the bitstream.

The first of any of the following NAL units after the last VCL NAL unit of a coded picture with nuh_layer_id equal to 0 specifies the start of a new access unit: [Ed. (YK): Within an access unit at least an SPS, PPS, or prefix SEI NAL unit may be present after the last VCL NAL unit of the picture with nuh_layer_id equal to 0. Maybe other NAL units as well. Check the need of more changes.]

– access unit delimiter NAL unit (when present),

– VPS NAL unit (when present),

– SPS NAL unit (when present),

– PPS NAL unit (when present),

– Prefix SEI NAL unit (when present),

– NAL units with nal_unit_type in the range of RSV_NVCL41..RSV_NVCL44 (when present), [Ed. (MH): It should be clarified if only the NAL units with nuh_layer_id equal to 0 are considered here or if nuh_layer_id can have any value in this condition. (YK): Also for other NAL units that may have nuh_layer_id greater than 0.]

– NAL units with nal_unit_type in the range of UNSPEC48..UNSPEC55 (when present),

– first VCL NAL unit of a coded picture with nuh_layer_id equal to 0 (always present).

The order of the coded pictures and non-VCL NAL units within an access unit shall obey the following constraints:

– When an access unit delimiter NAL unit is present, it shall be the first NAL unit. There shall be at most one access unit delimiter NAL unit in any access unit.

– When any prefix SEI NAL units are present, they shall not follow the last VCL NAL unit of the access unit.

– NAL units having nal_unit_type equal to FD_NUT or SUFFIX_SEI_NUT, or in the range of RSV_NVCL45..RSV_NVCL47 or UNSPEC56..UNSPEC63 shall not precede the first VCL NAL unit of the coded picture with nuh_layer_id equal to 0.

– When an end of sequence NAL unit is present, it shall be the last NAL unit in the access unit other than an end of bitstream NAL unit (when present).

– When an end of bitstream NAL unit is present, it shall be the last NAL unit in the access unit.

NOTE 2 – VPS NAL units, SPS NAL units, PPS NAL units, prefix SEI NAL units, or NAL units with nal_unit_type in the range of RSV_NVCL41..RSV_NVCL44 or UNSPEC48..UNSPEC55, may be present in an access unit, but cannot follow the last VCL NAL unit of the coded picture within the access unit, as this condition would specify the start of a new access unit.

The structure of access units not containing any NAL units with nal_unit_type equal to FD_NUT, VPS_NUT, SPS_NUT, PPS_NUT, RSV_VCL_N10, RSV_VCL_R11, RSV_VCL_N12, RSV_VCL_R13, RSV_VCL_N14, or RSV_VCL_R15, RSV_IRAP_VCL22, or RSV_IRAP_VCL23, or in the range of RSV_VCL24..RSV_VCL31, RSV_NVCL41..RSV_NVCL47, or UNSPEC48..UNSPEC63 is shown in Figure 8-1.

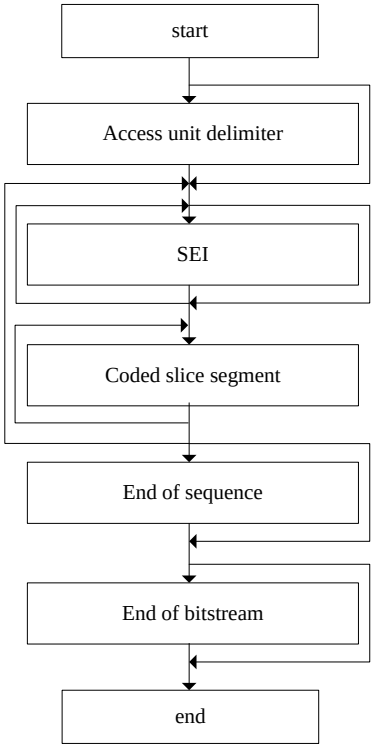

Figure 8-1 – Structure of an access unit not containing any NAL units with nal_unit_type equal to FD_NUT, SUFFIX_SEI_NUT, VPS_NUT, SPS_NUT, PPS_NUT, RSV_VCL_N10, RSV_VCL_R11, RSV_VCL_N12, RSV_VCL_R13, RSV_VCL_N14, RSV_VCL_R15, RSV_IRAP_VCL22, or RSV_IRAP_VCL23, or in the range of RSV_VCL24..RSV_VCL31, RSV_NVCL41..RSV_NVCL47, or UNSPEC48..UNSPEC63

Replace clause 8, subclauses 8.1, 8.2, 8.3, 8.3.1, 8.3.2, 8.3.3, and 8.3.3.1 with the following and add subclause 8.1.1 (with differences indicated in turquois):

8 Decoding process

8.1 General decoding process

Input to this process is a bitstream. Output of this process is a list of decoded pictures.

The variable TargetOlsIdx, which specifies the index to the list of the OLSs specified by the VPS, of the target OLS, is specified as follows:

– If some external means, not specified in this Specification, is available to set TargetOlsIdx, TargetOlsIdx is set by the external means.

– Otherwise, if the decoding process is invoked in a bitstream conformance test as specified in subclause C.1, TargetOlsIdx is set as specified in subclause C.1.

– Otherwise, TargetOlsIdx is set equal to 0.

The variable TargetDecLayerSetIdx, the layer identifier list TargetOptLayerIdList, which specifies the list of nuh_layer_id values, in increasing order of nuh_layer_id values, of the pictures to be output, and the layer identifier list TargetDecLayerIdList, which specifies the list of nuh_layer_id values, in increasing order of nuh_layer_id values, of the NAL units to be decoded, are specified as follows:

```
TargetDecLayerSetIdx = OlsIdxToLsIdx[ TargetOlsIdx ]
lsIdx = TargetDecLayerSetIdx
for( k = 0, j = 0; j < NumLayersInIdList[ lsIdx ]; j++ ) {
    TargetDecLayerIdList[ j ] = LayerSetLayerIdList[ lsIdx ][ j ]                    (8-1)
    if( OutputLayerFlag[ TargetOlsIdx ][ j ] )
        TargetOptLayerIdList[ k++ ] = LayerSetLayerIdList[ lsIdx ][ j ]
}
```

The variable HighestTid, which identifies the highest temporal sub-layer to be decoded, is specified as follows:

– If some external means, not specified in this Specification, is available to set HighestTid, HighestTid is set by the external means.

– Otherwise, if the decoding process is invoked in a bitstream conformance test as specified in subclause C.1, HighestTid is set as specified in subclause C.1.

– Otherwise, HighestTid is set equal to sps_max_sub_layers_minus1.

The sub-bitstream extraction process as specified in clause 10 is applied with the bitstream, HighestTid, and TargetDecLayerIdList as inputs, and the output is assigned to a bitstream referred to as BitstreamToDecode.

The decoding processes specified in the remainder of this subclause apply to each coded picture, referred to as the current picture and denoted by the variable CurrPic, in BitstreamToDecode.

Depending on the value of chroma_format_idc, the number of sample arrays of the current picture is as follows:

– If chroma_format_idc is equal to 0, the current picture consists of 1 sample array S_L.

– Otherwise (chroma_format_idc is not equal to 0), the current picture consists of 3 sample arrays S_L, S_{Cb}, S_{Cr}.

The decoding process for the current picture takes as inputs the syntax elements and upper-case variables from clause 7. When interpreting the semantics of each syntax element in each NAL unit, the term "the bitstream" (or part thereof, e.g. a CVS of the bitstream) refers to BitstreamToDecode (or part thereof).

When the current picture is an IRAP picture, the variable HandleCraAsBlaFlag is derived as specified in the following:

– If some external means not specified in this Specification is available to set the variable HandleCraAsBlaFlag to a value for the current picture, the variable HandleCraAsBlaFlag is set equal to the value provided by the external means.

– Otherwise, the variable HandleCraAsBlaFlag is set equal to 0.

When the current picture is an IRAP picture and has nuh_layer_id equal to 0, the following applies:

– The variable NoClrasOutputFlag is specified as follows:

  – If the current picture is the first picture in the bitstream, NoClrasOutputFlag is set equal to 1.

  – Otherwise, if the current picture is a BLA picture or a CRA picture with HandleCraAsBlaFlag equal to 1, NoClrasOutputFlag is set equal to 1.

  – Otherwise, if the current picture is an IDR picture with cross_layer_bla_flag is equal to1, NoClrasOutputFlag is set equal to 1.

  – Otherwise, if some external means, not specified in this Specification, is available to set NoClrasOutputFlag, NoClrasOutputFlag is set by the external means.

  – Otherwise, NoClrasOutputFlag is set equal to 0.

– When NoClrasOutputFlag is equal to 1, the variable LayerInitializedFlag[i] is set equal to 0 for all values of i from 0 to vps_max_layer_id, inclusive, and the variable FirstPicInLayerDecodedFlag[i] is set equal to 0 for all values of i from 0 to vps_max_layer_id, inclusive.

The decoding process is specified such that all decoders will produce numerically identical cropped decoded pictures. Any decoding process that produces identical cropped decoded pictures to those produced by the process described herein (with the correct output order or output timing, as specified) conforms to the decoding process requirements of this Specification.

When the current picture is an IRAP picture, the following applies:

– If the current picture with a particular value of nuh_layer_id is an IDR picture, a BLA picture, the first picture with that particular value of nuh_layer_id in the bitstream in decoding order, or the first picture with that particular value

of nuh_layer_id that follows an end of sequence NAL unit in decoding order, the variable NoRaslOutputFlag is set equal to 1.

– Otherwise, if LayerInitializedFlag[nuh_layer_id] is equal to 0 and LayerInitializedFlag[refLayerId] is equal to 1 for all values of refLayerId equal to RefLayerId[nuh_layer_id][j], where j is in the range of 0 to NumDirectRefLayers[nuh_layer_id] − 1, inclusive, the variable NoRaslOutputFlag is set equal to 1.

– Otherwise, the variable NoRaslOutputFlag is set equal to HandleCraAsBlaFlag.

When the current picture is an IRAP picture with NoRaslOutputFlag equal to 1 and one of the following conditions is true, LayerInitializedFlag[nuh_layer_id] is set equal to 1:

– nuh_layer_id is equal to 0.

– LayerInitializedFlag[nuh_layer_id] is equal to 0 and LayerInitializedFlag[refLayerId] is equal to 1 for all values of refLayerId equal to RefLayerId[nuh_layer_id][j], where j is in the range of 0 to NumDirectRefLayers[nuh_layer_id] − 1, inclusive.

Depending on the value of separate_colour_plane_flag, the decoding process is structured as follows:

– If separate_colour_plane_flag is equal to 0, the following decoding process is invoked a single time with the current picture being the output.

– Otherwise (separate_colour_plane_flag is equal to 1), the following decoding process is invoked three times. Inputs to the decoding process are all NAL units of the coded picture with identical value of colour_plane_id. The decoding process of NAL units with a particular value of colour_plane_id is specified as if only a CVS with monochrome colour format with that particular value of colour_plane_id would be present in the bitstream. The output of each of the three decoding processes is assigned to one of the 3 sample arrays of the current picture, with the NAL units with colour_plane_id equal to 0, 1, and 2 being assigned to S_L, S_{Cb}, and S_{Cr}, respectively.

NOTE – The variable ChromaArrayType is derived as equal to 0 when separate_colour_plane_flag is equal to 1 and chroma_format_idc is equal to 3. In the decoding process, the value of this variable is evaluated resulting in operations identical to that of monochrome pictures (when chroma_format_idc is equal to 0).

When the current picture has nuh_layer_id equal to 0, the decoding process for a coded picture with nuh_layer_id equal to 0 as specified in subclause 8.1.1 is invoked.

8.1.1 Decoding process for a coded picture with nuh_layer_id equal to 0

The decoding process operates as follows for the current picture CurrPic:

1. The decoding of NAL units is specified in subclause 8.2.
2. The processes in subclause 8.3 specify the following decoding processes using syntax elements in the slice segment layer and above:
   - Variables and functions relating to picture order count are derived as specified in subclause 8.3.1. This needs to be invoked only for the first slice segment of a picture.
   - The decoding process for RPS in subclause 8.3.2 is invoked, wherein reference pictures may be marked as "unused for reference" or "used for long-term reference". This needs to be invoked only for the first slice segment of a picture.
   - When the current picture is a BLA picture or is a CRA picture with NoRaslOutputFlag equal to 1, the decoding process for generating unavailable reference pictures specified in subclause 8.3.3 is invoked, which needs to be invoked only for the first slice segment of a picture.
   - PicOutputFlag is set as follows:
     - If the current picture is a RASL picture and NoRaslOutputFlag of the associated IRAP picture is equal to 1, PicOutputFlag is set equal to 0.
     - Otherwise, PicOutputFlag is set equal to pic_output_flag.
   - At the beginning of the decoding process for each P or B slice, the decoding process for reference picture lists construction specified in subclause 8.3.4 is invoked for derivation of reference picture list 0 (RefPicList0) and, when decoding a B slice, reference picture list 1 (RefPicList1).
3. The processes in subclauses 8.4, 8.5, 8.6, and 8.7 specify decoding processes using syntax elements in all syntax structure layers. It is a requirement of bitstream conformance that the coded slices of the picture shall contain slice segment data for every coding tree unit of the picture, such that the division of the picture into slices, the division of the slices into slice segments, and the division of the slice segments into coding tree units each form a partitioning of the picture.

4. After all slices of the current picture have been decoded, the decoded picture is marked as "used for short-term reference".

8.2 NAL unit decoding process

Inputs to this process are VCL NAL units of the current picture and their associated non-VCL NAL units.

Outputs of this process are the parsed RBSP syntax structures encapsulated within the NAL units of the access unit containing the current picture.

The decoding process for each NAL unit extracts the RBSP syntax structure from the NAL unit and then parses the RBSP syntax structure.

8.3 Slice decoding process

[Ed. (CY): consider moving the remaining part of 8.3, the entire 8.1 and entire 8.2 to Annex F. To be confirmed before the action is taken.]

8.3.1 Decoding process for picture order count

Output of this process is PicOrderCntVal, the picture order count of the current picture.

Picture order counts are used to identify pictures, for deriving motion parameters in merge mode and motion vector prediction, and for decoder conformance checking (see subclause 12).

Each coded picture is associated with a picture order count variable, denoted as PicOrderCntVal.

When the current picture is not an IRAP picture with NoRaslOutputFlag equal to 1, the variables prevPicOrderCntLsb and prevPicOrderCntMsb are derived as follows:

– Let prevTid0Pic be the previous picture in decoding order that has TemporalId equal to 0 and that is not a RASL picture, a RADL picture, or a sub-layer non-reference picture, and let PrevPicOrderCnt[nuh_layer_id] be the PicOrderCntVal of prevTid0Pic.

– The variable prevPicOrderCntLsb is set equal to PrevPicOrderCnt[nuh_layer_id] & (MaxPicOrderCntLsb − 1).

– The variable prevPicOrderCntMsb is set equal to PrevPicOrderCnt[nuh_layer_id] − prevPicOrderCntLsb.

The variable PicOrderCntMsb of the current picture is derived as follows:

– If the current picture is an IRAP picture with NoRaslOutputFlag equal to 1, PicOrderCntMsb is set equal to 0.

– Otherwise, PicOrderCntMsb is derived as follows:

```
if( ( slice_pic_order_cnt_lsb < prevPicOrderCntLsb )  &&
        ( ( prevPicOrderCntLsb − slice_pic_order_cnt_lsb )  >=  ( MaxPicOrderCntLsb / 2 ) ) )
    PicOrderCntMsb = prevPicOrderCntMsb + MaxPicOrderCntLsb                    (8-2)
else if( (slice_pic_order_cnt_lsb > prevPicOrderCntLsb )  &&
        ( ( slice_pic_order_cnt_lsb − prevPicOrderCntLsb ) > ( MaxPicOrderCntLsb / 2 ) ) )
    PicOrderCntMsb = prevPicOrderCntMsb − MaxPicOrderCntLsb
else
    PicOrderCntMsb = prevPicOrderCntMsb
```

PicOrderCntVal is derived as follows:

$$PicOrderCntVal = PicOrderCntMsb + slice\_pic\_order\_cnt\_lsb \quad (8\text{-}3)$$

NOTE 1 – All IDR pictures will have PicOrderCntVal equal to 0 since slice_pic_order_cnt_lsb is inferred to be 0 for IDR pictures and prevPicOrderCntLsb and prevPicOrderCntMsb are both set equal to 0.

The value of PicOrderCntVal shall be in the range of -2^{31} to $2^{31} - 1$, inclusive. In one CVS, the PicOrderCntVal values for any two coded pictures shall not be the same.

The function PicOrderCnt(picX) is specified as follows:

PicOrderCnt(picX) = PicOrderCntVal of the picture picX (8-4)

The function DiffPicOrderCnt(picA, picB) is specified as follows:

DiffPicOrderCnt(picA, picB) = PicOrderCnt(picA) − PicOrderCnt(picB) (8-5)

The bitstream shall not contain data that result in values of DiffPicOrderCnt(picA, picB) used in the decoding process that are not in the range of -2^{15} to $2^{15} - 1$, inclusive.

NOTE 2 – Let X be the current picture and Y and Z be two other pictures in the same CVS, Y and Z are considered to be in the same output order direction from X when both DiffPicOrderCnt(X, Y) and DiffPicOrderCnt(X, Z) are positive or both are negative.

8.3.2 Decoding process for reference picture set

This process is invoked once per picture, after decoding of a slice header but prior to the decoding of any coding unit and prior to the decoding process for reference picture list construction for the slice as specified in subclause 8.3.4. This process may result in one or more reference pictures in the DPB being marked as "unused for reference" or "used for long-term reference".

NOTE 1 – The RPS is an absolute description of the reference pictures used in the decoding process of the current and future coded pictures. The RPS signalling is explicit in the sense that all reference pictures included in the RPS are listed explicitly.

A decoded picture in the DPB can be marked as "unused for reference", "used for short-term reference", or "used for long-term reference", but only one among these three at any given moment during the operation of the decoding process. Assigning one of these markings to a picture implicitly removes another of these markings when applicable. When a picture is referred to as being marked as "used for reference", this collectively refers to the picture being marked as "used for short-term reference" or "used for long-term reference" (but not both).

The variable currPicLayerId is set equal to nuh_layer_id of the current picture.

When the current picture is an IRAP picture with nuh_layer_id equal to 0, all reference pictures with any value of nuh_layer_id currently in the DPB (if any) are marked as "unused for reference" when at least one of the following conditions is true:

– The current picture has NoClrasOutputFlag is equal to 1.

– The current picture activates a new VPS.

When the current picture is an IRAP picture with NoRaslOutputFlag equal to 1, all reference pictures with nuh_layer_id equal to currPicLayerId currently in the DPB (if any) are marked as "unused for reference".

Short-term reference pictures are identified by their PicOrderCntVal values. Long-term reference pictures are identified either by their PicOrderCntVal values or their slice_pic_order_cnt_lsb values.

Five lists of picture order count values are constructed to derive the RPS. These five lists are PocStCurrBefore, PocStCurrAfter, PocStFoll, PocLtCurr, and PocLtFoll, with NumPocStCurrBefore, NumPocStCurrAfter, NumPocStFoll, NumPocLtCurr, and NumPocLtFoll number of elements, respectively. The five lists and the five variables are derived as follows:

– If the current picture is an IDR picture, PocStCurrBefore, PocStCurrAfter, PocStFoll, PocLtCurr, and PocLtFoll are all set to be empty, and NumPocStCurrBefore, NumPocStCurrAfter, NumPocStFoll, NumPocLtCurr, and NumPocLtFoll are all set equal to 0.

– Otherwise, the following applies:

```
for( i = 0, j = 0, k = 0; i < NumNegativePics[ CurrRpsIdx ] ; i++ )
    if( UsedByCurrPicS0[ CurrRpsIdx ][ i ] )
        PocStCurrBefore[ j++ ] = PicOrderCntVal + DeltaPocS0[ CurrRpsIdx ][ i ]
    else
        PocStFoll[ k++ ] = PicOrderCntVal + DeltaPocS0[ CurrRpsIdx ][ i ]
NumPocStCurrBefore = j

for( i = 0, j = 0; i < NumPositivePics[ CurrRpsIdx ]; i++ )
    if( UsedByCurrPicS1[ CurrRpsIdx ][ i ] )
        PocStCurrAfter[ j++ ] = PicOrderCntVal + DeltaPocS1[ CurrRpsIdx ][ i ]
    else
        PocStFoll[ k++ ] = PicOrderCntVal + DeltaPocS1[ CurrRpsIdx ][ i ]
NumPocStCurrAfter = j
NumPocStFoll = k                                                              (8-6)
for( i = 0, j = 0, k = 0; i < num_long_term_sps + num_long_term_pics; i++ ) {
    pocLt = PocLsbLt[ i ]
    if( delta_poc_msb_present_flag[ i ] )
        pocLt  +=  PicOrderCntVal − DeltaPocMsbCycleLt[ i ] * MaxPicOrderCntLsb −
                                    PicOrderCntVal & ( MaxPicOrderCntLsb − 1 )
    if( UsedByCurrPicLt[ i ] ) {
```

```
            PocLtCurr[ j ] = pocLt
            CurrDeltaPocMsbPresentFlag[ j++ ] = delta_poc_msb_present_flag[ i ]
        } else {
            PocLtFoll[ k ] = pocLt
            FollDeltaPocMsbPresentFlag[ k++ ] = delta_poc_msb_present_flag[ i ]
        }
    }
    NumPocLtCurr = j
    NumPocLtFoll = k
```

where PicOrderCntVal is the picture order count of the current picture as specified in subclause 8.3.1.

NOTE 2 – A value of CurrRpsIdx in the range of 0 to num_short_term_ref_pic_sets − 1, inclusive, indicates that a candidate short-term RPS from the active SPS for the current layer is being used, where CurrRpsIdx is the index of the candidate short-term RPS into the list of candidate short-term RPSs signalled in the active SPS for the current layer. CurrRpsIdx equal to num_short_term_ref_pic_sets indicates that the short-term RPS of the current picture is directly signalled in the slice header.

For each i in the range of 0 to NumPocLtCurr − 1, inclusive, when CurrDeltaPocMsbPresentFlag[i] is equal to 1, it is a requirement of bitstream conformance that the following conditions apply:

– There shall be no j in the range of 0 to NumPocStCurrBefore − 1, inclusive, for which PocLtCurr[i] is equal to PocStCurrBefore[j].

– There shall be no j in the range of 0 to NumPocStCurrAfter − 1, inclusive, for which PocLtCurr[i] is equal to PocStCurrAfter[j].

– There shall be no j in the range of 0 to NumPocStFoll − 1, inclusive, for which PocLtCurr[i] is equal to PocStFoll[j].

– There shall be no j in the range of 0 to NumPocLtCurr − 1, inclusive, where j is not equal to i, for which PocLtCurr[i] is equal to PocLtCurr[j].

For each i in the range of 0 to NumPocLtFoll − 1, inclusive, when FollDeltaPocMsbPresentFlag[i] is equal to 1, it is a requirement of bitstream conformance that the following conditions apply:

– There shall be no j in the range of 0 to NumPocStCurrBefore − 1, inclusive, for which PocLtFoll[i] is equal to PocStCurrBefore[j].

– There shall be no j in the range of 0 to NumPocStCurrAfter − 1, inclusive, for which PocLtFoll[i] is equal to PocStCurrAfter[j].

– There shall be no j in the range of 0 to NumPocStFoll − 1, inclusive, for which PocLtFoll[i] is equal to PocStFoll[j].

– There shall be no j in the range of 0 to NumPocLtFoll − 1, inclusive, where j is not equal to i, for which PocLtFoll[i] is equal to PocLtFoll[j].

– There shall be no j in the range of 0 to NumPocLtCurr − 1, inclusive, for which PocLtFoll[i] is equal to PocLtCurr[j].

For each i in the range of 0 to NumPocLtCurr − 1, inclusive, when CurrDeltaPocMsbPresentFlag[i] is equal to 0, it is a requirement of bitstream conformance that the following conditions apply:

– There shall be no j in the range of 0 to NumPocStCurrBefore − 1, inclusive, for which PocLtCurr[i] is equal to (PocStCurrBefore[j] & (MaxPicOrderCntLsb − 1)).

– There shall be no j in the range of 0 to NumPocStCurrAfter − 1, inclusive, for which PocLtCurr[i] is equal to (PocStCurrAfter[j] & (MaxPicOrderCntLsb − 1)).

– There shall be no j in the range of 0 to NumPocStFoll − 1, inclusive, for which PocLtCurr[i] is equal to (PocStFoll[j] & (MaxPicOrderCntLsb − 1)).

– There shall be no j in the range of 0 to NumPocLtCurr − 1, inclusive, where j is not equal to i, for which PocLtCurr[i] is equal to (PocLtCurr[j] & (MaxPicOrderCntLsb − 1)).

For each i in the range of 0 to NumPocLtFoll − 1, inclusive, when FollDeltaPocMsbPresentFlag[i] is equal to 0, it is a requirement of bitstream conformance that the following conditions apply:

– There shall be no j in the range of 0 to NumPocStCurrBefore − 1, inclusive, for which PocLtFoll[i] is equal to (PocStCurrBefore[j] & (MaxPicOrderCntLsb − 1)).

– There shall be no j in the range of 0 to NumPocStCurrAfter − 1, inclusive, for which PocLtFoll[i] is equal to (PocStCurrAfter[j] & (MaxPicOrderCntLsb − 1)).

– There shall be no j in the range of 0 to NumPocStFoll − 1, inclusive, for which PocLtFoll[i] is equal to (PocStFoll[j] & (MaxPicOrderCntLsb − 1)).

– There shall be no j in the range of 0 to NumPocLtFoll − 1, inclusive, where j is not equal to i, for which PocLtFoll[i] is equal to (PocLtFoll[j] & (MaxPicOrderCntLsb − 1)).

– There shall be no j in the range of 0 to NumPocLtCurr − 1, inclusive, for which PocLtFoll[i] is equal to (PocLtCurr[j] & (MaxPicOrderCntLsb − 1)).

The variable NumPicTotalCurr is derived as specified in subclause 7.4.7.2. It is a requirement of bitstream conformance that the following applies to the value of NumPicTotalCurr:

– If currPicLayerId is equal to 0 and the current picture is a BLA or CRA picture, the value of NumPicTotalCurr shall be equal to 0.

– Otherwise, when the current picture contains a P or B slice, the value of NumPicTotalCurr shall not be equal to 0.

The RPS of the current picture consists of five RPS lists; RefPicSetStCurrBefore, RefPicSetStCurrAfter, RefPicSetStFoll, RefPicSetLtCurr and RefPicSetLtFoll. RefPicSetStCurrBefore, RefPicSetStCurrAfter, and RefPicSetStFoll are collectively referred to as the short-term RPS. RefPicSetLtCurr and RefPicSetLtFoll are collectively referred to as the long-term RPS.

NOTE 3 – RefPicSetStCurrBefore, RefPicSetStCurrAfter, and RefPicSetLtCurr contain all reference pictures that may be used for inter prediction of the current picture and one or more pictures that follow the current picture in decoding order. RefPicSetStFoll and RefPicSetLtFoll consist of all reference pictures that are *not* used for inter prediction of the current picture but may be used in inter prediction for one or more pictures that follow the current picture in decoding order.

The derivation process for the RPS and picture marking are performed according to the following ordered steps:

1. The following applies:

```
for( i = 0; i < NumPocLtCurr; i++ )
    if( !CurrDeltaPocMsbPresentFlag[ i ] )
        if( there is a reference picture picX in the DPB with PicOrderCntVal & ( MaxPicOrderCntLsb − 1 )
                                equal to PocLtCurr[ i ] and nuh_layer_id equal to currPicLayerId )
            RefPicSetLtCurr[ i ] = picX
        else
            RefPicSetLtCurr[ i ] = "no reference picture"
    else
        if( there is a reference picture picX in the DPB with PicOrderCntVal equal to PocLtCurr[ i ]
                                and nuh_layer_id equal to currPicLayerId )
            RefPicSetLtCurr[ i ] = picX
        else
            RefPicSetLtCurr[ i ] = "no reference picture"                                   (8-7)
for( i = 0; i < NumPocLtFoll; i++ )
    if( !FollDeltaPocMsbPresentFlag[ i ] )
        if( there is a reference picture picX in the DPB with PicOrderCntVal & ( MaxPicOrderCntLsb − 1 )
                                equal to PocLtFoll[ i ] and nuh_layer_id equal to currPicLayerId )
            RefPicSetLtFoll[ i ] = picX
        else
            RefPicSetLtFoll[ i ] = "no reference picture"
    else
        if( there is a reference picture picX in the DPB with PicOrderCntVal equal to PocLtFoll[ i ]
                                and nuh_layer_id equal to currPicLayerId )
            RefPicSetLtFoll[ i ] = picX
        else
            RefPicSetLtFoll[ i ] = "no reference picture"
```

2. All reference pictures that are included in RefPicSetLtCurr or RefPicSetLtFoll and have nuh_layer_id equal to currPicLayerId are marked as "used for long-term reference".

3. The following applies:

```
for( i = 0; i < NumPocStCurrBefore; i++ )
    if( there is a short-term reference picture picX in the DPB
            with PicOrderCntVal equal to PocStCurrBefore[ i ] and nuh_layer_id equal to currPicLayerId )
        RefPicSetStCurrBefore[ i ] = picX
    else
        RefPicSetStCurrBefore[ i ] = "no reference picture"
```

```
for( i = 0; i < NumPocStCurrAfter; i++ )
    if( there is a short-term reference picture picX in the DPB
            with PicOrderCntVal equal to PocStCurrAfter[ i ] and nuh_layer_id equal to currPicLayerId )
        RefPicSetStCurrAfter[ i ] = picX
    else
        RefPicSetStCurrAfter[ i ] = "no reference picture"                    (8-8)

for( i = 0; i < NumPocStFoll; i++ )
    if( there is a short-term reference picture picX in the DPB
            with PicOrderCntVal equal to PocStFoll[ i ] and nuh_layer_id equal to currPicLayerId )
        RefPicSetStFoll[ i ] = picX
    else
        RefPicSetStFoll[ i ] = "no reference picture"
```

4. All reference pictures in the DPB that are not included in RefPicSetLtCurr, RefPicSetLtFoll, RefPicSetStCurrBefore, RefPicSetStCurrAfter, or RefPicSetStFoll and have nuh_layer_id equal to currPicLayerId are marked as "unused for reference".

NOTE 4 – There may be one or more entries in the RPS lists that are equal to "no reference picture" because the corresponding pictures are not present in the DPB. Entries in RefPicSetStFoll or RefPicSetLtFoll that are equal to "no reference picture" should be ignored. An unintentional picture loss should be inferred for each entry in RefPicSetStCurrBefore, RefPicSetStCurrAfter, or RefPicSetLtCurr that is equal to "no reference picture".

NOTE 5 – A picture cannot be included in more than one of the five RPS lists.

It is a requirement of bitstream conformance that the RPS is restricted as follows:

- There shall be no entry in RefPicSetStCurrBefore, RefPicSetStCurrAfter, or RefPicSetLtCurr for which one or more of the following are true:
  - The entry is equal to "no reference picture".
  - The entry is a sub-layer non-reference picture and has TemporalId equal to that of the current picture.
  - The entry is a picture that has TemporalId greater than that of the current picture.
- There shall be no entry in RefPicSetLtCurr or RefPicSetLtFoll for which the difference between the picture order count value of the current picture and the picture order count value of the entry is greater than or equal to 2^{24}.
- When the current picture is a TSA picture, there shall be no picture included in the RPS with TemporalId greater than or equal to the TemporalId of the current picture.
- When the current picture is an STSA picture, there shall be no picture included in RefPicSetStCurrBefore, RefPicSetStCurrAfter, or RefPicSetLtCurr that has TemporalId equal to that of the current picture.
- When the current picture is a picture that follows, in decoding order, an STSA picture that has TemporalId equal to that of the current picture, there shall be no picture that has TemporalId equal to that of the current picture included in RefPicSetStCurrBefore, RefPicSetStCurrAfter, or RefPicSetLtCurr that precedes the STSA picture in decoding order.
- When the current picture is a CRA picture, there shall be no picture included in the RPS that precedes, in decoding order, any preceding IRAP picture in decoding order (when present).
- When the current picture is a trailing picture, there shall be no picture in RefPicSetStCurrBefore, RefPicSetStCurrAfter, or RefPicSetLtCurr that was generated by the decoding process for generating unavailable reference pictures as specified in clause 8.3.3.
- When the current picture is a trailing picture, there shall be no picture in the RPS that precedes the associated IRAP picture in output order or decoding order.
- When the current picture is a RADL picture, there shall be no picture included in RefPicSetStCurrBefore, RefPicSetStCurrAfter, or RefPicSetLtCurr that is any of the following:
  - A RASL picture
  - A picture that was generated by the decoding process for generating unavailable reference pictures as specified in clause 8.3.3
  - A picture that precedes the associated IRAP picture in decoding order
- When sps_temporal_id_nesting_flag is equal to 1, the following applies:
  - Let tIdA be the value of TemporalId of the current picture picA.

  - Any picture picB with TemporalId equal to tIdB that is less than or equal to tIdA shall not be included in RefPicSetStCurrBefore, RefPicSetStCurrAfter, or RefPicSetLtCurr of picA when there exists a picture picC that has TemporalId less than tIdB, follows picB in decoding order, and precedes picA in decoding order.

– There shall be no picture in the RPS that has discardable_flag equal to 1.

8.3.3 Decoding process for generating unavailable reference pictures

8.3.3.1 General decoding process for generating unavailable reference pictures

This process is invoked once per coded picture when the current picture is a BLA picture or is a CRA picture with NoRaslOutputFlag equal to 1.

NOTE – This process is primarily specified only for the specification of syntax constraints for RASL pictures. The entire specification of the decoding process for RASL pictures associated with an IRAP picture that has NoRaslOutputFlag equal to 1 is included herein only for purposes of specifying constraints on the allowed syntax content of such RASL pictures. During the decoding process, any RASL pictures associated with an IRAP picture that has NoRaslOutputFlag equal to 1 may be ignored, as these pictures are not specified for output and have no effect on the decoding process of any other pictures that are specified for output. However, in HRD operations as specified in Annex C, RASL access units may need to be taken into consideration in derivation of CPB arrival and removal times.

When this process is invoked, the following applies:

– For each RefPicSetStFoll[i], with i in the range of 0 to NumPocStFoll − 1, inclusive, that is equal to "no reference picture", a picture is generated as specified in subclause 8.3.3.2, and the following applies:
  - The value of PicOrderCntVal for the generated picture is set equal to PocStFoll[i].
  - The value of PicOutputFlag for the generated picture is set equal to 0.
  - The generated picture is marked as "used for short-term reference".
  - RefPicSetStFoll[i] is set to be the generated reference picture.
  - The value of nuh_layer_id for the generated picture is inferred to be equal to nuh_layer_id.

– For each RefPicSetLtFoll[i], with i in the range of 0 to NumPocLtFoll − 1, inclusive, that is equal to "no reference picture", a picture is generated as specified in subclause 8.3.3.2, and the following applies:
  - The value of PicOrderCntVal for the generated picture is set equal to PocLtFoll[i].
  - The value of slice_pic_order_cnt_lsb for the generated picture is inferred to be equal to (PocLtFoll[i] & (MaxPicOrderCntLsb − 1)).
  - The value of PicOutputFlag for the generated picture is set equal to 0.
  - The generated picture is marked as "used for long-term reference".
  - RefPicSetLtFoll[i] is set to be the generated reference picture.
  - The value of nuh_layer_id for the generated picture is inferred to be equal to nuh_layer_id.

Add a new subclause "A.3.6 Monochrome 8 profile". [Ed (MH): If a RExt profile_idc is used, the Monochrome 8 profile specification should be appended into A.3.5 instead.]

A.3.6 Monochrome 8 profile

Bitstreams conforming to the Monochrome 8 profile shall obey all constraints of the Main profile with the following exceptions:

– SPSs shall have chroma_format_idc equal to 0 only.

Conformance of a bitstream to the Monochrome 8 profile is indicated by general_profile_idc being equal to X or general_profile_compatibility_flag[X] being equal to 1. [Ed. (JB): Consider whether to use the RExt profile_idc or a separate profile_idc for Monochrome 8 profile. This section requires further editorial changes after integration with RExt specification.]

Replace Annex C with the following (with differences indicated in turquois):

Annex C

Hypothetical reference decoder

(This annex forms an integral part of this Recommendation | International Standard)

C.1 General

This annex specifies the hypothetical reference decoder (HRD) and its use to check bitstream and decoder conformance.

Two types of bitstreams or bitstream subsets are subject to HRD conformance checking for this Specification. The first type, called a Type I bitstream, is a NAL unit stream containing only the VCL NAL units and NAL units with nal_unit_type equal to FD_NUT (filler data NAL units) for all access units in the bitstream. The second type, called a Type II bitstream, contains, in addition to the VCL NAL units and filler data NAL units for all access units in the bitstream, at least one of the following:

– additional non-VCL NAL units other than filler data NAL units,

– all leading_zero_8bits, zero_byte, start_code_prefix_one_3bytes, and trailing_zero_8bits syntax elements that form a byte stream from the NAL unit stream (as specified in Annex B).

Figure C-1 shows the types of bitstream conformance points checked by the HRD.

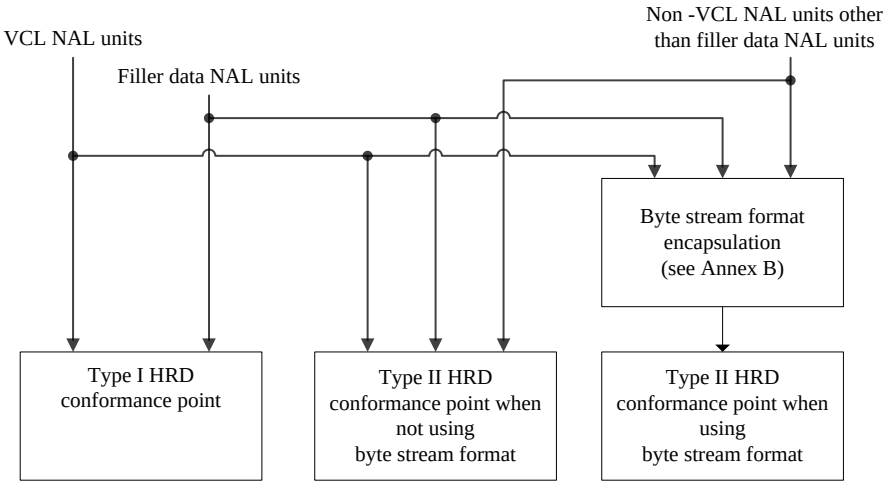

Figure C-1 – Structure of byte streams and NAL unit streams for HRD conformance checks

The syntax elements of non-VCL NAL units (or their default values for some of the syntax elements), required for the HRD, are specified in the semantic subclauses of clause 7, Annexes D and E.

Two types of HRD parameter sets (NAL HRD parameters and VCL HRD parameters) are used. The HRD parameter sets are signalled through the hrd_parameters( ) syntax structure, which may be part of the SPS syntax structure or the VPS syntax structure.

Multiple tests may be needed for checking the conformance of a bitstream, which is referred to as the bitstream under test. For each test, the following steps apply in the order listed:

1. An output operation point under test, denoted as TargetOp, is selected by selecting a value for TargetOlsIdx identifying a target OLS and selecting a target highest TemporalId value HighestTid. The value of TargetOlsIdx shall be in the range of 0 to NumOutputLayerSets − 1, inclusive. The value of HighestTid shall be in the range of 0 to MaxSubLayersInLayerSetMinus1[OlsIdxToLsIdx [TargetOlsIdx]], inclusive. The variables TargetDecLayerSetIdx, TargetOptLayerIdList, and TargetDecLayerIdList are then derived as specified by Equation 8-1. The output operation point under test has OptLayerIdList equal to TargetOptLayerIdList, OpLayerIdList equal to TargetDecLayerIdList, and OpTid equal to HighestTid.
2. The sub-bitstream extraction process as specified in clause 10 is invoked with the bitstream under test, HighestTid, and TargetDecLayerIdList as inputs, and the output is assigned to BitstreamToDecode.

3. When both the vps_vui_bsp_hrd_parameters( ) syntax structure is present in the active VPS and num_bitstream_partitions[TargetDecLayerSetIdx] is greater than 1 or both a bitstream partition HRD parameters SEI message is present and the SEI message contains syntax element num_sei_bitstream_partitions_minus1[TargetDecLayerSetIdx] greater than 0, either the bitstream-specific CPB operation or the bitstream-partition-specific CPB operation is selected for a conformance test, and both CPB operations shall be tested for checking the conformance of a bitstream. When the bitstream-specific CPB operation is tested, the subsequent steps apply for the bitstream under test. When the bitstream-partition-specific CPB operation is tested, the subsequent steps apply to each bitstream partition of the bitstream under test, referred to as the bitstream partition under test. When the bitstream-partition-specific CPB operation is tested and the input to the HRD is a bitstream, the bitstream partitions are derived with the demultiplexing process for deriving a bitstream partition in subclause C.6.
4. The hrd_parameters( ) syntax structure and the sub_layer_hrd_parameters( ) syntax structure applicable to TargetOp are selected as follows:
   – If the bitstream-specific CPB operation is tested, the following applies:
     – If TargetDecLayerIdList contains all nuh_layer_id values present in the bitstream under test, the hrd_parameters( ) syntax structure in the active SPS for the base layer (or provided through an external means not specified in this Specification) is selected.
     – Otherwise, the hrd_parameters( ) syntax structure in the active VPS (or provided through some external means not specified in this Specification) that applies to TargetOp is selected.
   – Otherwise, the hrd_parameters( ) syntax structure is selected as follows:
     – Either one of the hrd_parameters( ) syntax structures in the following conditions can be selected, if both of the following conditions are true:
       – The vps_vui_bsp_hrd_parameters( ) syntax structure is present in the active VPS (or is available through some external means not specified in this Specification) and contains a hrd_parameters( ) syntax structure that applies to TargetOp and to the bitstream partition under test.
       – A bitstream partition HRD parameters SEI message that is included in a scalable nesting SEI message that applies to TargetOp and contains a hrd_parameters( ) syntax structure that applies to TargetOp and to the bitstream partition under test is present (or is available through some external means not specified in this Specification).
     – Otherwise, if the vps_vui_bsp_hrd_parameters( ) syntax structure is present in the active VPS (or is available through some external means not specified in this Specification) and contains a hrd_parameters( ) syntax structure that applies to TargetOp and the bitstream partition under test, that hrd_parameters( ) syntax structure is selected.
     – Otherwise, a hrd_parameters( ) syntax structure that applies to the bitstream partition under test in the bitstream partition HRD parameters SEI message that is included in a scalable nesting SEI message that applies to TargetOp shall be present (or shall be available through some external means not specified in this Specification) and is selected.

   Within the selected hrd_parameters( ) syntax structure, if BitstreamToDecode is a Type I bitstream, the sub_layer_hrd_parameters(HighestTid) syntax structure that immediately follows the condition "if(vcl_hrd_parameters_present_flag)" is selected and the variable NalHrdModeFlag is set equal to 0; otherwise (BitstreamToDecode is a Type II bitstream), the sub_layer_hrd_parameters(HighestTid) syntax structure that immediately follows either the condition "if(vcl_hrd_parameters_present_flag)" (in this case the variable NalHrdModeFlag is set equal to 0) or the condition "if(nal_hrd_parameters_present_flag)" (in this case the variable NalHrdModeFlag is set equal to 1) is selected. When BitstreamToDecode is a Type II bitstream and NalHrdModeFlag is equal to 0, all non-VCL NAL units except filler data NAL units, and all leading_zero_8bits, zero_byte, start_code_prefix_one_3bytes, and trailing_zero_8bits syntax elements that form a byte stream from the NAL unit stream (as specified in Annex B), when present, are discarded from BitstreamToDecode, and the remaining bitstream is assigned to BitstreamToDecode.
5. An access unit associated with a buffering period SEI message (present in BitstreamToDecode or available through external means not specified in this Specification) applicable to TargetOp is selected as the HRD initialization point and referred to as access unit 0. An applicable buffering period SEI message is available through external means not specified in this Specification or is selected from access unit 0 as follows:
   – If the bitstream-specific CPB operation is tested, the following applies:
     – If TargetDecLayerIdList contains all nuh_layer_id values present in the bitstream under test, a non-nested buffering period SEI message is selected.
     – Otherwise, a buffering period SEI message included in the scalable nesting SEI message with bitstream_subset_flag equal to 1 and applicable to TargetOp is selected.

– Otherwise, a buffering period SEI message included in the bitstream partition nesting SEI message applicable to the bitstream partition under test is selected.

The variable MultiLayerCpbOperationFlag is derived as follows:

– If the selected buffering period SEI message is non-nested or is included in a scalable nesting SEI message that applies only to the sub-bitstream that contains only the base layer, MultiLayerCpbOperationFlag is set equal to 0.

– Otherwise, MultiLayerCpbOperationFlag is set equal to 1.

6. For each access unit in BitstreamToDecode starting from access unit 0, the buffering period SEI message (present in BitstreamToDecode or available through external means not specified in this Specification) that is associated with the access unit and applies to TargetOp is selected, the picture timing SEI message (present in BitstreamToDecode or available through external means not specified in this Specification) that is associated with the access unit and applies to TargetOp is selected, and when SubPicHrdFlag is equal to 1 and sub_pic_cpb_params_in_pic_timing_sei_flag is equal to 0, the decoding unit information SEI messages (present in BitstreamToDecode or available through external means not specified in this Specification) that are associated with decoding units in the access unit and apply to TargetOp are selected as follows:

– If the bitstream-specific CPB operation is tested, the following applies:

  – If TargetDecLayerIdList contains all nuh_layer_id values present in the bitstream under test, non-nested buffering period, picture timing and decoding unit information SEI messages are selected.

  – Otherwise, buffering period, picture timing and decoding unit information SEI messages included in the scalable nesting SEI message with bitstream_subset_flag equal to 1 and applicable to TargetOp are selected.

– Otherwise, buffering period, picture timing and decoding unit information SEI messages included in the bitstream partition nesting SEI message and applicable to the bitstream partition under test are selected.

7. A value of SchedSelIdx is selected as follows:

– If the bitstream-specific CPB operation is tested, the selected SchedSelIdx shall be in the range of 0 to cpb_cnt_minus1[HighestTid], inclusive, where cpb_cnt_minus1[HighestTid] is found in the sub_layer_hrd_parameters(HighestTid) syntax structure as selected above.

– Otherwise (the bitstream-partition-specific CPB operation is tested), a SchedSelCombIdx is selected for the bitstream under test and used for each bitstream partition under test. The following applies:

  – If the vps_vui_bsp_hrd_parameters( ) syntax structure is present in the active VPS (or made available through external means not specified in this Specification) and contains the selected hrd_parameters( ) syntax structure that applies to TargetOp and the bitstream partition under test, the selected SchedSelCombIdx shall be in the range of 0 to num_bsp_sched_combinations_minus1[TargetDecLayerSetIdx], inclusive, and the selected SchedSelIdx shall be equal to bsp_comb_sched_idx[TargetDecLayerSetIdx][SchedSelCombIdx][j] where j is the index of the bitstream partition under test.

  – Otherwise, the selected SchedSelCombIdx shall be in the range of 0 to sei_num_bsp_sched_combinations_minus1[TargetDecLayerSetIdx], inclusive, and the selected SchedSelIdx shall be equal to sei_bsp_comb_sched_idx[TargetDecLayerSetIdx][SchedSelCombIdx][j] of the bitstream partition HRD parameters SEI message applicable to TargetOp where j is the index of the bitstream partition under test.

8. The variable initialAltParamSelectionFlag is derived as follows:

– If all of the following conditions are true, initialAltParamSelectionFlag is set equal to 1:

  – The coded picture with nuh_layer_id equal to 0 in access unit 0 has nal_unit_type equal to CRA_NUT or BLA_W_LP.

  – MultiLayerCpbOperationFlag is equal to 0.

  – irap_cpb_params_present_flag in the selected buffering period SEI message is equal to 1.

– Otherwise, if all of the following conditions are true, initialAltParamSelectionFlag is set equal to 1:

  – The coded picture with nuh_layer_id equal to 0 in access unit 0 is an IRAP picture,

  – MultiLayerCpbOperationFlag is equal to 1.

  – irap_cpb_params_present_flag in the selected buffering period SEI message is equal to 1.

– Otherwise, initialAltParamSelectionFlag is set equal to 0.

– When initialAltParamSelectionFlag is equal to 1, the following applies:
  – If the selected buffering period SEI message is included in a scalable nesting SEI message that applies at least to one sub-bitstream that contains more than one layer, a set of skipped leading pictures skippedPictureList consists of the CL-RAS pictures and the RASL pictures associated with the IRAP pictures with nuh_layer_id equal to nuhLayerId for which LayerInitializedFlag[nuhLayerId] is equal to 0 at the start of decoding the IRAP picture and for which nuhLayerId is among TargetDecLayerIdList. Otherwise (a buffering period SEI message is not nested in a scalable nesting SEI message), skippedPictureList consists of the RASL pictures associated with the coded picture with nuh_layer_id equal to 0 in access unit 0.
  – Either of the following applies for selection of the initial CPB removal delay and delay offset:

[Ed. (JB): "Either of the following applies" language is unclear. How is it known which one(s) apply? (MH): This phrasing is from version 1. I suppose the intent is to let the HRD to pick either one of the following arbitrarily for its operation. (YK): The intent is to choose either one of the two first, and then to choose the other one, as each possible combination needs to be tested. However, this intent is indeed not clearly specified. We can try to improve it at the next editing session in Sapporo.]

    – If NalHrdModeFlag is equal to 1, the default initial CPB removal delay and delay offset represented by nal_initial_cpb_removal_delay[SchedSelIdx] and nal_initial_cpb_removal_offset[SchedSelIdx], respectively, in the selected buffering period SEI message are selected. Otherwise, the default initial CPB removal delay and delay offset represented by vcl_initial_cpb_removal_delay[SchedSelIdx] and vcl_initial_cpb_removal_offset[SchedSelIdx], respectively, in the selected buffering period SEI message are selected. The variable DefaultInitCpbParamsFlag is set equal to 1.
    – If NalHrdModeFlag is equal to 1, the alternative initial CPB removal delay and delay offset represented by nal_initial_alt_cpb_removal_delay[SchedSelIdx] and nal_initial_alt_cpb_removal_offset[SchedSelIdx], respectively, in the selected buffering period SEI message are selected. Otherwise, the alternative initial CPB removal delay and delay offset represented by vcl_initial_alt_cpb_removal_delay[SchedSelIdx] and vcl_initial_alt_cpb_removal_offset[SchedSelIdx], respectively, in the selected buffering period SEI message are selected. The variable DefaultInitCpbParamsFlag is set equal to 0, and all the pictures in skippedPictureList are discarded from BitstreamToDecode and the remaining bitstream is assigned to BitstreamToDecode.

9. For the bitstream-partition-specific CPB operation, SubPicHrdFlag is set equal to 1. For the bitstream-specific CPB operation, when sub_pic_hrd_params_present_flag in the selected hrd_parameters( ) syntax structure is equal to 1, the CPB is scheduled to operate either at the access unit level (in which case the variable SubPicHrdFlag is set equal to 0) or at the sub-picture level (in which case the variable SubPicHrdFlag is set equal to 1).

For each output operation point under test when the bitstream-specific CPB operation is tested, the number of bitstream conformance tests to be performed is equal to n0 * n1 * (n2 * 2 + n3) * n4, where the values of n0, n1, n2, n3, and n4 are specified as follows:

– n0 is derived as follows:
  – If BitstreamToDecode is a Type I bitstream, n0 is equal to 1.
  – Otherwise (BitstreamToDecode is a Type II bitstream), n0 is equal to 2.
– n1 is equal to cpb_cnt_minus1[HighestTid] + 1.
– n2 is the number of access units in BitstreamToDecode that each is associated with a buffering period SEI message applicable to TargetOp and for each of which both of the following conditions are true:
  – nal_unit_type is equal to CRA_NUT or BLA_W_LP for the VCL NAL units;
  – The associated buffering period SEI message applicable to TargetOp has irap_cpb_params_present_flag equal to 1.
– n3 is the number of access units in BitstreamToDecode that each is associated with a buffering period SEI message applicable to TargetOp and for each of which one or both of the following conditions are true:
  – nal_unit_type is equal to neither CRA_NUT nor BLA_W_LP for the VCL NAL units;
  – The associated buffering period SEI message applicable to TargetOp has irap_cpb_params_present_flag equal to 0.
– n4 is derived as follows:
  – If sub_pic_hrd_params_present_flag in the selected hrd_parameters( ) syntax structure is equal to 0, n4 is equal to 1;

– Otherwise, n4 is equal to 2.

When BitstreamToDecode is a Type II bitstream, the following applies:

– If the sub_layer_hrd_parameters(HighestTid) syntax structure that immediately follows the condition "if(vcl_hrd_parameters_present_flag)" is selected, the test is conducted at the Type I conformance point shown in Figure C-1, and only VCL and filler data NAL units are counted for the input bit rate and CPB storage.

– Otherwise (the sub_layer_hrd_parameters(HighestTid) syntax structure that immediately follows the condition "if(nal_hrd_parameters_present_flag)" is selected), the test is conducted at the Type II conformance point shown in Figure C-1, and all bytes of the Type II bitstream, which may be a NAL unit stream or a byte stream, are counted for the input bit rate and CPB storage.

NOTE 1 – NAL HRD parameters established by a value of SchedSelIdx for the Type II conformance point shown in Figure C-1 are sufficient to also establish VCL HRD conformance for the Type I conformance point shown in Figure C-1 for the same values of InitCpbRemovalDelay[SchedSelIdx], BitRate[SchedSelIdx], and CpbSize[SchedSelIdx] for the VBR case (cbr_flag[SchedSelIdx] equal to 0). This is because the data flow into the Type I conformance point is a subset of the data flow into the Type II conformance point and because, for the VBR case, the CPB is allowed to become empty and stay empty until the time a next picture is scheduled to begin to arrive. For example, when decoding a CVS conforming to one or more of the profiles specified in Annex A using the decoding process specified in clauses 2 through 10, when NAL HRD parameters are provided for the Type II conformance point that not only fall within the bounds set for NAL HRD parameters for profile conformance in item f) of subclause A.4.2 but also fall within the bounds set for VCL HRD parameters for profile conformance in item e) of subclause A.4.2, conformance of the VCL HRD for the Type I conformance point is also assured to fall within the bounds of item e) of subclause A.4.2.

All VPSs, SPSs and PPSs referred to in the VCL NAL units, and the corresponding buffering period, picture timing and decoding unit information SEI messages shall be conveyed to the HRD, in a timely manner, either in the bitstream (by non-VCL NAL units), or by other means not specified in this Specification.

In Annexes C, D, and E, the specification for "presence" of non-VCL NAL units that contain VPSs, SPSs, PPSs, buffering period SEI messages, picture timing SEI messages, or decoding unit information SEI messages is also satisfied when those NAL units (or just some of them) are conveyed to decoders (or to the HRD) by other means not specified in this Specification. For the purpose of counting bits, only the appropriate bits that are actually present in the bitstream are counted.

NOTE 2 – As an example, synchronization of such a non-VCL NAL unit, conveyed by means other than presence in the bitstream, with the NAL units that are present in the bitstream, can be achieved by indicating two points in the bitstream, between which the non-VCL NAL unit would have been present in the bitstream, had the encoder decided to convey it in the bitstream.

When the content of such a non-VCL NAL unit is conveyed for the application by some means other than presence within the bitstream, the representation of the content of the non-VCL NAL unit is not required to use the same syntax as specified in this Specification.

NOTE 3 – When HRD information is contained within the bitstream, it is possible to verify the conformance of a bitstream to the requirements of this subclause based solely on information contained in the bitstream. When the HRD information is not present in the bitstream, as is the case for all "stand-alone" Type I bitstreams, conformance can only be verified when the HRD data are supplied by some other means not specified in this Specification.

For the bitstream-specific CPB operation, the HRD contains a coded picture buffer (CPB), an instantaneous decoding process, a decoded picture buffer (DPB) that contains a sub-DPB for each layer, and output cropping as shown in Figure C-2.

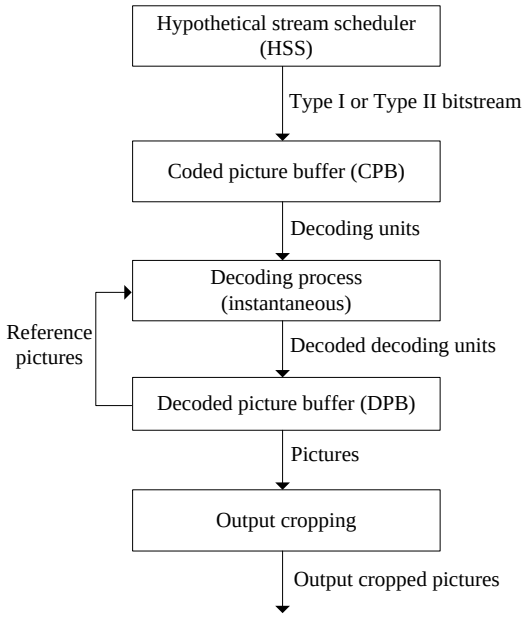

Figure C-2 – Bitstream-specific HRD buffer model

For the bitstream-partition-specific CPB operation, the HRD contains a bitstream demultiplexer (optionally present), two or more bitstream partition buffers (BPB), two or more instantaneous decoding processes, a decoded picture buffer (DPB) that contains a sub-DPB for each layer, and output cropping as shown in Figure C-3.

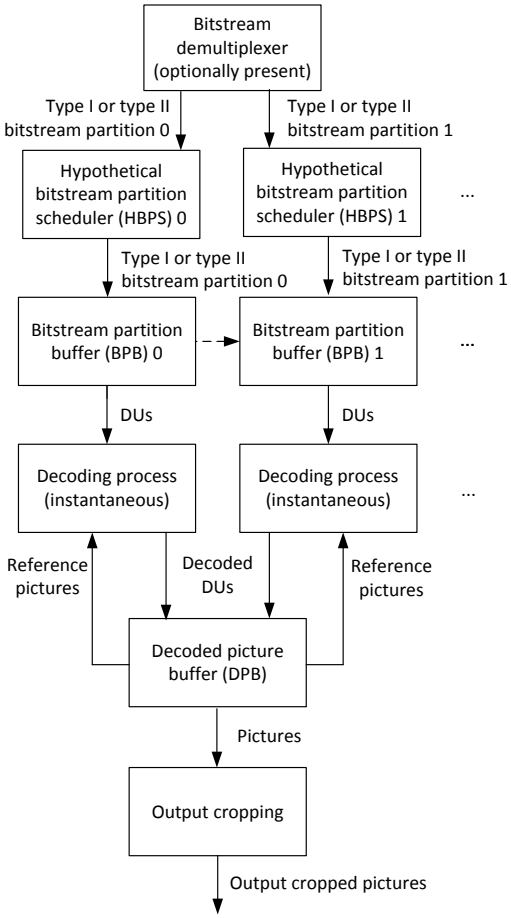

Figure C-3 – Bitstream-partition-specific HRD buffer model

[Ed. (JO): Is the scheduler part of the Decoder? To me it seems that the decoder should start with the demultiplexer, and a single hypothetical bitstream partition scheduler (responsible in managing all partitions) should be a block in front of that (MH): The order of bitstream demultiplexer and HBPSs is correct in the figure. Bitstream partitions may be

delivered by HBPSs to BPBs using different bitrates, hence the data streams are separated in the figure. The intent is also to indicate that the bitstream demultiplexer is optionally present and that the coded data may be readily organized in bitstream partitions rather than a united bitstream.]

For each bitstream conformance test, the CPB size (number of bits) for the bitstream-specific CPB operation and the BPB size for the bitstream-partition-specific CPB operation is CpbSize[SchedSelIdx] as specified in subclause E.3.3, where SchedSelIdx and the HRD parameters are specified above in this subclause. The sub-DPB size of the sub-DPB for a layer with nuh_layer_id equal to currLayerId is max_vps_dec_pic_buffering_minus1[TargetOlsIdx][layerIdx][HighestTid] + 1, where layerIdx is equal to the value such that LayerSetLayerIdList[TargetDecLayerSetIdx][layerIdx] is equal to currLayerId.

The variable SubPicHrdPreferredFlag is either specified by external means, or when not specified by external means, set equal to 0.

When the value of the variable SubPicHrdFlag has not been set by step 9 above in this subclause, it is derived as follows:

SubPicHrdFlag = SubPicHrdPreferredFlag && sub_pic_hrd_params_present_flag (C-1)

If SubPicHrdFlag is equal to 0, the HRD operates at access unit level and each decoding unit is an access unit. Otherwise the HRD operates at sub-picture level and each decoding unit is a subset of an access unit.

NOTE 4 – If the HRD operates at access unit level, each time a decoding unit that is an entire access unit is removed from the CPB. Otherwise (the HRD operates at sub-picture level), each time a decoding unit that is a subset of an access unit is removed from the CPB. In both cases, each time an entire decoded picture is output from the DPB, though the picture output time is derived based on the differently derived CPB removal times and the differently signalled DPB output delays.

The following is specified for expressing the constraints in this annex:

– Each access unit is referred to as access unit n, where the number n identifies the particular access unit. Access unit 0 is selected per step 5 above. The value of n is incremented by 1 for each subsequent access unit in decoding order.

– Each decoding unit is referred to as decoding unit m, where the number m identifies the particular decoding unit. The first decoding unit in decoding order in access unit 0 is referred to as decoding unit 0. The value of m is incremented by 1 for each subsequent decoding unit in decoding order.

NOTE 5 – The numbering of decoding units is relative to the first decoding unit in access unit 0.

– Picture n refers to the coded picture or the decoded picture of access unit n.

The HRD operates as follows:

– The HRD is initialized at decoding unit 0, with the CPB, each sub-DPB of the DPB, and each BPB being set to be empty (the sub-DPB fullness for each sub-DPB is set equal to 0).

NOTE 6 – After initialization, the HRD is not initialized again by subsequent buffering period SEI messages.

– For the bitstream-specific CPB operation, data associated with decoding units that flow into the CPB according to a specified arrival schedule are delivered by the HSS. For the bitstream-partition-specific CPB operation, data associated with decoding units that flow into the BPB according to a specified arrival schedule are delivered by an HBPS.

– When the bitstream-partition-specific CPB operation is used, each bitstream partition with index j is processed as specified in clause C.2 with the HSS replaced by the HPBS and with SchedSelIdx equal to bsp_comb_sched_idx[TargetDecLayerSetIdx][SchedSelCombIdx][j], if vps_vui_bsp_hrd_parameters( ) syntax structure is present in the active VPS or is available through some external means not specified in this Specification), or equal to sei_bsp_comb_sched_idx[TargetDecLayerSetIdx][SchedSelCombIdx][j] of the bitstream partition HRD parameters SEI message applicable to TargetOp, otherwise.

– The data associated with each decoding unit are removed and decoded instantaneously by the instantaneous decoding process at the CPB removal time of the decoding unit.

– Each decoded picture is placed in the DPB.

– A decoded picture is removed from the DPB when it becomes no longer needed for inter prediction reference and no longer needed for output.

For each bitstream conformance test, the operation of the CPB and the BPB is specified in subclause C.2, the instantaneous decoder operation is specified in clauses 2 through 10, the operation of the DPB is specified in subclause C.3, and the output cropping is specified in subclause C.3.3 and subclause C.5.2.2.

HSS, HBPS and HRD information concerning the number of enumerated delivery schedules and their associated bit rates and buffer sizes is specified in subclauses E.2.2 and E.3.2. The HRD is initialized as specified by the buffering period SEI message specified in subclauses D.2.2 and D.3.2. The removal timing of decoding units from the CPB and output

timing of decoded pictures from the DPB is specified using information in picture timing SEI messages (specified in subclauses D.2.3 and D.3.3) or in decoding unit information SEI messages (specified in subclauses D.2.21 and D.3.21). All timing information relating to a specific decoding unit shall arrive prior to the CPB removal time of the decoding unit.

The requirements for bitstream conformance are specified in subclause C.4, and the HRD is used to check conformance of bitstreams as specified above in this subclause and to check conformance of decoders as specified in subclause 11.

NOTE 7 – While conformance is guaranteed under the assumption that all picture-rates and clocks used to generate the bitstream match exactly the values signalled in the bitstream, in a real system each of these may vary from the signalled or specified value.

All the arithmetic in this annex is performed with real values, so that no rounding errors can propagate. For example, the number of bits in a CPB just prior to or after removal of a decoding unit is not necessarily an integer.

The variable ClockTick is derived as follows and is called a clock tick:

$$ClockTick = vui\_num\_units\_in\_tick \div vui\_time\_scale \quad (C\text{-}2)$$

The variable ClockSubTick is derived as follows and is called a clock sub-tick:

$$ClockSubTick = ClockTick \div (tick\_divisor\_minus2 + 2) \quad (C\text{-}3)$$

C.2 Operation of coded picture buffer (CPB) and bitstream partition buffer (BPB)

C.2.1 General

The specifications in this subclause apply independently to each set of CPB parameters that is present and to both the Type I and Type II conformance points shown in Figure C-1, and the set of CPB parameters is selected as specified in subclause C.1.

C.2.2 Timing of decoding unit arrival

The variable altParamSelectionFlag is derived as follows:

– If all of the following conditions are true, altParamSelectionFlag is set equal to 1:
  – The current picture is a BLA picture that has nal_unit_type equal to BLA_W_LP and nuh_layer_id equal to 0 or is a CRA picture that has nuh_layer_id equal to 0.
  – MultiLayerCpbOperationFlag is equal to 0.
– Otherwise, if all of the following conditions are true, altParamSelectionFlag is set equal to 1:
  – The current picture is an IRAP picture with nuh_layer_id equal to 0 and with NoClrasOutputFlag equal to 1.
  – MultiLayerCpbOperationFlag is equal to 1.
– Otherwise, altParamSelectionFlag is set equal to 0.

When altParamSelectionFlag is equal to 1, the following applies:

– If some external means not specified in this Specification is available to set the variable UseAltCpbParamsFlag to a value, UseAltCpbParamsFlag is set equal to the value provided by the external means.
– Otherwise, UseAltCpbParamsFlag is set equal to the value of use_alt_cpb_params_flag of the buffering period SEI message selected as specified in subclause C.1.

If SubPicHrdFlag is equal to 0, the variable subPicParamsFlag is set equal to 0, and the process specified in the remainder of this subclause is invoked with a decoding unit being considered as an access unit, for derivation of the initial and final CPB arrival times for access unit n.

Otherwise (SubPicHrdFlag is equal to 1), the process specified in the remainder of this subclause is first invoked with the variable subPicParamsFlag set equal to 0 and a decoding unit being considered as an access unit, for derivation of the initial and final CPB arrival times for access unit n, and then invoked with subPicParamsFlag set equal to 1 and a decoding unit being considered as a subset of an access unit, for derivation of the initial and final CPB arrival times for the decoding units in access unit n.

The variables InitCpbRemovalDelay[SchedSelIdx] and InitCpbRemovalDelayOffset[SchedSelIdx] are derived as follows:

– If one or more of the following conditions are true, InitCpbRemovalDelay[SchedSelIdx] and InitCpbRemovalDelayOffset[SchedSelIdx] are set equal to the values of the buffering period SEI message syntax elements nal_initial_alt_cpb_removal_delay[SchedSelIdx] and nal_initial_alt_cpb_removal_offset[SchedSelIdx],

respectively, when NalHrdModeFlag is equal to 1, or vcl_initial_alt_cpb_removal_delay[SchedSelIdx] and vcl_initial_alt_cpb_removal_offset[SchedSelIdx], respectively, when NalHrdModeFlag is equal to 0, where the buffering period SEI message syntax elements are selected as specified in subclause C.1:

- Access unit 0 includes a BLA picture with nuh_layer_id equal to 0 and nal_unit_type equal to BLA_W_RADL or BLA_N_LP, MultiLayerCpbOperationFlag is equal to 0 and the value of irap_cpb_params_present_flag of the buffering period SEI message is equal to 1.
- Access unit 0 includes a BLA picture with nuh_layer_id equal to 0 and nal_unit_type equal to BLA_W_LP or includes a CRA picture with nuh_layer_id equal to 0, MultiLayerCpbOperationFlag is equal to 0, and the value of irap_cpb_params_present_flag of the buffering period SEI message is equal to 1, and one or more of the following conditions are true:
  - UseAltCpbParamsFlag for access unit 0 is equal to 1.
  - DefaultInitCpbParamsFlag is equal to 0.
- Access unit 0 includes an IRAP picture with nuh_layer_id equal to 0, MultiLayerCpbOperationFlag is equal to 1 and the value of irap_cpb_params_present_flag of the buffering period SEI message is equal to 1, and one or more of the following conditions are true:
  - UseAltCpbParamsFlag for access unit 0 is equal to 1.
  - DefaultInitCpbParamsFlag is equal to 0.
- The value of subPicParamsFlag is equal to 1.

– Otherwise, InitCpbRemovalDelay[SchedSelIdx] and InitCpbRemovalDelayOffset[SchedSelIdx] are set equal to the values of the buffering period SEI message syntax elements nal_initial_cpb_removal_delay[SchedSelIdx] and nal_initial_cpb_removal_offset[SchedSelIdx], respectively, when NalHrdModeFlag is equal to 1, or vcl_initial_cpb_removal_delay[SchedSelIdx] and vcl_initial_cpb_removal_offset[SchedSelIdx], respectively, when NalHrdModeFlag is equal to 0, where the buffering period SEI message syntax elements are selected as specified in subclause C.1.

The time at which the first bit of decoding unit m begins to enter the CPB is referred to as the initial arrival time initArrivalTime[m].

If the bitstream-specific CPB operation is used, decoding units are indexed in decoding order within the bitstream. Otherwise (the bitstream-partition-specific CPB operation is used), decoding units are indexed in decoding order with each bitstream partition.

The initial arrival time of decoding unit m is derived as follows:

– If the decoding unit is decoding unit 0 (i.e. m = 0) and either the bitstream-specific CPB operation is used or the decoding unit belongs to the base bitstream partition, initArrivalTime[0] = 0.

– Otherwise, if the decoding unit is decoding unit 0, the bitstream-partition-specific CPB operation is used, and the decoding unit does not belong to the base bitstream partition, initArrivalTime[0] is obtained from the bitstream partition initial arrival time SEI message (present in BitstreamToDecode or available through external means not specified in this Specification) applicable to TargetOp.

– Otherwise, the following applies:

  - If cbr_flag[SchedSelIdx] is equal to 1, the initial arrival time for decoding unit m is equal to the final arrival time (which is derived below) of decoding unit m − 1, i.e.

```
if( !subPicParamsFlag )
    initArrivalTime[ m ] = AuFinalArrivalTime[ m − 1 ]                    (C-4)
else
    initArrivalTime[ m ] = DuFinalArrivalTime[ m − 1 ]
```

  - Otherwise (cbr_flag[SchedSelIdx] is equal to 0), the initial arrival time for decoding unit m is derived as follows:

```
if( !subPicParamsFlag )
    initArrivalTime[ m ] = Max( AuFinalArrivalTime[ m − 1 ], initArrivalEarliestTime[ m ] )    (C-5)
else
    initArrivalTime[ m ] = Max( DuFinalArrivalTime[ m − 1 ], initArrivalEarliestTime[ m ] )
```

    where initArrivalEarliestTime[m] is derived as follows:

    - The variable tmpNominalRemovalTime is derived as follows:

```
if( !subPicParamsFlag )
   tmpNominalRemovalTime = AuNominalRemovalTime[ m ]                    (C-6)
else
   tmpNominalRemovalTime = DuNominalRemovalTime[ m ]
```

where AuNominalRemovalTime[m] and DuNominalRemovalTime[m] are the nominal CPB removal time of access unit m and decoding unit m, respectively, as specified in subclause C.2.3.

– If decoding unit m is not the first decoding unit of a subsequent buffering period, initArrivalEarliestTime[m] is derived as follows:

$$initArrivalEarliestTime[m] = tmpNominalRemovalTime - (InitCpbRemovalDelay[SchedSelIdx] + InitCpbRemovalDelayOffset[SchedSelIdx]) \div 90000 \quad (C\text{-}7)$$

– Otherwise (decoding unit m is the first decoding unit of a subsequent buffering period), initArrivalEarliestTime[m] is derived as follows:

$$initArrivalEarliestTime[m] = tmpNominalRemovalTime - (InitCpbRemovalDelay[SchedSelIdx] \div 90000) \quad (C\text{-}8)$$

The final arrival time for decoding unit m is derived as follows:

```
if( !subPicParamsFlag )
   AuFinalArrivalTime[ m ] = initArrivalTime[ m ] + sizeInbits[ m ] ÷ BitRate[ SchedSelIdx ]   (C-9)
else
   DuFinalArrivalTime[ m ] = initArrivalTime[ m ] + sizeInbits[ m ] ÷ BitRate[ SchedSelIdx ]
```

where sizeInbits[m] is the size in bits of decoding unit m, counting the bits of the VCL NAL units and the filler data NAL units for the Type I conformance point or all bits of the Type II bitstream for the Type II conformance point, where the Type I and Type II conformance points are as shown in Figure C-1.

The values of SchedSelIdx, BitRate[SchedSelIdx], and CpbSize[SchedSelIdx] are constrained as follows:

– If the content of the selected hrd_parameters( ) syntax structures for the access unit containing decoding unit m and the previous access unit differ, the HSS selects a value SchedSelIdx1 of SchedSelIdx from among the values of SchedSelIdx provided in the selected hrd_parameters( ) syntax structures for the access unit containing decoding unit m that results in a BitRate[SchedSelIdx1] or CpbSize[SchedSelIdx1] for the access unit containing decoding unit m. The value of BitRate[SchedSelIdx1] or CpbSize[SchedSelIdx1] may differ from the value of BitRate[SchedSelIdx0] or CpbSize[SchedSelIdx0] for the value SchedSelIdx0 of SchedSelIdx that was in use for the previous access unit.

– Otherwise, the HSS continues to operate with the previous values of SchedSelIdx, BitRate[SchedSelIdx] and CpbSize[SchedSelIdx].

When the HSS selects values of BitRate[SchedSelIdx] or CpbSize[SchedSelIdx] that differ from those of the previous access unit, the following applies:

– The variable BitRate[SchedSelIdx] comes into effect at the initial CPB arrival time of the current access unit.

– The variable CpbSize[SchedSelIdx] comes into effect as follows:

  – If the new value of CpbSize[SchedSelIdx] is greater than the old CPB size, it comes into effect at the initial CPB arrival time of the current access unit.

  – Otherwise, the new value of CpbSize[SchedSelIdx] comes into effect at the CPB removal time of the current access unit.

C.2.3 Timing of decoding unit removal and decoding of decoding unit

The variables InitCpbRemovalDelay[SchedSelIdx], InitCpbRemovalDelayOffset[SchedSelIdx], CpbDelayOffset, and DpbDelayOffset are derived as follows:

– If one or more of the following conditions are true, CpbDelayOffset is set equal to the value of the buffering period SEI message syntax element cpb_delay_offset, DpbDelayOffset is set equal to the value of the buffering period SEI message syntax element dpb_delay_offset, and InitCpbRemovalDelay[SchedSelIdx] and InitCpbRemovalDelayOffset[SchedSelIdx] are set equal to the values of the buffering period SEI message syntax elements nal_initial_alt_cpb_removal_delay[SchedSelIdx] and nal_initial_alt_cpb_removal_offset[SchedSelIdx], respectively, when NalHrdModeFlag is equal to 1, or vcl_initial_alt_cpb_removal_delay[SchedSelIdx] and vcl_initial_alt_cpb_removal_offset[SchedSelIdx], respectively, when NalHrdModeFlag is equal to 0, where the buffering period SEI message containing the syntax elements is selected as specified in subclause C.1:

- Access unit 0 includes a BLA picture with nuh_layer_id equal to 0 and nal_unit_type equal to BLA_W_RADL or BLA_N_LP, MultiLayerCpbOperationFlag is equal to 0 and the value of irap_cpb_params_present_flag of the buffering period SEI message is equal to 1.
- Access unit 0 includes a BLA picture with nuh_layer_id equal to 0 and nal_unit_type equal to BLA_W_LP or includes a CRA picture with nuh_layer_id equal to 0, MultiLayerCpbOperationFlag is equal to 0 and the value of irap_cpb_params_present_flag of the buffering period SEI message is equal to 1, and one or more of the following conditions are true:
  - UseAltCpbParamsFlag for access unit 0 is equal to 1.
  - DefaultInitCpbParamsFlag is equal to 0.
- Access unit 0 includes an IRAP picture with nuh_layer_id equal to 0, MultiLayerCpbOperationFlag is equal to 1 and the value of irap_cpb_params_present_flag of the buffering period SEI message is equal to 1, and one or more of the following conditions are true:
  - UseAltCpbParamsFlag for access unit 0 is equal to 1.
  - DefaultInitCpbParamsFlag is equal to 0.

- Otherwise, InitCpbRemovalDelay[SchedSelIdx] and InitCpbRemovalDelayOffset[SchedSelIdx] are set equal to the values of the buffering period SEI message syntax elements nal_initial_cpb_removal_delay[SchedSelIdx] and nal_initial_cpb_removal_offset[SchedSelIdx], respectively, when NalHrdModeFlag is equal to 1, or vcl_initial_cpb_removal_delay[SchedSelIdx] and vcl_initial_cpb_removal_offset[SchedSelIdx], respectively, when NalHrdModeFlag is equal to 0, where the buffering period SEI message containing the syntax elements is selected as specified in subclause C.1, CpbDelayOffset and DpbDelayOffset are both set equal to 0.

The nominal removal time of the access unit n from the CPB is specified as follows:

- If access unit n is the access unit with n equal to 0 (the access unit that initializes the HRD), the nominal removal time of the access unit from the CPB is specified by:

$$AuNominalRemovalTime[\ 0\ ] = InitCpbRemovalDelay[\ SchedSelIdx\ ] \div 90000 \quad \text{(C-10)}$$

- Otherwise, the following applies:
  - When access unit n is the first access unit of a buffering period that does not initialize the HRD, the following applies:

    The nominal removal time of the access unit n from the CPB is specified by:

```
if( !concatenationFlag ) {
    baseTime = AuNominalRemovalTime[ firstPicInPrevBuffPeriod ]
    tmpCpbRemovalDelay = AuCpbRemovalDelayVal
} else {
    baseTime = AuNominalRemovalTime[ prevNonDiscardablePic ]
    tmpCpbRemovalDelay =
        Max( ( auCpbRemovalDelayDeltaMinus1 + 1 ),                                  (C-11)
            Ceil( ( InitCpbRemovalDelay[ SchedSelIdx ] ÷ 90000 +
                AuFinalArrivalTime[ n − 1 ] − AuNominalRemovalTime[ n − 1 ] ) ÷ ClockTick ) )
}
AuNominalRemovalTime[ n ] = baseTime + ClockTick * ( tmpCpbRemovalDelay − CpbDelayOffset )
```

    where AuNominalRemovalTime[firstPicInPrevBuffPeriod] is the nominal removal time of the first access unit of the previous buffering period, AuNominalRemovalTime[prevNonDiscardablePic] is the nominal removal time of the preceding access unit in decoding order, each picture of which is with TemporalId equal to 0 that is not a RASL, RADL or sub-layer non-reference picture, AuCpbRemovalDelayVal is the value of AuCpbRemovalDelayVal derived according to au_cpb_removal_delay_minus1 in the picture timing SEI message, selected as specified in subclause C.1, associated with access unit n, and concatenationFlag and auCpbRemovalDelayDeltaMinus1 are the values of the syntax elements concatenation_flag and au_cpb_removal_delay_delta_minus1, respectively, in the buffering period SEI message, selected as specified in subclause C.1, associated with access unit n.

    After the derivation of the nominal CPB removal time and before the derivation of the DPB output time of access unit n, the values of CpbDelayOffset and DpbDelayOffset are updated as follows:

    - If one or more of the following conditions are true, CpbDelayOffset is set equal to the value of the buffering period SEI message syntax element cpb_delay_offset, and DpbDelayOffset is set equal to the value of the buffering period SEI message syntax element dpb_delay_offset, where the buffering period SEI message containing the syntax elements is selected as specified in subclause C.1:

- Access unit n includes a BLA picture with nuh_layer_id equal to 0 and nal_unit_type equal to BLA_W_RADL or BLA_N_LP, MultiLayerCpbOperationFlag is equal to 0 and the value of irap_cpb_params_present_flag of the buffering period SEI message is equal to 1.
- Access unit includes a BLA picture with nuh_layer_id equal to 0 and nal_unit_type equal to BLA_W_LP or includes a CRA picture with nuh_layer_id equal to 0, MultiLayerCpbOperationFlag is equal to 0 and the value of irap_cpb_params_present_flag of the buffering period SEI message is equal to 1, and UseAltCpbParamsFlag for access unit n is equal to 1.
- Access unit n includes an IRAP picture with nuh_layer_id equal to 0, MultiLayerCpbOperationFlag is equal to 1, the value of irap_cpb_params_present_flag of the buffering period SEI message is equal to 1, and UseAltCpbParamsFlag for access unit n is equal to 1.

– Otherwise, CpbDelayOffset and DpbDelayOffset are both set equal to 0.

– When access unit n is not the first access unit of a buffering period, the nominal removal time of the access unit n from the CPB is specified by:

$$AuNominalRemovalTime[n] = AuNominalRemovalTime[firstPicInCurrBuffPeriod] + ClockTick * (AuCpbRemovalDelayVal - CpbDelayOffset) \quad \text{(C-12)}$$

where AuNominalRemovalTime[firstPicInCurrBuffPeriod] is the nominal removal time of the first access unit of the current buffering period, and AuCpbRemovalDelayVal is the value of AuCpbRemovalDelayVal derived according to au_cpb_removal_delay_minus1 in the picture timing SEI message, selected as specified in subclause C.1, associated with access unit n.

When SubPicHrdFlag is equal to 1, the following applies:

– The variable duCpbRemovalDelayInc is derived as follows:

- If sub_pic_cpb_params_in_pic_timing_sei_flag is equal to 0, duCpbRemovalDelayInc is set equal to the value of du_spt_cpb_removal_delay_increment in the decoding unit information SEI message, selected as specified in subclause C.1, associated with decoding unit m.
- Otherwise, if du_common_cpb_removal_delay_flag is equal to 0, duCpbRemovalDelayInc is set equal to the value of du_cpb_removal_delay_increment_minus1[i] + 1 for decoding unit m in the picture timing SEI message, selected as specified in subclause C.1, associated with access unit n, where the value of i is 0 for the first num_nalus_in_du_minus1[0] + 1 consecutive NAL units in the access unit that contains decoding unit m, 1 for the subsequent num_nalus_in_du_minus1[1] + 1 NAL units in the same access unit, 2 for the subsequent num_nalus_in_du_minus1[2] + 1 NAL units in the same access unit, etc.
- Otherwise, duCpbRemovalDelayInc is set equal to the value of du_common_cpb_removal_delay_increment_minus1 + 1 in the picture timing SEI message, selected as specified in subclause C.1, associated with access unit n.

– The nominal removal time of decoding unit m from the CPB is specified as follows, where AuNominalRemovalTime[n] is the nominal removal time of access unit n:

- If decoding unit m is the last decoding unit in access unit n, the nominal removal time of decoding unit m DuNominalRemovalTime[m] is set equal to AuNominalRemovalTime[n].
- Otherwise (decoding unit m is not the last decoding unit in access unit n), the nominal removal time of decoding unit m DuNominalRemovalTime[m] is derived as follows:

```
if( sub_pic_cpb_params_in_pic_timing_sei_flag )
    DuNominalRemovalTime[ m ] = DuNominalRemovalTime[ m + 1 ] −
        ClockSubTick * duCpbRemovalDelayInc                                  (C-13)
else
    DuNominalRemovalTime[ m ] = AuNominalRemovalTime[ n ] −
        ClockSubTick * duCpbRemovalDelayInc
```

If SubPicHrdFlag is equal to 0, the removal time of access unit n from the CPB is specified as follows, where AuFinalArrivalTime[n] and AuNominalRemovalTime[n] are the final CPB arrival time and nominal CPB removal time, respectively, of access unit n:

```
if( !low_delay_hrd_flag[ HighestTid ] || AuNominalRemovalTime[ n ] >= AuFinalArrivalTime[ n ] )
    AuCpbRemovalTime[ n ] = AuNominalRemovalTime[ n ]
else                                                                         (C-14)
    AuCpbRemovalTime[ n ] = AuNominalRemovalTime[ n ] + ClockTick *
        Ceil( ( AuFinalArrivalTime[ n ] − AuNominalRemovalTime[ n ] ) ÷ ClockTick )
```

NOTE 1 – When low_delay_hrd_flag[HighestTid] is equal to 1 and AuNominalRemovalTime[n] is less than AuFinalArrivalTime[n], the size of access unit n is so large that it prevents removal at the nominal removal time.

Otherwise (SubPicHrdFlag is equal to 1), the removal time of decoding unit m from the CPB is specified as follows:

– When the bitstream-specific CPB operation is used or when the current DU belongs to the base bitstream partition, the following applies:

```
if( !low_delay_hrd_flag[ HighestTid ] || DuNominalRemovalTime[ m ] >= DuFinalArrivalTime[ m ] )
    DuCpbRemovalTime[ m ] = DuNominalRemovalTime[ m ]
else                                                                                    (C-15)
    DuCpbRemovalTime[ m ] = DuFinalArrivalTime[ m ]
```

NOTE 2 – When low_delay_hrd_flag[HighestTid] is equal to 1 and DuNominalRemovalTime[m] is less than DuFinalArrivalTime[m], the size of decoding unit m is so large that it prevents removal at the nominal removal time.

– When the bitstream-partition-specific CPB operation is used and cbr_flag[SchedSelIdx] is equal to 0, the following applies:

  – Let refDuCpbRemovalTime be equal to the CPB removal time of the previous DU preceding the current DU in decoding order (regardless of the bitstream partitions to which the previous DU and the current DU belong).

  – The variable DuCpbRemovalTime[m] is modified as follows:

```
DuCpbRemovalTime[ m ] = Max( DuCpbRemovalTime[ m ], refDuCpbRemovalTime )                (C-16)
```

If SubPicHrdFlag is equal to 0, at the CPB removal time of access unit n, the access unit is instantaneously decoded.

Otherwise (SubPicHrdFlag is equal to 1), at the CPB removal time of decoding unit m, the decoding unit is instantaneously decoded, and when decoding unit m is the last decoding unit of access unit n, the following applies:

– Access unit n is considered as decoded.

– The final CPB arrival time of access unit n, i.e. AuFinalArrivalTime[n], is set equal to the final CPB arrival time of the last decoding unit in access unit n, i.e. DuFinalArrivalTime[m].

– The nominal CPB removal time of access unit n, i.e. AuNominalRemovalTime[n], is set equal to the nominal CPB removal time of the last decoding unit in access unit n, i.e. DuNominalRemovalTime[m].

– The CPB removal time of access unit n, i.e. AuCpbRemovalTime[m], is set equal to the CPB removal time of the last decoding unit in access unit n, i.e. DuCpbRemovalTime[m].

C.3 Operation of the decoded picture buffer (DPB)

C.3.1 General

The specifications in this subclause apply independently to each set of DPB parameters selected as specified in subclause C.1.

The decoded picture buffer consists of sub-DPBs, and each sub-DPB contains picture storage buffers for storage of decoded pictures of one layer. Each of the picture storage buffers of a sub-DPB may contain a decoded picture that is marked as "used for reference" or is held for future output.

The following applies for all decoded access units:

– If AltOptLayerFlag[TargetOlsIdx] is equal to 1 and an access unit either does not contain a picture at the output layer or contains a picture at the output layer that has PicOutputFlag equal to 0, the following ordered steps apply:

  – The list nonOutputLayerPictures is the list of the pictures of the access unit with PicOutputFlag equal to 1 and with nuh_layer_id values among the nuh_layer_id values of the direct and indirect reference layers of the output layer.

  – The picture with the highest nuh_layer_id value among the list nonOutputLayerPictures is removed from the list nonOutputLayerPictures.

  – PicOutputFlag for each picture that is included in the list nonOutputLayerPictures is set equal to 0.

– Otherwise, PicOutputFlag for pictures that are not included in an output layer is set equal to 0.

The processes specified in subclauses C.3.2, C.3.3 and C.3.4 are sequentially applied as specified below, and are applied independently for each layer, starting from the base layer, in increasing order of nuh_layer_id values of the layers in the bitstream. When these processes are applied for a particular layer, only the sub-DPB for the particular layer is affected.

In the descriptions of these processes, the DPB refers to the sub-DPB for the particular layer, and the particular layer is referred to as the current layer.

NOTE – In the operation of output timing DPB, decoded pictures with PicOutputFlag equal to 1 in the same access unit are output consecutively in ascending order of the nuh_layer_id values of the decoded pictures.

Let picture n and the current picture be the coded picture or decoded picture of the access unit n for a particular value of nuh_layer_id, wherein n is a non-negative integer number. [Ed. (CY&YK): This probably is not a good definition of picture n especially if each picture is a DU. It is a temporary term defined only for DPB operations, further improvements are needed.]

C.3.2 Removal of pictures from the DPB

When the current picture is not picture 0 in the current layer, the removal of pictures in the current layer, with nuh_layer_id equal to currLayerId, from the DPB before decoding of the current picture, i.e. picture n, but after parsing the slice header of the first slice of the current picture, happens instantaneously at the CPB removal time of the first decoding unit of the current picture and proceeds as follows:

– The decoding process for RPS as specified in subclause 8.3.1 is invoked.

– The variable crossLayerBufferEmptyFlag is derived as follows:

  – If a new VPS is activated by the current access unit or the current picture is an IRAP picture with nuh_layer_id equal to 0, NoRaslOutputFlag equal to 1, and NoClrasOutputFlag equal to 1, crossLayerBufferEmptyFlag is set equal to 1.

  – Otherwise, crossLayerBufferEmptyFlag is set equal to 0.

– When the current picture is an IRAP picture with NoRaslOutputFlag equal to 1 and nuh_layer_id equal to 0, the following ordered steps are applied:

  1. The variable NoOutputOfPriorPicsFlag is derived for the decoder under test as follows:

     – If the current picture is a CRA picture, NoOutputOfPriorPicsFlag is set equal to 1 (regardless of the value of no_output_of_prior_pics_flag).

     – Otherwise, if the value of pic_width_in_luma_samples, pic_height_in_luma_samples, chroma_format_idc, bit_depth_luma_minus8, bit_depth_chroma_minus8, separate_colour_plane_flag, or sps_max_dec_pic_buffering_minus1[HighestTid] derived from the active SPS for the current layer is different from the value of pic_width_in_luma_samples, pic_height_in_luma_samples, chroma_format_idc, bit_depth_luma_minus8, bit_depth_chroma_minus8, separate_colour_plane_flag, or sps_max_dec_pic_buffering_minus1[HighestTid], respectively, derived from the SPS that was active for the current layer when decoding the preceding picture in the current layer, NoOutputOfPriorPicsFlag may (but should not) be set equal to 1 by the decoder under test, regardless of the value of no_output_of_prior_pics_flag.

       NOTE – Although setting NoOutputOfPriorPicsFlag equal to no_output_of_prior_pics_flag is preferred under these conditions, the decoder under test is allowed to set NoOutputOfPriorPicsFlag to 1 in this case.

     – Otherwise, NoOutputOfPriorPicsFlag is set equal to no_output_of_prior_pics_flag.

  2. When the value of NoOutputOfPriorPicsFlag derived for the decoder under test is equal to 1, the following applies for the HRD:

     – If the value of crossLayerBufferEmptyFlag is equal to 1, all non-empty picture storage buffers in all the sub-DPBs are emptied without output of the pictures they contain, and the sub-DPB fullness of each sub-DPB is set equal to 0.

     – Otherwise (the value of crossLayerBufferEmptyFlag is equal to 0), all non-empty picture storage buffers that contain pictures with nuh_layer_id equal to 0 are emptied without output of the pictures they contain, and the sub-DPB fullness of the sub-DPB associated with nuh_layer_id equal to 0 is decremented by the number of picture storage buffers that were emptied.

– When both of the following conditions are true for any pictures k in the DPB, all such pictures k in the DPB are removed from the DPB:

  – picture k is marked as "unused for reference"

  – picture k has PicOutputFlag equal to 0 or its DPB output time is less than or equal to the CPB removal time of the first decoding unit (denoted as decoding unit m) of the current picture n; i.e. DpbOutputTime[k] is less than or equal to CpbRemovalTime(m)

– For each picture that is removed from the DPB, the DPB fullness is decremented by one.

C.3.3 Picture output

The processes specified in this subclause happen instantaneously at the CPB removal time of access unit n, AuCpbRemovalTime[n].

When picture n has PicOutputFlag equal to 1, its DPB output time DpbOutputTime[n] is derived as follows, where the variable firstPicInBufferingPeriodFlag is equal to 1 if access unit n is the first access unit of a buffering period and 0 otherwise:

```
if( !SubPicHrdFlag ) {
    DpbOutputTime[ n ] = AuCpbRemovalTime[ n ] + ClockTick * picDpbOutputDelay                (C-17)
    if( firstPicInBufferingPeriodFlag )
        DpbOutputTime[ n ]  −=  ClockTick * DpbDelayOffset
} else
    DpbOutputTime[ n ] = AuCpbRemovalTime[ n ] + ClockSubTick * picSptDpbOutputDuDelay
```

where picDpbOutputDelay is the value of pic_dpb_output_delay in the picture timing SEI message associated with access unit n, and picSptDpbOutputDuDelay is the value of pic_spt_dpb_output_du_delay, when present, in the decoding unit information SEI messages associated with access unit n, or the value of pic_dpb_output_du_delay in the picture timing SEI message associated with access unit n when there is no decoding unit information SEI message associated with access unit n or no decoding unit information SEI message associated with access unit n has pic_spt_dpb_output_du_delay present.

NOTE – When the syntax element pic_spt_dpb_output_du_delay is not present in any decoding unit information SEI message associated with access unit n, the value is inferred to be equal to pic_dpb_output_du_delay in the picture timing SEI message associated with access unit n.

The output of the current picture is specified as follows:

– If PicOutputFlag is equal to 1 and DpbOutputTime[n] is equal to AuCpbRemovalTime[n], the current picture is output.

– Otherwise, if PicOutputFlag is equal to 0, the current picture is not output, but will be stored in the DPB as specified in subclause C.3.4.

– Otherwise (PicOutputFlag is equal to 1 and DpbOutputTime[n] is greater than AuCpbRemovalTime[n]), the current picture is output later and will be stored in the DPB (as specified in subclause C.3.4) and is output at time DpbOutputTime[n] unless indicated not to be output by the decoding or inference of no_output_of_prior_pics_flag equal to 1 at a time that precedes DpbOutputTime[n].

When output, the picture is cropped, using the conformance cropping window specified in the active SPS for the layer containing the picture.

When picture n is a picture that is output and is not the last picture of the bitstream that is output, the value of the variable DpbOutputInterval[n] is derived as follows:

```
DpbOutputInterval[ n ] = DpbOutputTime[ nextPicInOutputOrder ] − DpbOutputTime[ n ]          (C-18)
```

where nextPicInOutputOrder is the picture that follows picture n in output order and has PicOutputFlag equal to 1.

C.3.4 Current decoded picture marking and storage

The process specified in this subclause happens instantaneously at the CPB removal time of the last decoding unit of the current picture. [Ed. (MH): This change might not comply with version 1, because version 1 decoders would mark and store the base-layer picture at the CPB removal time of the AU, which can be later than the CPB removal time of the base-layer picture.]

The current decoded picture is stored in the DPB in an empty picture storage buffer, the DPB fullness is incremented by one, and the current picture is marked as "used for short-term reference".

C.4 Bitstream conformance

A bitstream of coded data conforming to this Specification shall fulfil all requirements specified in this subclause.

The bitstream shall be constructed according to the syntax, semantics, and constraints specified in this Specification outside of this annex.

The first access unit in a bitstream shall be an IRAP access unit.

The bitstream is tested by the HRD for conformance as specified in subclause C.1.

When vps_base_layer_internal_flag is equal to 0, all the following bitstream conformance constraints apply without considering pictures with nuh_layer_id equal to 0, for which there is no coded picture in the bitstream and the decoded pictures are provided by external means. [Ed. (YK): Check for possible wording improvements.] Ed. (JB): How about this?: When vps_base_layer_internal_flag is equal to 0, all the following bitstream conformance constraints apply only to coded pictures present in the bitstream, and do not apply to pictures with nuh_layer_id equal to 0 which are provided by external means.]

Let currPicLayerId be equal to the nuh_layer_id of the current picture.

For each current picture, let the variables maxPicOrderCnt and minPicOrderCnt be set equal to the maximum and the minimum, respectively, of the PicOrderCntVal values of the following pictures with nuh_layer_id equal to currPicLayerId:

– The current picture.

– The previous picture in decoding order that has TemporalId equal to 0 and that is not a RASL picture, a RADL picture, or a sub-layer non-reference picture.

– The short-term reference pictures in the RPS of the current picture.

– All pictures n that have PicOutputFlag equal to 1, AuCpbRemovalTime[n] less than AuCpbRemovalTime[currPic], and DpbOutputTime[n] greater than or equal to AuCpbRemovalTime[currPic], where currPic is the current picture. [Ed. (CY): clarify the AuCpbRemovalTime of a picture to be that of the containing AU.]

All of the following conditions shall be fulfilled for each of the bitstream conformance tests:

1. For each access unit n, with n greater than 0, associated with a buffering period SEI message, let the variable deltaTime90k[n] be specified as follows:

   deltaTime90k[n] = 90000 * (AuNominalRemovalTime[n] − AuFinalArrivalTime[n − 1]) (C-19)

   The value of InitCpbRemovalDelay[SchedSelIdx] is constrained as follows:

   – If cbr_flag[SchedSelIdx] is equal to 0, the following condition shall be true:

     InitCpbRemovalDelay[SchedSelIdx] <= Ceil(deltaTime90k[n]) (C-20)

   – Otherwise (cbr_flag[SchedSelIdx] is equal to 1), the following condition shall be true:

     Floor(deltaTime90k[n]) <= InitCpbRemovalDelay[SchedSelIdx] <= Ceil(deltaTime90k[n]) (C-21)

     NOTE 1 – The exact number of bits in the CPB at the removal time of each picture may depend on which buffering period SEI message is selected to initialize the HRD. Encoders must take this into account to ensure that all specified constraints must be obeyed regardless of which buffering period SEI message is selected to initialize the HRD, as the HRD may be initialized at any one of the buffering period SEI messages.

2. A CPB overflow is specified as the condition in which the total number of bits in the CPB is greater than the CPB size. The CPB shall never overflow.

3. A CPB underflow is specified as the condition in which the nominal CPB removal time of decoding unit m DuNominalRemovalTime(m) is less than the final CPB arrival time of decoding unit m DuFinalArrivalTime(m) for at least one value of m. When low_delay_hrd_flag[HighestTid] is equal to 0, the CPB shall never underflow.

4. When SubPicHrdFlag is equal to 1, low_delay_hrd_flag[HighestTid] is equal to 1, and the nominal removal time of a decoding unit m of access unit n is less than the final CPB arrival time of decoding unit m (i.e. DuNominalRemovalTime[m] < DuFinalArrivalTime[m]), the nominal removal time of access unit n shall be less than the final CPB arrival time of access unit n (i.e. AuNominalRemovalTime[n] < AuFinalArrivalTime[n]).

5. When the bitstream-partition-specific CPB operation is used and cbr_flag[SchedSelIdx] is equal to 1, DuCpbRemovalTime[m] shall be greater than or equal to the CPB removal time of the previous DU preceding the current DU in decoding order (regardless of the bitstream partitions to which the previous DU and the current DU belong) for any decoding unit m in bitstream partitions with index greater than 0.

6. The nominal removal times of access units from the CPB (starting from the second access unit in decoding order) shall satisfy the constraints on AuNominalRemovalTime[n] and AuCpbRemovalTime[n] expressed in subclauses A.4.1 through A.4.2.

7. For each current picture, after invocation of the process for removal of pictures from the sub-DPB as specified in subclause C.3.2, the number of decoded pictures in the sub-DPB for the current layer, including all pictures n in the current layer that are marked as "used for reference", or that have PicOutputFlag equal to 1 and

AuCpbRemovalTime[n] less than AuCpbRemovalTime[currPic], where currPic is the current picture, shall be less than or equal to max_vps_dec_pic_buffering_minus1[TargetOlsIdx][layerIdx][HighestTid], where layerIdx is equal to the value such that LayerSetLayerIdList[TargetDecLayerSetIdx][layerIdx] is equal to currPicLayerId.

8. All reference pictures shall be present in the DPB when needed for prediction. Each picture that has PicOutputFlag equal to 1 shall be present in the DPB at its DPB output time unless it is removed from the DPB before its output time by one of the processes specified in subclause C.3.

9. For each current picture, the value of maxPicOrderCnt − minPicOrderCnt shall be less than MaxPicOrderCntLsb / 2.

10. The value of DpbOutputInterval[n] as given by Equation C-18, which is the difference between the output time of an access unit and that of the first access unit following it in output order and having PicOutputFlag equal to 1, shall satisfy the constraint expressed in subclause A.4.1 for the profile, tier and level specified in the bitstream using the decoding process specified in clauses 2 through 10. [Ed. (MH): This constraint has to be updated, since 1) it assumes a single profile-tier-level combination for a bitstream (as if the bitstream were a single-layer bitstream), and 2) it refers to the decoding process in clauses 2 to 10 (while now also the decoding process of extensions should somehow be referred to).]

11. For each current picture, when sub_pic_cpb_params_in_pic_timing_sei_flag is equal to 1, let tmpCpbRemovalDelaySum be derived as follows:

```
tmpCpbRemovalDelaySum = 0
for( i = 0; i < num_decoding_units_minus1; i++ )                    (C-22)
    tmpCpbRemovalDelaySum  +=  du_cpb_removal_delay_increment_minus1[ i ] + 1
```

The value of ClockSubTick * tmpCpbRemovalDelaySum shall be equal to the difference between the nominal CPB removal time of the current access unit and the nominal CPB removal time of the first decoding unit in the current access unit in decoding order.

12. For any two pictures m and n in the same CVS, when DpbOutputTime[m] is greater than DpbOutputTime[n], the PicOrderCntVal of picture m shall be greater than the PicOrderCntVal of picture n.

NOTE 2 – All pictures of an earlier CVS in decoding order that are output are output before any pictures of a later CVS in decoding order. Within any particular CVS, the pictures that are output are output in increasing PicOrderCntVal order.

C.5 Decoder conformance

C.5.1 General

A decoder conforming to this Specification shall fulfil all requirements specified in this subclause.

A decoder claiming conformance to a specific profile, tier and level shall be able to successfully decode all bitstreams that conform to the bitstream conformance requirements specified in subclause C.4, in the manner specified in Annex A, provided that all VPSs, SPSs and PPSs referred to by the VCL NAL units, appropriate buffering period, picture timing, and decoder unit information SEI messages are conveyed to the decoder, in a timely manner, either in the bitstream (by non-VCL NAL units), or by external means not specified in this Specification, and, when vps_base_layer_internal_flag is equal to 0, the decoded pictures with nuh_layer_id equal to 0 and their properties as specified in subclause F.8.1 are conveyed to the decoder in a timely manner by external means not specified in this Specification.

When a bitstream contains syntax elements that have values that are specified as reserved and it is specified that decoders shall ignore values of the syntax elements or NAL units containing the syntax elements having the reserved values, and the bitstream is otherwise conforming to this Specification, a conforming decoder shall decode the bitstream in the same manner as it would decode a conforming bitstream and shall ignore the syntax elements or the NAL units containing the syntax elements having the reserved values as specified.

There are two types of conformance that can be claimed by a decoder: output timing conformance and output order conformance.

To check conformance of a decoder, test bitstreams conforming to the claimed profile, tier and level, as specified in subclause C.4 are delivered by a hypothetical stream scheduler (HSS) both to the HRD and to the decoder under test (DUT). When vps_base_layer_internal_flag is equal to 0, decoded pictures with nuh_layer_id equal to 0 and their properties as specified in subclause F.8.1 are also conveyed both to the HRD and to the DUT in a timely manner by external means not specified in this Specification. All cropped decoded pictures output by the HRD shall also be output by the DUT, each cropped decoded picture output by the DUT shall be a picture with PicOutputFlag equal to 1, and, for each such cropped decoded picture output by the DUT, the values of all samples that are output shall be equal to the values of the samples produced by the specified decoding process. The flag BaseLayerOutputFlag and all flags

BaseLayerPicOutputFlag output by the HRD shall also be output by the DUT, and the values that are output shall be equal to the values produced by the specified decoding process.

For output timing decoder conformance, the HSS operates as described above, with delivery schedules selected only from the subset of values of SchedSelIdx for which the bit rate and CPB size are restricted as specified in Annex A for the specified profile, tier and level, or with "interpolated" delivery schedules as specified below for which the bit rate and CPB size are restricted as specified in Annex A. The same delivery schedule is used for both the HRD and the DUT.

When the HRD parameters and the buffering period SEI messages are present with cpb_cnt_minus1[HighestTid] greater than 0, the decoder shall be capable of decoding the bitstream as delivered from the HSS operating using an "interpolated" delivery schedule specified as having peak bit rate r, CPB size c(r), and initial CPB removal delay (f(r) ÷ r) as follows:

$$\alpha = (r - BitRate[SchedSelIdx - 1]) \div (BitRate[SchedSelIdx] - BitRate[SchedSelIdx - 1]), \quad \text{(C-23)}$$

$$c(r) = \alpha * CpbSize[SchedSelIdx] + (1 - \alpha) * CpbSize[SchedSelIdx - 1], \quad \text{(C-24)}$$

$$f(r) = \alpha * InitCpbRemovalDelay[SchedSelIdx] * BitRate[SchedSelIdx] + (1 - \alpha) * InitCpbRemovalDelay[SchedSelIdx - 1] * BitRate[SchedSelIdx - 1] \quad \text{(C-25)}$$

for any SchedSelIdx > 0 and r such that BitRate[SchedSelIdx − 1] <= r <= BitRate[SchedSelIdx] such that r and c(r) are within the limits as specified in Annex A for the maximum bit rate and buffer size for the specified profile, tier and level.

NOTE 1 – InitCpbRemovalDelay[SchedSelIdx] can be different from one buffering period to another and need to be recalculated.

For output timing decoder conformance, an HRD as described above is used and the timing (relative to the delivery time of the first bit) of picture output is the same for both the HRD and the DUT up to a fixed delay.

For output order decoder conformance, the following applies:

– The HSS delivers the bitstream BitstreamToDecode to the DUT "by demand" from the DUT, meaning that the HSS delivers bits (in decoding order) only when the DUT requires more bits to proceed with its processing.

  NOTE 2 – This means that for this test, the coded picture buffer of the DUT could be as small as the size of the largest decoding unit.

– A modified HRD as described below is used, and the HSS delivers the bitstream to the HRD by one of the schedules specified in the bitstream BitstreamToDecode such that the bit rate and CPB size are restricted as specified in Annex A. The order of pictures output shall be the same for both the HRD and the DUT.

– The HRD CPB size is given by CpbSize[SchedSelIdx] as specified in subclause E.3.3, where SchedSelIdx and the HRD parameters are selected as specified in subclause C.1. The DPB size is given by sps_max_dec_pic_buffering_minus1[HighestTid] + 1. Removal time from the CPB for the HRD is the final bit arrival time and decoding is immediate. The operation of the DPB of this HRD is as described in subclauses C.5.2 through C.5.2.3.

C.5.2 Operation of the output order DPB

C.5.2.1 General

The decoded picture buffer consists of sub-DPBs, and each sub-DPB contains picture storage buffers for storage of decoded pictures of one layer. Each of the picture storage buffers of a sub-DPB contains a decoded picture that is marked as "used for reference" or is held for future output.

The process for output and removal of pictures from the DPB as specified in subclause C.5.2.2 is invoked, followed by the invocation of the process for picture decoding, marking, additional bumping, and storage as specified in subclause C.5.2.3. The "bumping" process is specified in subclause C.5.2.4 and is invoked as specified in subclauses C.5.2.2 and C.5.2.3.

These processes are applied independently for each layer, starting from the base layer, in increasing order of the nuh_layer_id values of the layers in the bitstream. When these processes are applied for a particular layer, only the sub-DPB for the particular layer is affected except for the "bumping" process, which may crop and output pictures, mark pictures as "not needed for output" and empty picture storage buffers for any layer.

NOTE – In the operation of output order DPB, same as in the operation of output timing DPB, decoded pictures with PicOutputFlag equal to 1 in the same access unit are also output consecutively in ascending order of the nuh_layer_id values of the decoded pictures.

Let picture n and the current picture be the coded picture or decoded picture of the access unit n for a particular value of nuh_layer_id, wherein n is a non-negative integer number.

When these processes are applied for a layer with nuh_layer_id equal to currLayerId, the variables MaxNumReorderPics, MaxLatencyIncreasePlus1, CurrLayerMaxLatencyPictures, and MaxDecPicBufferingMinus1 are derived as follows:

– MaxNumReorderPics is set equal to max_vps_num_reorder_pics[TargetOlsIdx][HighestTid] of the active VPS.

– MaxLatencyIncreasePlus1 is set equal to the value of the syntax element max_vps_latency_increase_plus1[TargetOlsIdx][HighestTid] of the active VPS.

– CurrLayerMaxLatencyPictures is set equal to VpsMaxLatencyPictures[TargetOlsIdx][HighestTid] of the active VPS.

– MaxDecPicBufferingMinus1 is set equal to the value of the syntax element max_vps_dec_pic_buffering_minus1[TargetOlsIdx][layerIdx][HighestTid] of the active VPS, where layerIdx is equal to the value such that LayerSetLayerIdList[TargetDecLayerSetIdx][layerIdx] is equal to currLayerId.

C.5.2.2 Output and removal of pictures from the DPB

When the current picture is not picture 0 in the current layer, the output and removal of pictures in the current layer, with nuh_layer_id equal to currLayerId, from the DPB before the decoding of the current picture , i.e. picture n, but after parsing the slice header of the first slice of the current picture and before the invocation of the decoding process for picture order count, happens instantaneously when the first decoding unit of the current picture is removed from the CPB and proceeds as follows:

– When the current picture is a POC resetting picture, all pictures in the DPB that do not belong to the current access unit and that are marked as "needed for output" are output, starting with pictures with the smallest value of PicOrderCntVal of all pictures excluding those in the current access unit in the DPB, in ascending order of the PicOrderCntVal values, and pictures with the same value of PicOrderCntVal are output in ascending order of the nuh_layer_id values. When a picture is output, it is cropped using the conformance cropping window specified in the active SPS for the picture, the cropped picture is output, and the picture is marked as "not needed for output".

– The decoding processes for picture order count and RPS are invoked. When decoding a CVS conforming to one or more of the profiles specified in Annex A using the decoding process specified in clauses 2 through 10, the decoding processes for picture order count and RPS that are invoked are as specified in subclauses 8.3.1and 8.3.2, respectively. When decoding a CVS conforming to one or more of the profiles specified in Annex G or H using the decoding process specified in Annex F, and Annex G or H, the decoding processes for picture order count and RPS that are invoked are as specified in subclauses F.8.3.1 and F.8.3.2, respectively.

– The variable crossLayerBufferEmptyFlag is derived as follows:

  – If a new VPS is activated by the current access unit or the current picture is IRAP picture with nuh_layer_id equal to 0, NoRaslOutputFlag equal to 1, and NoClrasOutputFlag equal to 1, crossLayerBufferEmptyFlag is set equal to 1.

  – Otherwise, crossLayerBufferEmptyFlag is set equal to 0.

– If the current picture is an IRAP picture with NoRaslOutputFlag equal to 1 and nuh_layer_id equal to 0, the following ordered steps are applied:

  1. The variable NoOutputOfPriorPicsFlag is derived for the decoder under test as follows:

     – If the current picture is a CRA picture, NoOutputOfPriorPicsFlag is set equal to 1 (regardless of the value of no_output_of_prior_pics_flag).

     – Otherwise, if the value of pic_width_in_luma_samples, pic_height_in_luma_samples, chroma_format_idc, bit_depth_luma_minus8, bit_depth_chroma_minus8, separate_colour_plane_flag, or sps_max_dec_pic_buffering_minus1[HighestTid] derived from the active SPS for the current layer is different from the value of pic_width_in_luma_samples, pic_height_in_luma_samples, chroma_format_idc, bit_depth_luma_minus8, bit_depth_chroma_minus8, separate_colour_plane_flag, or sps_max_dec_pic_buffering_minus1[HighestTid], respectively, derived from the SPS that was active for the current layer when decoding the preceding picture in the current layer, NoOutputOfPriorPicsFlag may (but should not) be set equal to 1 by the decoder under test, regardless of the value of no_output_of_prior_pics_flag.

       NOTE – Although setting NoOutputOfPriorPicsFlag equal to no_output_of_prior_pics_flag is preferred under these conditions, the decoder under test is allowed to set NoOutputOfPriorPicsFlag to 1 in this case.

     – Otherwise, NoOutputOfPriorPicsFlag is set equal to no_output_of_prior_pics_flag.

  2. The value of NoOutputOfPriorPicsFlag derived for the decoder under test is applied for the HRD as follows:

- If NoOutputOfPriorPicsFlag is equal to 0, all non-empty picture storage buffers in all the sub-DPBs are output by repeatedly invoking the "bumping" process specified in subclause C.5.2.4 until all these pictures are marked as "not needed for output".
- Otherwise if crossLayerBufferEmptyFlag is equal to 1, all picture storage buffers in all the sub-DPBs are emptied, and the sub-DPB fullness of all the sub-DPBs is set equal to 0.
- Otherwise (crossLayerBufferEmptyFlag is equal to 0), all picture storage buffers containing a picture that is marked as "not needed for output" and "unused for reference" are emptied (without output), all pictures that have nuh_layer_id equal to 0 in the sub-DPB containing the layer with nuh_layer_id equal to 0 are emptied, and the sub-DPB fullness of each sub-DPB is decremented by the number of picture storage buffers emptied in that sub-DPB.

– Otherwise, all picture storage buffers that contain a picture in the current layer and that are marked as "not needed for output" and "unused for reference" are emptied (without output). For each picture storage buffer that is emptied, the sub-DPB fullness is decremented by one. When one or more of the following conditions are true, the "bumping" process specified in subclause C.5.2.4 is invoked repeatedly until none of the following conditions are true:
  - The number of access units that contain at least one decoded picture in the DPB marked as "needed for output" is greater than MaxNumReorderPics.
  - MaxLatencyIncreasePlus1 is not equal to 0 and there is at least one access unit that contains at least one decoded picture in the DPB marked as "needed for output" for which the associated variable PicLatencyCount is greater than or equal to CurrLayerMaxLatencyPictures.
  - The number of pictures in the sub-DPB is greater than or equal to MaxDecPicBufferingMinus1 + 1.

C.5.2.3 Picture decoding, marking, additional bumping, and storage

The processes specified in this subclause happen instantaneously when the last decoding unit of picture n is removed from the CPB. [Ed. (MH): This change might not comply with version 1, because version 1 decoders would mark and store the base-layer picture at the CPB removal time of the AU, which can be later than the CPB removal time of the base-layer picture.]

PicOutputFlag is updated as follows:

– If AltOptLayerFlag[TargetOlsIdx] is equal to 1 and the current access unit either does not contain a picture at the output layer or contains a picture at the output layer that has PicOutputFlag equal to 0, the following ordered steps apply:
  - The list nonOutputLayerPictures is the list of the pictures of the access unit with PicOutputFlag equal to 1 and with nuh_layer_id values among the nuh_layer_id values of the direct and indirect reference layers of the output layer.
  - The picture with the highest nuh_layer_id value among the list nonOutputLayerPictures is removed from the list nonOutputLayerPictures.
  - PicOutputFlag for each picture that is included in the list nonOutputLayerPictures is set equal to 0.
– Otherwise, PicOutputFlag for pictures that are not included in an output layer is set equal to 0.

When the current picture has PicOutputFlag equal to 1, for each picture in the current layer in the sub-DPB that is marked as "needed for output" and follows the current picture in output order, the associated variable PicLatencyCount is set equal to PicLatencyCount + 1.

The current picture is considered as decoded after the last decoding unit of the picture is decoded. The current decoded picture is stored in an empty picture storage buffer in the sub-DPB, and the following applies:

– If the current decoded picture has PicOutputFlag equal to 1, it is marked as "needed for output" and its associated variable PicLatencyCount is set equal to 0.
– Otherwise (the current decoded picture has PicOutputFlag equal to 0), it is marked as "not needed for output".

The current decoded picture is marked as "used for short-term reference".

When one or more of the following conditions are true, the "bumping" process specified in subclause C.5.2.4 is invoked repeatedly until none of the following conditions are true:

– The number of access units that contain at least one decoded picture in the DPB marked as "needed for output" is greater than MaxNumReorderPics.

– MaxLatencyIncreasePlus1 is not equal to 0 and there is at least one access unit that contains at least one decoded picture in the DPB marked as "needed for output" for which the associated variable PicLatencyCount is greater than or equal to CurrLayerMaxLatencyPictures.

C.5.2.4 "Bumping" process

The "bumping" process consists of the following ordered steps:

1. The picture or pictures that are first for output are selected as the ones having the smallest value of PicOrderCntVal of all pictures in the DPB marked as "needed for output".
2. Each of these pictures is, in ascending nuh_layer_id order, cropped, using the conformance cropping window specified in the active SPS for the picture, the cropped picture is output, and the picture is marked as "not needed for output".
3. Each picture storage buffer that contains a picture marked as "unused for reference" and that was one of the pictures cropped and output is emptied and the fullness of the associated sub-DPB is decremented by one.

C.6 Demultiplexing process for deriving a bitstream partition

Inputs to this process are a bitstream, a layer identifier list bspLayerId[bspIdx] and the number of layer identifiers numBspLayerId in the layer index list bspLayerId[bspIdx].

Output of this process is a bitstream partition.

Let variable minBspLayerId be the smallest value of bspLayerId[bspIdx] with any value of bspIdx in the range of 0 to numBspLayerId − 1, inclusive.

The output bitstream partition consists of selected NAL units of the input bitstream in the same order as they appear in the input bitstream. The following NAL units of the input bitstream are omitted from the output bitstream partition, while the remaining NAL units of the input bitstream are included in the output bitstream partition:

– Omit all NAL units that have a nuh_layer_id value other than bspLayerId[bspIdx] with any value of bspIdx in the range of 0 to numBspLayerId − 1, inclusive.

– Omit all SEI NAL units containing a scalable nesting SEI message for which no derived nestingLayerIdList[i] contains any layer identifier value equal to bspLayerId[bspIdx] with any value of bspIdx in the range of 0 to numBspLayerId − 1, inclusive.

– Omit all SEI NAL units containing a scalable nesting SEI message for which a derived nestingLayerIdList[i] contains a layer identifier value less than minBspLayerId.

Modify Annex D as follows:

Annex D

Supplemental enhancement information

(This annex forms an integral part of this Recommendation | International Standard)

Modify subclause D.2.1 as follows:

Add rows enclosed by "...".

sei_payload(payloadType, payloadSize) {	**Descriptor**
if(nal_unit_type = = PREFIX_SEI_NUT)	
if(payloadType = = 0)	
...	
else if(payloadType = = XXX)	
layers_not_present(payloadSize)	
else if(payloadType = = XXX)	
inter_layer_constrained_tile_sets(payloadSize)	
else if(payloadType = = XXX)	
bsp_nesting(payloadSize)	
else if(payloadType = = XXX)	
bsp_initial_arrival_time(payloadSize)	
else if(payloadType = = XXX)	
bsp_hrd(payloadSize)	
else if(payloadType = = XXX)	
sub_bitstream_property(payloadSize)	
else if(payloadType = = XXX)	
three_dimensional_reference_displays_info(payloadSize)	
else if(payloadType = = XXX)	
depth_representation_info_sei(payloadSize)	
else if(payloadType = = XXX)	
multiview_scene_info(payloadSize)	
else if(payloadType = = XXX)	
multiview_acquisition_info(payloadSize)	
else if(payloadType = = XXX)	
multiview_view_position(payloadSize)	
else if(payloadType = = XXX)	
alpha_channel_info(payloadSize)	
else if(payloadType = = XXX)	
overlay_info(payloadSize)	
else if(payloadType = = XXX)	
temporal_motion_vector_prediction_constraints(payloadSize)	
else if(payloadType = = XXX)	
frame_field_info(payloadSize)	
else if(payloadType = = XXX)	
ols_nesting(payloadSize)	
else if(payloadType = = XXX)	
vps_rewriting(payloadSize)	
...	
else	

reserved_sei_message(payloadSize)	
else /* nal_unit_type = = SUFFIX_SEI_NUT */	
if(payloadType = = 3)	
filler_payload(payloadSize)	
...	
else	
reserved_sei_message(payloadSize)	
if(more_data_in_payload( )) {	
if(payload_extension_present( ))	
reserved_payload_extension_data	u(v)
payload_bit_equal_to_one /* equal to 1 */	f(1)
while(!byte_aligned( ))	
payload_bit_equal_to_zero /* equal to 0 */	f(1)
}	
}	

Modify subclause D.2.2 as follows:

buffering_period(payloadSize) {	**Descriptor**
bp_seq_parameter_set_id	ue(v)
if(!sub_pic_hrd_params_present_flag)	
irap_cpb_params_present_flag	u(1)
if(irap_cpb_params_present_flag) {	
cpb_delay_offset	u(v)
dpb_delay_offset	u(v)
}	
concatenation_flag	u(1)
au_cpb_removal_delay_delta_minus1	u(v)
if(NalHrdBpPresentFlag) {	
for(i = 0; i <= CpbCnt; i++) {	
nal_initial_cpb_removal_delay[i **]**	u(v)
nal_initial_cpb_removal_offset[i **]**	u(v)
if(sub_pic_hrd_params_present_flag || irap_cpb_params_present_flag) {	
nal_initial_alt_cpb_removal_delay[i **]**	u(v)
nal_initial_alt_cpb_removal_offset[i **]**	u(v)
}	
}	
}	
if(VclHrdBpPresentFlag) {	
for(i = 0; i <= CpbCnt; i++) {	
vcl_initial_cpb_removal_delay[i **]**	u(v)
vcl_initial_cpb_removal_offset[i **]**	u(v)
if(sub_pic_hrd_params_present_flag || irap_cpb_params_present_flag) {	
vcl_initial_alt_cpb_removal_delay[i **]**	u(v)
vcl_initial_alt_cpb_removal_offset[i **]**	u(v)
}	
}	
}	
if(payload_extension_present( ))	
use_alt_cpb_params_flag	u(1)
}	

Modify the text after Table D-1 in subclause D.3.1 as follows:

It is a requirement of bitstream conformance that when a prefix SEI message with payloadType equal to 17 (progressive refinement segment end) or 22 (post-filter hint) is present in an access unit, a suffix SEI message with the same value of payloadType shall not be present in the same access unit.

It is a requirement of bitstream conformance that the following restrictions apply on containing of SEI messages in SEI NAL units:

– An SEI NAL unit containing an active parameter sets SEI message shall contain only one active parameter sets SEI message and shall not contain any other SEI messages.

– When an SEI NAL unit contains a non-nested buffering period SEI message, a non-nested picture timing SEI message, or a non-nested decoding unit information SEI message, the SEI NAL unit shall not contain any other SEI message with payloadType not equal to 0 (buffering period), 1 (picture timing), or 130 (decoding unit information).

– When an SEI NAL unit contains a nested buffering period SEI message, a nested picture timing SEI message, or a nested decoding unit information SEI message, the SEI NAL unit shall not contain any other SEI message with payloadType not equal to 0 (buffering period), 1 (picture timing), 130 (decoding unit information), or 133 (scalable nesting).

Let prevVclNalUnitInAu of an SEI NAL unit or an SEI message be the preceding VCL NAL unit in decoding order, if any, in the same access unit, and nextVclNalUnitInAu of an SEI NAL unit or an SEI message be the next VCL NAL unit in decoding order, if any, in the same access unit.

It is a requirement of bitstream conformance that the following restrictions apply on decoding order of SEI messages:

– When an SEI NAL unit containing an active parameter sets SEI message is present in an access unit, it shall be the first SEI NAL unit that follows the prevVclNalUnitInAu of the SEI NAL unit and precedes the nextVclNalUnitInAu of the SEI NAL unit.

– When a non-nested buffering period SEI message is present in an access unit, it shall not follow any other SEI message that follows the prevVclNalUnitInAu of the buffering period SEI message and precedes the nextVclNalUnitInAu of the buffering period SEI message, other than an active parameter sets SEI message.

– When a non-nested picture timing SEI message is present in an access unit, it shall not follow any other SEI message that follows the prevVclNalUnitInAu of the picture timing SEI message and precedes the nextVclNalUnitInAu of the picture timing SEI message, other than an active parameter sets SEI message or a non-nested buffering period SEI message.

– When a non-nested decoding unit information SEI message is present in an access unit, it shall not follow any other SEI message in the same access unit that follows the prevVclNalUnitInAu of the decoding unit information SEI message and precedes the nextVclNalUnitInAu of the decoding unit information SEI message, other than an active parameter sets SEI message, a non-nested buffering period SEI message, or a non-nested picture timing SEI message.

– When a nested buffering period SEI message, a nested picture timing SEI message, or a nested decoding unit information SEI message is contained in a scalable nesting SEI message in an access unit, the scalable nesting SEI message shall not follow any other SEI message that follows the prevVclNalUnitInAu of the scalable nesting SEI message and precedes the nextVclNalUnitInAu of the scalable nesting SEI message, other than an active parameter sets SEI message, a non-nested buffering period SEI message, a non-nested picture timing SEI message, a non-nested decoding unit information SEI message, or another scalable nesting SEI message that contains a buffering period SEI message, a picture timing SEI message, or a decoding unit information SEI message.

– When payloadType is equal to 0 (buffering period), 1 (picture timing), or 130 (decoding unit information) for an SEI message, nested or non-nested, within the access unit, the SEI NAL unit containing the SEI message shall precede all NAL units of any picture unit that has nuh_layer_id greater than highestAppLayerId, where highestAppLayerId is the greatest value of nuh_layer_id of all the layers in all the operation points that the SEI message applies to.

– When payloadType is equal to 2, 3, 6, 9, 15, 16, 17, 19, 22, 23, 45, 47, 128, 131, 132, or 134 (i.e. one of the SEI messages that have payloadType not equal to any of 0, 1, 4, 5, 130, and 133) for an SEI message, nested or non-nested, within the access unit, the SEI NAL unit containing the SEI message shall precede all NAL units of any picture unit that has nuh_layer_id greater than highestAppLayerId, where highestAppLayerId is the greatest value of nuh_layer_id of all the layers that the SEI message applies to.

The following applies on the applicable operation points or layers of SEI messages:

– For a non-nested SEI message, when payloadType is equal to 0 (buffering period) or 130 (decoding unit information), the non-nested SEI message applies to the operation point that has OpTid equal to the greatest value of nuh_temporal_id_plus1 among all VCL NAL units in the bitstream, and that has OpLayerIdList containing all values of nuh_layer_id in all VCL units in the bitstream.

– For a non-nested SEI message, when payloadType is equal to 1 (picture timing), the frame field information carried in the syntax elements pic_struct, source_scan_type, and duplicate_flag, when present, in the non-nested picture timing SEI message applies to the base layer only, while the picture timing information carried in other syntax elements, when present, in the non-nested picture timing SEI message applies to the operation point that has OpTid equal to the greatest value of nuh_temporal_id_plus1 among all VCL NAL units in the bitstream, and that has OpLayerIdList containing all values of nuh_layer_id in all VCL units in the bitstream.

– For a non-nested SEI message, when payloadType is equal to 2, 3, 6, 9, 15, 16, 17, 19, 22, 23, 45, 47, 128, 131, 132, or 134 (i.e. one of the SEI messages that have payloadType not equal to any of 0, 1, 4, 5, 130, and 133), the non-nested SEI message applies to the layer for which the VCL NAL units have nuh_layer_id equal to the nuh_layer_id of the SEI NAL unit containing the SEI message. [Ed. (MH): Editorial suggestion: as this list is repeated multiple

times and as any new SEI messages would have to be included in the list, it would be better to assign the list to a global variable and refer to the variable. The same applies for the other list 0, 1, 4, 5, 130 and other similar lists.]

– An active parameter sets SEI message, which cannot be nested, applies to all layers in the bitstream.

It is a requirement of bitstream conformance that the following restrictions apply on nesting of SEI messages:

– An SEI message that has payloadType equal to 129 (active parameter sets), 132 (decoded picture hash), and 133 (scalable nesting) shall not be nested in a scalable nesting SEI message.

– When a scalable nesting SEI message contains a buffering period SEI message, a picture timing SEI message, or a decoding unit information SEI message, the scalable nesting SEI message shall not contain any other SEI message with payloadType not equal to 0 (buffering period), 1 (picture timing), or 130 (decoding unit information).

– When a scalable nesting SEI message contains a buffering period SEI message, a picture timing SEI message, or a decoding unit information SEI message, the value of bitstream_subset_flag of the scalable nesting SEI message shall be equal to 1.

– When a scalable nesting SEI message contains an SEI message that has payloadType equal to 2, 3, 6, 9, 15, 16, 17, 19, 22, 23, 45, 47, 128, 131, 132, or 134 (i.e. one of the SEI messages that have payloadType not equal to any of 0, 1, 4, 5, 130, and 133), the value of bitstream_subset_flag of the scalable nesting SEI message shall be equal to 0.

It is a requirement of bitstream conformance that the following restrictions apply on the values of nuh_layer_id and TemporalId of SEI NAL units:

– When a non-nested SEI message has payloadType equal to 2, 3, 6, 9, 15, 16, 17, 19, 22, 23, 45, 47, 128, 131, 132, or 134 (i.e. one of the SEI messages that have payloadType not equal to any of 0, 1, 4, 5, 129, 130, and 133), the SEI NAL unit containing the non-nested SEI message shall have TemporalId equal to the TemporalId of the access unit containing the SEI NAL unit.

– When a non-nested SEI message has payloadType equal to 0, 1, 129, or 130, the SEI NAL unit containing the non-nested SEI message shall have nuh_layer_id equal to 0.

– When a non-nested SEI message has payloadType equal to 2, 3, 6, 9, 15, 16, 17, 19, 22, 23, 45, 47, 128, 131, 132, or 134 (i.e. one of the SEI messages that have payloadType not equal to any of 0, 1, 129, 130, and 133), the SEI NAL unit containing the non-nested SEI message shall have nuh_layer_id equal to the nuh_layer_id of VCL NAL unit associated with the SEI NAL unit.

NOTE 4 – For an SEI NAL unit containing a scalable nesting SEI message, the values of TemporalId and nuh_layer_id should be set equal to the lowest value of TemporalId and nuh_layer_id, respectively, of all the sub-layers or operation points the nested SEI messages apply to.

It is a requirement of bitstream conformance that the following restrictions apply on the presence of SEI messages between two VCL NAL units of a picture:

– When there is a prefix SEI message that has payloadType equal to 0, 1, 2, 3, 6, 9, 15, 16, 17, 19, 22, 23, 45, 47, 128, 129, or 131 (i.e. one of the prefix SEI messages that are not user data registered by Rec. ITU-T T.35 SEI message, user data unregistered SEI message, decoding unit information SEI message, scalable nesting SEI message, or region refresh information SEI message) and applies to a picture of a layer layerA present between two VCL NAL units of the picture in decoding order, there shall be a prefix SEI message that is of the same type and applies to the layer layerA present in the same access unit preceding the first VCL NAL unit of the picture.

– When there is a suffix SEI message that has payloadType equal to 3 (filler payload), 17 (progressive refinement segment end), 22 (post filter hint), or 132 (decoded picture hash) and applies to a picture of a layer layerA present between two VCL NAL units of the picture in decoding order, there shall be a suffix SEI message that is of the same type and applies to the layer layerA present in the same access unit succeeding the last VCL NAL unit of the picture.

It is a requirement of bitstream conformance that the following restrictions apply on repetition of SEI messages:

– For each of the following payloadType values, there shall be less than or equal to 8 identical sei_payload( ) syntax structures within a picture unit: 0, 1, 2, 6, 9, 15, 16, 17, 19, 22, 23, 45, 47, 128, 129, 131, 132, and 133.

– There shall be less than or equal to 8 identical sei_payload( ) syntax structures with payloadType equal to 130 within a decoding unit.

– The number of identical sei_payload( ) syntax structures with payloadType equal to 134 in a picture unit shall be less than or equal to the number of slice segments in the picture unit.

In the following subclauses of this annex, when a particular SEI message applies to a set of one or more layers (instead of a set of operation points), i.e. when the payloadType value is not equal to one of 0 (buffering period), 1 (picture timing), and 130 (decoding unit information), the following applies:

– The semantics apply independently to each particular layer with nuh_layer_id equal to targetLayerId of the layers to which the particular SEI message applies.

– The current SEI message refers to the particular SEI message.

– The current access unit refers to the access unit containing the current SEI message.

– The current layer refers to the layer with nuh_layer_id equal to targetLayerId.

– The current picture or the current decoded picture refers to the picture with nuh_layer_id equal to targetLayerId (i.e. in the current layer) in the current access unit.

– The direct and indirect reference layers of the current layer are referred to as the reference layers of the current layer.

In the following subclauses of this annex, when a particular SEI message applies to a set of one or more operation points (instead of a set of one or more layers), i.e. when the payloadType value is equal to 0 (buffering period), 1 (picture timing), or 130 (decoding unit information), the following applies:

– The semantics apply independently to each particular operation point of the set of operation points to which the particular SEI message applies.

– The current SEI message refers to the particular SEI message.

– The current operation point refers to the particular operation point.

– The terms "access unit" and "CVS" apply to the bitstream BitstreamToDecode that is the sub-bitstream of the particular operation point.

Modify subclause D.3.2 as follows:

A buffering period SEI message provides initial CPB removal delay and initial CPB removal delay offset information for initialization of the HRD at the position of the associated access unit in decoding order.

A buffering period SEI message may be included in a scalable nesting SEI message with nesting_op_flag equal to 1. [Ed. (YK): The sentence does not say anything normative/essential. Is it trying to say that when buffering period SEI message is nested, the containing scalable nesting SEI message shall have nesting_op_flag equal to 1? Either remove it, just put it to the semantics of the SN SEI message to, and it should be consistent for PT and DUI SEIs.]

If a buffering period SEI message is included in a scalable nesting SEI message, a set of skipped leading pictures skippedPictureList consists of the CL-RAS pictures and the RASL pictures associated with the IRAP pictures with nuh_layer_id equal to nuhLayerId for which LayerInitializedFlag[nuhLayerId] is equal to 0 at the start of decoding the IRAP picture and for which nuhLayerId is among the nestingLayerIdList[i] for any value of i in the range of 0 to nesting_num_ops_minus1, inclusive. Otherwise (a buffering period SEI message is not nested in a scalable nesting SEI message), skippedPictureList consists of the RASL pictures associated with which the IRAP picture which the buffering period SEI message is associated.

The following applies for the buffering period SEI message syntax and semantics:

– The syntax elements initial_cpb_removal_delay_length_minus1, au_cpb_removal_delay_length_minus1, dpb_output_delay_length_minus1, and sub_pic_hrd_params_present_flag, and the variables NalHrdBpPresentFlag and VclHrdBpPresentFlag are found in or derived from syntax elements found in the hrd_parameters( ) syntax structure that is applicable to at least one of the operation points to which the buffering period SEI message applies.

– The variables CpbSize[i], BitRate[i] and CpbCnt are derived from syntax elements found in the sub_layer_hrd_parameters( ) syntax structure that is applicable to at least one of the operation points to which the buffering period SEI message applies.

– Any two operation points that the buffering period SEI message applies to having different OpTid values tIdA and tIdB indicate that the values of cpb_cnt_minus1[tIdA] and cpb_cnt_minus1[tIdB] coded in the hrd_parameters( ) syntax structure(s) applicable to the two operation points are identical.

– Any two operation points that the buffering period SEI message applies to having different OpLayerIdList values layerIdListA and layerIdListB indicate that the values of nal_hrd_parameters_present_flag and vcl_hrd_parameters_present_flag, respectively, for the two hrd_parameters( ) syntax structures applicable to the two operation points are identical.

– The bitstream (or a part thereof) refers to the bitstream subset (or a part thereof) associated with any of the operation points to which the buffering period SEI message applies.

The presence of buffering period SEI messages for an operation point is specified as follows:

– If NalHrdBpPresentFlag is equal to 1 or VclHrdBpPresentFlag is equal to 1, the following applies for each access unit in the CVS:
  – If the access unit is an IRAP access unit, a buffering period SEI message applicable to the operation point shall be associated with the access unit.
  – Otherwise, if both of the following conditions apply, a buffering period SEI message applicable to the operation point may or may not be present for the access unit:
    – The access unit has TemporalId equal to 0.
    – The access unit has at least one picture that has discardable_flag equal to 0 and is not a RASL, RADL or sub-layer non-reference picture.
  – Otherwise, the access unit shall not be associated with a buffering period SEI message applicable to the operation point.
– Otherwise (NalHrdBpPresentFlag and VclHrdBpPresentFlag are both equal to 0), no access unit in the CVS shall be associated with a buffering period SEI message applicable to the operation point.

NOTE 1 – For some applications, frequent presence of buffering period SEI messages may be desirable (e.g. for random access at an IRAP picture or a non-IRAP picture or for bitstream splicing).

bp_seq_parameter_set_id indicates and shall be equal to the sps_seq_parameter_set_id for the SPS that is active for the coded picture associated with the buffering period SEI message. The value of bp_seq_parameter_set_id shall be equal to the value of pps_seq_parameter_set_id in the PPS referenced by the slice_pic_parameter_set_id of the slice segment headers of the coded picture associated with the buffering period SEI message. The value of bp_seq_parameter_set_id shall be in the range of 0 to 15, inclusive.

irap_cpb_params_present_flag equal to 1 specifies the presence of the initial_alt_cpb_removal_delay[i] and initial_alt_cpb_removal_offset[i] syntax elements. When not present, the value of irap_cpb_params_present_flag is inferred to be equal to 0. When the associated picture is neither a CRA picture nor a BLA picture, the value of irap_cpb_params_present_flag shall be equal to 0.

NOTE 2 – The values of sub_pic_hrd_params_present_flag and irap_cpb_params_present_flag cannot be both equal to 1.

cpb_delay_offset specifies an offset to be used in the derivation of the nominal CPB removal times of pictures following, in decoding order, the CRA or BLA picture associated with the buffering period SEI message when no picture in skippedPictureList is present. The syntax element has a length in bits given by au_cpb_removal_delay_length_minus1 + 1. When not present, the value of cpb_delay_offset is inferred to be equal to 0.

dpb_delay_offset specifies an offset to be used in the derivation of the DPB output times of the CRA or BLA picture associated with the buffering period SEI message when no picture in skippedPictureList is present. The syntax element has a length in bits given by dpb_output_delay_length_minus1 + 1. When not present, the value of dpb_delay_offset is inferred to be equal to 0.

When the current picture is not the first picture in the bitstream in decoding order, let prevNonDiscardablePic be the preceding picture in decoding order with TemporalId equal to 0 that is not a RASL, RADL or sub-layer non-reference picture.

concatenation_flag indicates, when the current picture is not the first picture in the bitstream in decoding order, whether the nominal CPB removal time of the current picture is determined relative to the nominal CPB removal time of the preceding picture with a buffering period SEI message or relative to the nominal CPB removal time of the picture prevNonDiscardablePic.

au_cpb_removal_delay_delta_minus1 plus 1, when the current picture is not the first picture in the bitstream in decoding order, specifies a CPB removal delay increment value relative to the nominal CPB removal time of the picture prevNonDiscardablePic. This syntax element has a length in bits given by au_cpb_removal_delay_length_minus1 + 1.

When the current picture contains a buffering period SEI message and concatenation_flag is equal to 0 and the current picture is not the first picture in the bitstream in decoding order, it is a requirement of bitstream conformance that the following constraint applies:

– If the picture prevNonDiscardablePic is not associated with a buffering period SEI message, the au_cpb_removal_delay_minus1 of the current picture shall be equal to the au_cpb_removal_delay_minus1 of prevNonDiscardablePic plus au_cpb_removal_delay_delta_minus1 + 1.
– Otherwise, au_cpb_removal_delay_minus1 shall be equal to au_cpb_removal_delay_delta_minus1.

NOTE 3 – When the current picture contains a buffering period SEI message and concatenation_flag is equal to 1, the au_cpb_removal_delay_minus1 for the current picture is not used. The above-specified constraint can, under some circumstances, make it possible to splice bitstreams (that use suitably-designed referencing structures) by simply changing the value of concatenation_flag from 0 to 1 in the buffering period SEI message for an IRAP picture at the splicing point. When

concatenation_flag is equal to 0, the above-specified constraint enables the decoder to check whether the constraint is satisfied as a way to detect the loss of the picture prevNonDiscardablePic.

nal_initial_cpb_removal_delay[i] and **nal_initial_alt_cpb_removal_delay**[i] specify the default and the alternative initial CPB removal delays, respectively, for the i-th CPB when the NAL HRD parameters are in use. The syntax elements have a length in bits given by initial_cpb_removal_delay_length_minus1 + 1, and are in units of a 90 kHz clock. The values of the syntax elements shall not be equal to 0 and shall be less than or equal to 90000 * (CpbSize[i] ÷ BitRate[i]), the time-equivalent of the CPB size in 90 kHz clock units.

nal_initial_cpb_removal_offset[i] and **nal_initial_alt_cpb_removal_offset**[i] specify the default and the alternative initial CPB removal offsets, respectively, for the i-th CPB when the NAL HRD parameters are in use. The syntax elements have a length in bits given by initial_cpb_removal_delay_length_minus1 + 1 and are in units of a 90 kHz clock.

Over the entire CVS, the sum of nal_initial_cpb_removal_delay[i] and nal_initial_cpb_removal_offset[i] shall be constant for each value of i, and the sum of nal_initial_alt_cpb_removal_delay[i] and nal_initial_alt_cpb_removal_offset[i] shall be constant for each value of i.

vcl_initial_cpb_removal_delay[i] and **vcl_initial_alt_cpb_removal_delay**[i] specify the default and the alternative initial CPB removal delays, respectively, for the i-th CPB when the VCL HRD parameters are in use. The syntax elements have a length in bits given by initial_cpb_removal_delay_length_minus1 + 1, and are in units of a 90 kHz clock. The values of the syntax elements shall not be equal to 0 and shall be less than or equal to 90000 * (CpbSize[i] ÷ BitRate[i]), the time-equivalent of the CPB size in 90 kHz clock units.

vcl_initial_cpb_removal_offset[i] and **vcl_initial_alt_cpb_removal_offset**[i] specify the default and the alternative initial CPB removal offsets, respectively, for the i-th CPB when the VCL HRD parameters are in use. The syntax elements have a length in bits given by initial_cpb_removal_delay_length_minus1 + 1 and are in units of a 90 kHz clock.

Over the entire CVS, the sum of vcl_initial_cpb_removal_delay[i] and vcl_initial_cpb_removal_offset[i] shall be constant for each value of i, and the sum of vcl_initial_alt_cpb_removal_delay[i] and vcl_initial_alt_cpb_removal_offset[i] shall be constant for each value of i.

use_alt_cpb_params_flag is used to derive the value of UseAltCpbParamsFlag. When irap_cpb_params_present_flag is equal to 0, use_alt_cpb_params_flag shall not be equal to 1. When use_alt_cpb_params_flag is not present, it is inferred to be equal to 0.

NOTE 4 – Encoders are recommended either to set use_alt_cpb_params_flag equal to 0 or not to include irap_cpb_params_present_flag equal to 1 in non-nested buffering period SEI messages associated with a CRA or BLA picture for which at least one of its associated RASL pictures follows one or more of its associated RADL pictures in decoding order. Encoders are recommended either to set use_alt_cpb_params_flag equal to 0 or not to include irap_cpb_params_present_flag equal to 1 in a nested buffering period SEI message that is nested in a scalable nesting SEI message and associated with an IRAP picture with NoClrasOutputFlag equal to 1 for which at least one of RASL pictures associated with an IRAP picture with nuh_layer_id equal to nuhLayerId such that LayerInitializedFlag[nuhLayerId] equal to 0 (at the beginning of decoding the IRAP picture) follows one or more of its associated RADL pictures in decoding order or for which CL-RAS pictures are present.

Add in subclause D.3.3 before the semantics of pic_struct:

If the picture timing SEI message is nested in a scalable nesting SEI message, the semantics of pic_struct, source_scan_type, and duplicate_flag are unspecified. [Ed. (YK): Should it be specified that decoders shall ignore the values of these fields in this case? (MH): "shall ignore" would not make any practical difference, as these syntax elements affect decoding.] Otherwise, the semantics of pic_struct, source_scan_type, and duplicate_flag are specified in the following paragraphs.

NOTE X – When an OLS contains multiple layers, the frame-field information SEI message can be used to indicate pic_struct, source_scan_type, and duplicate_flag for each of the multiple layers.

Modify subclause D.3.4 as follows:

pan_scan_rect_cancel_flag equal to 1 indicates that the SEI message cancels the persistence of any previous pan-scan rectangle SEI message in output order that applies to the current layer. pan_scan_rect_cancel_flag equal to 0 indicates that pan-scan rectangle information follows.

pan_scan_rect_persistence_flag specifies the persistence of the pan-scan rectangle SEI message for the current layer.

pan_scan_rect_persistence_flag equal to 0 specifies that the pan-scan rectangle information applies to the current decoded picture only.

Let picA be the current picture. pan_scan_rect_persistence_flag equal to 1 specifies that the pan-scan rectangle information persists for the current layer in output order until any of the following conditions are true:

– A new CVS begins.

– The bitstream ends.

– A picture picB in the current layer in an access unit containing a pan-scan rectangle SEI message with the same value of pan_scan_rect_id and applicable to the current layer is output for which PicOrderCnt(picB) is greater than PicOrderCnt(picA), where PicOrderCnt(picB) and PicOrderCnt(picA) are the PicOrderCntVal values of picB and picA, respectively, immediately after the invocation of the decoding process for picture order count for picB.

Modify subclause D.3.8 as follows:

The semantics below apply independently to each particular layer with nuh_layer_id equal to targetLayerId of the layers to which the recovery point SEI message applies. The current picture refers to the picture with nuh_layer_id equal to targetLayerId in the access unit containing the current SEI message.

NOTE 1 – If not nested, a recovery point SEI message applies to the layer for which the VCL NAL units have nuh_layer_id equal to the nuh_layer_id of the SEI NAL unit containing the SEI message. Otherwise, the layers to which a recovery point SEI message applies are specified by the scalable nesting SEI message that contains the SEI message.

The recovery point SEI message assists a decoder in determining when the decoding process will produce acceptable pictures with nuh_layer_id equal to targetLayerId for display after the decoder initiates random access or after the encoder indicates a broken link.

NOTE 2 – For a single-layer bitstream, the recovery point SEI message may be used to indicate that it is possible to perform random access from the current access unit even when the current picture is not an IRAP picture. For example, it is possible to code a picture as an intra picture but not an IRAP picture, enable random accessing from the picture, and add an associated recovery point SEI message to indicate random accessibility. This functionality can be used to improve the coding efficiency of a sequence of interlaced field pictures with random accessibility needed, because there is a restriction that pictures before a CRA picture in output order cannot use pictures that follow the CRA picture for inter-prediction reference, while such referencing is possible if the CRA picture was encoded as a non-IRAP picture.

When all decoded pictures in earlier access units in decoding order are removed from the bitstream, the recovery point picture (defined below) and all the subsequent pictures in output order in the current layer can be correctly or approximately correctly decoded, the current picture is referred to as a layer random-accessing picture. When the pictures that belong to any reference layer, that precede, in decoding order, the current picture and that may be used for reference by the current picture or subsequent pictures in decoding order are correctly decoded, and the recovery point picture and all the subsequent pictures in output order in the current layer can be correctly or approximately correctly decoded when no picture prior to the current picture in decoding order in the current layer are present in the bitstream, the current picture is referred to as a layer up-switching picture.

When the recovery point SEI message applies to the current layer and all the reference layers of the current layer, the current picture is indicated as a layer random-accessing picture. When the recovery point SEI message applies to the current layer only, the current picture is indicated as a layer up-switching picture.

Decoded pictures with nuh_layer_id equal to targetLayerId produced by random access at or before the access unit containing the recovery point SEI message need not be correct in content until the indicated recovery point, and the operation of the decoding process starting at access unit containing the recovery point SEI message may contain references to pictures unavailable in the decoded picture buffer.

In addition, by use of the broken_link_flag, the recovery point SEI message can indicate to the decoder the location of some pictures with nuh_layer_id equal to targetLayerId in the bitstream that can result in serious visual artefacts when displayed, even when the decoding process was begun at the location of a previous access unit containing an IRAP picture with nuh_layer_id equal to targetLayerId in decoding order.

NOTE 3 – The broken_link_flag can be used by encoders to indicate the location of a point after which the decoding process for the decoding of some pictures with nuh_layer_id equal to targetLayerId may cause references to pictures that, though available for use in the decoding process, are not the pictures that were used for reference when the bitstream was originally encoded (e.g. due to a splicing operation performed during the generation of the bitstream).

When random access is performed to start decoding from the access unit containing the recovery point SEI message, the decoder operates as if the associated access unit was the first access unit in the bitstream in decoding order, and the variable PrevPicOrderCnt[nuh_layer_id] used in derivation of PicOrderCntVal for each picture in the access unit is set equal to 0.

NOTE 4 – When HRD information is present in the bitstream, a buffering period SEI message should be associated with the access unit associated with the recovery point SEI message in order to establish initialization of the HRD buffer model after a random access.

Any SPS or PPS RBSP that is referred to by a picture of the access unit containing a recovery point SEI message or by any picture in a subsequent access unit in decoding order shall be available to the decoding process prior to its activation,

regardless of whether or not the decoding process is started at the beginning of the bitstream or with the access unit, in decoding order, that contains the recovery point SEI message.

recovery_poc_cnt specifies the recovery point of decoded pictures with nuh_layer_id equal to targetLayerId in output order. If there is a picture picB with nuh_layer_id equal to targetLayerId that follows the current picture picA but precedes an access unit containing an IRAP picture with nuh_layer_id equal to targetLayerId in decoding order and PicOrderCnt(picB) is equal to PicOrderCnt(picA) plus the value of recovery_poc_cnt, where PicOrderCnt(picA) and PicOrderCnt(picB) are the PicOrderCntVal values of picA and picB, respectively, immediately after the invocation of the decoding process for picture order count for picB, the picture picB is referred to as the recovery point picture. Otherwise, the first picture picC with nuh_layer_id equal to targetLayerId in output order for which PicOrderCnt(picC) is greater than PicOrderCnt(picA) plus the value of recovery_poc_cnt is referred to as the recovery point picture, where PicOrderCnt(picA) and PicOrderCnt(picC) are the PicOrderCntVal values of picA and picC, respectively, immediately after the invocation of the decoding process for picture order count for picC. The recovery point picture shall not precede the current picture in decoding order. All decoded pictures with nuh_layer_id equal to targetLayerId in output order are indicated to be correct or approximately correct in content starting at the output order position of the recovery point picture. The value of recovery_poc_cnt shall be in the range of −MaxPicOrderCntLsb / 2 to MaxPicOrderCntLsb / 2 − 1, inclusive.

exact_match_flag indicates whether decoded pictures with nuh_layer_id equal to targetLayerId at and subsequent to the specified recovery point in output order derived by starting the decoding process at the access unit containing the recovery point SEI message will be an exact match to the pictures with nuh_layer_id equal to targetLayerId that would be produced by starting the decoding process at the location of a previous access unit where the picture of the layer with nuh_layer_id equal to targetLayerId and the pictures of all the direct and indirect reference layers are IRAP pictures, if any, in the bitstream. The value 0 indicates that the match may not be exact and the value 1 indicates that the match will be exact. When exact_match_flag is equal to 1, it is a requirement of bitstream conformance that the decoded pictures with nuh_layer_id equal to targetLayerId at and subsequent to the specified recovery point in output order derived by starting the decoding process at the access unit containing the recovery point SEI message shall be an exact match to the pictures with nuh_layer_id equal to targetLayerId that would be produced by starting the decoding process at the location of a previous access unit where the picture of the layer with nuh_layer_id equal to targetLayerId and the pictures of all the direct and indirect reference layers are IRAP pictures, if any, in the bitstream.

NOTE 5 – When performing random access, decoders should infer all references to unavailable pictures as references to pictures containing only intra coding blocks and having sample values given by Y equal to (1 << ($BitDepth_Y$ − 1)), Cb and Cr both equal to (1 << ($BitDepth_C$ − 1)) (mid-level grey), regardless of the value of exact_match_flag.

When exact_match_flag is equal to 0, the quality of the approximation at the recovery point is chosen by the encoding process and is not specified in this Specification.

broken_link_flag indicates the presence or absence of a broken link in the layer with nuh_layer_id equal to targetLayerId at the location of the recovery point SEI message and is assigned further semantics as follows:

– If broken_link_flag is equal to 1, pictures with nuh_layer_id equal to targetLayerId produced by starting the decoding process at the location of a previous access unit where the picture of the layer with nuh_layer_id equal to targetLayerId and the pictures of all the direct and indirect reference layers are IRAP pictures may contain undesirable visual artefacts to the extent that decoded pictures with nuh_layer_id equal to targetLayerId at and subsequent to the access unit containing the recovery point SEI message in decoding order should not be displayed until the specified recovery point in output order.

– Otherwise (broken_link_flag is equal to 0), no indication is given regarding any potential presence of visual artefacts.

When the current picture is a BLA picture, the value of broken_link_flag shall be equal to 1.

Regardless of the value of the broken_link_flag, pictures with nuh_layer_id equal to targetLayerId subsequent to the specified recovery point in output order are specified to be correct or approximately correct in content.

Modify subclause D.3.11 as follows:

The progressive refinement segment start SEI message specifies the beginning of a set of consecutive coded pictures in the current layer in decoding order that consists of the current picture and a sequence of one or more subsequent pictures in the current layer that refine the quality of the current picture, rather than a representation of a continually moving scene.

Let picA be the current picture. The tagged set of consecutive coded pictures refinementPicSet in the current layer starts from the next picture in the current layer after the current picture in decoding order and continues, in decoding order, until one of the following conditions is true: [Ed. (MH): It is suggested to change the phrasing to indicate that the picture for which the condition is true is not included in refinementPicSet.]

– A new CVS begins.
– The bitstream ends.
– pic_order_cnt_delta is greater than 0 and the PicOrderCntVal of the next slice, which belongs to the picture picB in the current layer, to be decoded, i.e. PicOrderCnt(picB), is greater than PicOrderCnt(picA) plus pic_order_cnt_delta, where PicOrderCnt(picB) and PicOrderCnt(picA) are the PicOrderCntVal values of picB and picA, respectively, immediately after the invocation of the decoding process for picture order count for picB.
– A progressive refinement segment end SEI message that has the same progressive_refinement_id as the one in this SEI message and also applies to the current layer is decoded.

The decoding order of pictures within refinementPicSet should be the same as their output order.

progressive_refinement_id specifies an identification number for the progressive refinement operation. progressive_refinement_id shall be in the range of 0 to $2^{32} - 2$, inclusive.

Values of progressive_refinement_id in the range of 0 to 255, inclusive, and in the range of 512 to $2^{31} - 1$, inclusive, may be used as determined by the application. Values of progressive_refinement_id in the range of 256 to 511, inclusive, and in the range of 2^{31} to $2^{32} - 2$, inclusive, are reserved for future use by ITU-T | ISO/IEC. Decoders encountering a value of progressive_refinement_id in the range of 256 to 511, inclusive, or in the range of 2^{31} to $2^{32} - 2$, inclusive, shall ignore it.

pic_order_cnt_delta specifies the last picture in refinementPicSet in decoding order as follows:

– If pic_order_cnt_delta is equal to 0, the last picture in refinementPicSet in decoding order is the following picture:
  – If the CVS contains one or more pictures in the current layer that follow the current picture in decoding order and are associated with a progressive refinement segment end SEI message that has the same progressive_refinement_id and also applies to the current layer, the last picture in refinementPicSet in decoding order is the first of these pictures in decoding order.
  – Otherwise, the last picture in refinementPicSet in decoding order is the last picture in the current layer within the CVS in decoding order.
– Otherwise, the last picture in refinementPicSet in decoding order is the following picture:
  – If the CVS contains one or more pictures in the current layer that follow the current picture in decoding order, are associated with a progressive refinement segment end SEI message with the same progressive_refinement_id and applicable to the current layer, and precede any picture picC in the current layer in the CVS for which PicOrderCnt(picC) is greater than PicOrderCnt(picA) plus pic_order_cnt_delta, where PicOrderCnt(picC) and PicOrderCnt(picA) are the PicOrderCntVal values of picC and picA, respectively, immediately after the invocation of the decoding process for picture order count for picC, the last picture in refinementPicSet in decoding order is the first of these pictures in decoding order.
  – Otherwise, if the CVS contains one or more pictures picD in the current layer that follow the current picture in decoding order for which PicOrderCnt(picD) is greater than PicOrderCnt(picA) plus pic_order_cnt_delta, where PicOrderCnt(picD) and PicOrderCnt(picA) are the PicOrderCntVal values of picD and picA, respectively, immediately after the invocation of the decoding process for picture order count for picD, the last picture in refinementPicSet in decoding order is the last picture in the current layer that precedes the first of these pictures in decoding order.
  – Otherwise, the last picture in refinementPicSet in decoding order is the last picture in the current layer within the CVS in decoding order.

The value of pic_order_cnt_delta shall be in the range of 0 to 256, inclusive.

Modify subclause D.3.13 as follows:

film_grain_characteristics_cancel_flag equal to 1 indicates that the SEI message cancels the persistence of any previous film grain characteristics SEI message in output order that applies to the current layer. film_grain_characteristics_cancel_flag equal to 0 indicates that film grain modelling information follows.

…

film_grain_characteristics_persistence_flag specifies the persistence of the film grain characteristics SEI message for the current layer.

film_grain_characteristics_persistence_flag equal to 0 specifies that the film grain characteristics SEI message applies to the current decoded picture only.

Let picA be the current picture. film_grain_characteristics_persistence_flag equal to 1 specifies that the film grain characteristics SEI message persists for the current layer in output order until any of the following conditions are true:

– A new CVS begins.
– The bitstream ends.
– A picture picB in the current layer in an access unit containing a film grain characteristics SEI message that is applicable to the current layer is output for which PicOrderCnt(picB) is greater than PicOrderCnt(picA), where PicOrderCnt(picB) and PicOrderCnt(picA) are the PicOrderCntVal values of picB and picA, respectively, immediately after the invocation of the decoding process for picture order count for picB.

Modify subclause D.3.15 as follows:

tone_map_cancel_flag equal to 1 indicates that the tone mapping information SEI message cancels the persistence of any previous tone mapping information SEI message in output order that applies to the current layer. tone_map_cancel_flag equal to 0 indicates that tone mapping information follows.

tone_map_persistence_flag specifies the persistence of the tone mapping information SEI message for the current layer.

tone_map_persistence_flag equal to 0 specifies that the tone mapping information applies to the current decoded picture only.

Let picA be the current picture. tone_map_persistence_flag equal to 1 specifies that the tone mapping information persists for the current layer in output order until any of the following conditions are true:

– A new CVS begins.
– A picture picB in the current layer in an access unit containing a tone mapping information SEI message with the same value of tone_map_id and applicable to the current layer is output for which PicOrderCnt(picB) is greater than PicOrderCnt(picA), where PicOrderCnt(picB) and PicOrderCnt(picA) are the PicOrderCntVal values of picB and picA, respectively, immediately after the invocation of the decoding process for picture order count for picB.

Modify subclause D.3.16 as follows:

frame_packing_arrangement_cancel_flag equal to 1 indicates that the frame packing arrangement SEI message cancels the persistence of any previous frame packing arrangement SEI message in output order that applies to the current layer. frame_packing_arrangement_cancel_flag equal to 0 indicates that frame packing arrangement information follows.

…

frame_packing_arrangement_persistence_flag specifies the persistence of the frame packing arrangement SEI message for the current layer.

frame_packing_arrangement_persistence_flag equal to 0 specifies that the frame packing arrangement SEI message applies to the current decoded frame only.

Let picA be the current picture. frame_packing_arrangement_persistence_flag equal to 1 specifies that the frame packing arrangement SEI message persists for the current layer in output order until any of the following conditions are true:

– A new CVS begins.
– The bitstream ends.
– A frame picB in the current layer in an access unit containing a frame packing arrangement SEI message with the same value of frame_packing_arrangement_id and applicable to the current layer is output for which PicOrderCnt(picB) is greater than PicOrderCnt(picA), where PicOrderCnt(picB) and PicOrderCnt(picA) are the PicOrderCntVal values of picB and picA, respectively, immediately after the invocation of the decoding process for picture order count for picB.

Modify subclause D.3.17 as follows:

display_orientation_persistence_flag specifies the persistence of the display orientation SEI message for the current layer.

display_orientation_persistence_flag equal to 0 specifies that the display orientation SEI message applies to the current decoded picture only.

Let picA be the current picture. display_orientation_persistence_flag equal to 1 specifies that the display orientation SEI message persists for the current layer in output order until one or more of the following conditions are true:

– A new CVS begins.
– The bitstream ends.
– A picture picB in the current layer in an access unit containing a display orientation SEI message that is applicable to the current layer is output for which PicOrderCnt(picB) is greater than PicOrderCnt(picA), where PicOrderCnt(picB) and PicOrderCnt(picA) are the PicOrderCntVal values of picB and picA, respectively, immediately after the invocation of the decoding process for picture order count for picB.

Modify subclause D.3.18 as follows:

The structure of pictures information SEI message provides information for a list of entries, some of which correspond to a series of pictures in decoding order in the current layer in the CVS.

The first entry in the structure of pictures information SEI message corresponds to the current picture. When there is a picture in the current layer that has PicOrderCntVal equal to the variable entryPicOrderCnt[i] as specified below, the entry i corresponds to the picture in the CVS. The decoding order of the pictures in the current layer in the CVS that correspond to entries in the structure of pictures information SEI message corresponds to increasing values of i in the list of entries.

Any picture in the current layer in the CVS that has PicOrderCntVal equal to entryPicOrderCnt[i] for any i in the range of 0 to num_entries_in_sop_minus1, inclusive, shall correspond to an entry in the list of entries.

The structure of pictures information SEI message shall not be present in a CVS and applicable for a layer for which the active SPS has long_term_ref_pics_present_flag equal to 1 or num_short_term_ref_pic_sets equal to 0.

The structure of pictures information SEI message shall not be present in any access unit that has TemporalId greater than 0 or contains a RASL, RADL or sub-layer non-reference picture in the current layer. Any picture in the current layer in the CVS that corresponds to an entry other than the first entry described in the structure of pictures information SEI message shall not be an IRAP picture.

Modify subclause D.3.19 as follows:

This message provides a hash for each colour component of the current decoded picture.

NOTE 1 – The decoded picture hash SEI message is a suffix SEI message and cannot be contained in a scalable nesting SEI message.

Modify subclause D.3.20 as follows:

num_sps_ids_minus1 plus 1 indicates and shall be equal to the number of SPSs that are referred to by the VCL NAL units of the access unit associated with the active parameter sets SEI message. The value of num_sps_ids_minus1 shall be in the range of 0 to 15, inclusive.

Modify subclause D.3.23 as follows:

The scalable nesting SEI message provides a mechanism to associate SEI messages with bitstream subsets corresponding to various operation points or with specific layers or sub-layers.

A scalable nesting SEI message contains one or more SEI messages.

bitstream_subset_flag equal to 0 specifies that the SEI messages contained in the scalable nesting SEI message apply to specific layers or sub-layers. bitstream_subset_flag equal to 1 specifies that the SEI messages contained in the scalable nesting SEI message apply to one or more sub-bitstreams resulting from a sub-bitstream extraction process as specified in clause 10 with inputs based on the syntax elements of the scalable nesting SEI message as specified below.

[Ed. (YK): A paragraph is removed here.]

Depending on the value of bitstream_subset_flag, the layers or sub-layers, or the operation points to which the SEI messages contained in the scalable nesting SEI message apply are specified by deriving the lists nestingLayedIdList[i] and the variables maxTemporalId[i] based on syntax element values as specified below.

nesting_op_flag equal to 0 specifies that the list nestingLayerIdList[0] is specified by all_layers_flag and, when present, nesting_layer_id[i] for all i values in the range of 0 to nesting_num_layers_minus1, inclusive, and that the variable maxTemporalId[0] is specified by nesting_no_op_max_temporal_id_plus1. nesting_op_flag equal to 1 specifies that the list nestingLayerIdList[i] and the variable maxTemporalId[i] are specified by

nesting_num_ops_minus1, default_op_flag, nesting_max_temporal_id_plus1[i], when present, and nesting_op_idx[i], when present.

default_op_flag equal to 1 specifies that maxTemporalId[0] is equal to nuh_temporal_id_plus1 of the current SEI NAL unit minus 1 and that nestingLayerIdList[0] contains all integer values in the range of 0 to nuh_layer_id of the current SEI NAL unit, inclusive, in increasing order of the values.

nesting_num_ops_minus1 plus 1 minus default_op_flag specifies the number of the following nesting_op_idx[i] syntax elements. The value of nesting_num_ops_minus1 shall be in the range of 0 to 1023, inclusive.

If nesting_op_flag is equal to 0, the variable nestingNumOps is set equal to 1. Otherwise, the variable nestingNumOps is set equal to nesting_num_ops_minus1 + 1.

nesting_max_temporal_id_plus1[i] is used to specify the variable maxTemporalId[i]. The value of nesting_max_temporal_id_plus1[i] shall be greater than or equal to nuh_temporal_id_plus1 of the current SEI NAL unit. The variable maxTemporalId[i] is set equal to nesting_max_temporal_id_plus1[i] − 1.

nesting_op_idx[i] is used to specify the list nestingLayerIdList[i]. The value of nesting_op_idx[i] shall be in the range of 0 to 1023, inclusive.

The list nestingLayerIdList[i] is set equal to the OpLayerIdList of the nesting_op_idx[i]-th layer set specified by the active VPS.

all_layers_flag equal to 0 specifies that the list nestingLayerIdList[0] is specified by nesting_layer_id[i] for all i values in the range of 0 to nesting_num_layers_minus1, inclusive. all_layers_flag equal to 1 specifies that the list nestingLayerIdList[0] consists of all values of nuh_layer_id present in the current access unit that are greater than or equal to nuh_layer_id of the current SEI NAL unit, in increasing order of the values.

NOTE – When nuh_layer_id of the SEI NAL unit containing the scalable nesting SEI message is greater than 0, bitstream_subset_flag and all_layers_flag cannot both be equal to 1, because in this case the applicable operation point of the nested SEI messages would not include the base layer and consequently the sub-bitstream corresponding to the applicable operation point would be a non-conforming bitstream.

When nesting_op_flag is equal to 0 and all_layers_flag is equal to 1, maxTemporalId[0] is set equal to 6.

nesting_no_op_max_temporal_id_plus1 minus 1 specifies the value of maxTemporalId[0] when nesting_op_flag is equal to 0 and all_layers_flag is equal to 0. The value of nesting_no_op_max_temporal_id_plus1 shall not be equal to 0.

nesting_num_layers_minus1 plus 1 specifies the number of the following nesting_layer_id[i] syntax elements. The value of nesting_num_layers_minus1 shall be in the range of 0 to 63, inclusive.

nesting_layer_id[i] specifies the i-th nuh_layer_id value included in the list nestingLayerIdList[0].

For any i and j in the range of 0 to nesting_num_layers_minus1, inclusive, with i less than j, nesting_layer_id[i] shall be less than nesting_layer_id[j].

The list nestingLayerIdList[0] is set to consist of nesting_layer_id[i] for all i values in the range of 0 to nesting_num_layers_minus1, inclusive, in increasing order of i values.

When bitstream_subset_flag is equal to 0, the following applies:

– The SEI messages contained in the scalable nesting SEI message apply to the sets of layers or sub-layers subLayerSet[i] for all i values in the range of 0 to nestingNumOps – 1, inclusive, where the VCL NAL units of the layers or sub-layers in each set subLayerSet[i] have nuh_layer_id values that are included in the list nestingLayerIdList[i] and TemporalId values that are in the range of the TemporalId of the current SEI NAL unit to maxTemporalId[i], inclusive.

– When a nested SEI message has payloadType equal to 2, 3, 6, 9, 15, 16, 17, 19, 22, 23, 45, 47, 128, 131, 132, or 134 (i.e. one of the SEI messages that have payloadType not equal to any of 0, 1, 4, 5, 130, and 133), the value of TemporalId of the SEI NAL unit containing the scalable nesting SEI message shall be equal to 0 and maxTemporalId[i] for all i shall be equal to 6. [Ed. (MH): This constraint seems too restrictive and unintuitive for those SEI messages which could apply to single pictures and hence have the TemporalId of the associated picture unit. (YK): Thanks for the fix – we had a weird typo in the original text. The intention for this constraint is just to simply say that all these SEI messages when nested apply to entire layers instead of sub-layers. Otherwise, quite some clarifications would be needed for at least some of the individual SEI messages to clarify how they apply to sub-layers. Think about how to clarify this for the recovery point SEI message and the region refresh information for example – a whole lot of text changes would be needed – I dared not even to try those though I did think about it.]

– When a nested SEI message has payloadType equal to 2, 3, 6, 9, 15, 16, 17, 19, 22, 23, 45, 47, 128, 131, 132, or 134 (i.e. one of the SEI messages that have payloadType not equal to any of 0, 1, 4, 5, 130, and 133) and the value of

nestingNumOps is greater than 0, the nested SEI message applies to all layers for which each nuh_layer_id is included in at least one of the lists nestingLayerIdList[i] with i ranging from 0 to nestingNumOps – 1, inclusive.

When bitstream_subset_flag is equal to 1, the SEI messages contained in the scalable nesting SEI message apply to the operation points corresponding to the sub-bitstreams subBitstream[i] for all i values in the range of 0 to nestingNumOps − 1, inclusive, where each sub-bitstream subBitstream[i] is the output of the sub-bitstream extraction process of clause 10 with the bitstream, maxTemporalId[i], and nestingLayerIdList[i] as inputs.

nesting_zero_bit shall be equal to 0.

Modify subclause D.3.24 as follows:

The region refresh information SEI message indicates whether the slice segments that the current SEI message applies to belong to a refreshed region of the current picture.

The variable targetLayerIdList is derived as follows:

– If the region refresh information SEI message applies to the current layer and all the reference layers, targetLayerIdList contains the nuh_layer_id of the current layer and all the reference layers.

– Otherwise, targetLayerIdList contains the nuh_layer_id of the current layer.

The region refresh SEI message is associated with a recovery point SEI message that applies to targetLayerIdList.

A picture that belongs to a layer with nuh_layer_id greater than 0 or a picture that is not an IRAP picture and belongs to the layer with nuh_layer_id equal to 0, that is contained in an access unit containing a recovery point SEI message where the recovery point SEI message applies to that layer is referred to as a gradual decoding refresh (GDR) picture, and the access unit containing the picture is referred to as a GDR access unit. The access unit corresponding to the indicated recovery point picture is referred to as the recovery point access unit.

If there is a picture picB in the current layer that follows the GDR picture picA in the current layer in decoding order in the CVS and PicOrderCnt(picB) is equal to PicOrderCnt(picA) plus the value of recovery_poc_cnt in the recovery point SEI message, where PicOrderCnt(picA) and PicOrderCnt(picB) are the PicOrderCntVal values of picA and picB, respectively, immediately after the invocation of the decoding process for picture order count for picB, let the variable lastPicInSet be the recovery point picture. Otherwise, let lastPicInSet be the picture in targetLayerIdList that immediately precedes the recovery point picture in output order. The picture lastPicInSet shall not precede the GDR access unit in decoding order.

Let gdrPicSet be the set of pictures in targetLayerIdList starting from a GDR access unit to the access unit containing lastPicInSet, inclusive, in output order. When the decoding process for the current layer is started from a GDR access unit, the refreshed region in each picture of the gdrPicSet is indicated to be the region of the picture that is correct or approximately correct in content, and, when lastPicInSet is contained in the recovery point access unit, the refreshed region in lastPicInSet covers the entire picture.

The slice segments of the current picture to which a region refresh information SEI message applies consist of all slice segments within the picture that follow the SEI NAL unit containing the region refresh information SEI message and precede the next SEI NAL unit, in decoding order, containing a region refresh information SEI message (if any) that has the same targetLayerIdList as the current SEI message. These slice segments are referred to as the slice segments associated with the region refresh information SEI message.

Let gdrAuSet be the set of access units corresponding to gdrPicSet. A gdrAuSet and the corresponding gdrPicSet are referred to as being associated with the recovery point SEI message contained in the GDR access unit.

Region refresh information SEI messages shall not be present in an access unit unless the access unit is included in a gdrAuSet associated with a recovery point SEI message. When any picture that is included in a gdrPicSet is associated with one or more region refresh information SEI messages, all pictures in the gdrPicSet shall be associated with one or more region refresh information SEI messages.

refreshed_region_flag equal to 1 indicates that the slice segments associated with the current SEI message belong to the refreshed region in the current picture. refreshed_region_flag equal to 0 indicates that the slice segments associated with the current SEI message may not belong to the refreshed region in the current picture.

When one or more region refresh information SEI messages are associated with a picture belonging to gdrPicSet and the first slice segment of the picture in decoding order does not have an associated region refresh information SEI message, the value of refreshed_region_flag for the slice segments of the picture that precede the first region refresh information SEI message is inferred to be equal to 0.

When lastPicInSet is the recovery point picture, and any region refresh SEI message is associated with the recovery point access unit, the first slice segment of the picture in decoding order shall have an associated region refresh SEI message, and the value of refreshed_region_flag shall be equal to 1 in all region refresh SEI messages associated with the picture.

When one or more region refresh information SEI messages are associated with a picture, the refreshed region in the picture is specified as the set of CTUs in all slice segments of the picture that are associated with region refresh information SEI messages that have refreshed_region_flag equal to 1. Other slice segments belong to the non-refreshed region of the picture.

It is a requirement of bitstream conformance that when a dependent slice segment belongs to the refreshed region, the preceding slice segment in decoding order shall also belong to the refreshed region.

Let gdrRefreshedSliceSegmentSet be the set of all slice segments that belong to the refreshed regions in the gdrPicSet. The variable upSwitchingRefreshedSliceSegmentSet is derived as follows:

– If targetLayerIdList contains only one non-zero nuh_layer_id, upSwitchingRefreshedSliceSegmentSet is defined as the set inclusive of the following:
  – all slice segments of all pictures of the reference layers that precede, in decoding order, the current picture and that may be used for reference by the current picture or subsequent pictures of the reference layers.
  – all slice segments of all pictures of the reference layers that succeed, in decoding order, the current picture and that belong to gdrAuSet.
– Otherwise, upSwitchingRefreshedSliceSegmentSet is defined as an empty set.

When a gdrPicSet contains one or more pictures associated with region refresh information SEI messages, it is a requirement of bitstream conformance that the following constraints all apply:

– For each layer in targetLayerIdList, the refreshed region in the first picture, in decoding order, that belongs to the layer and that is included in gdrPicSet that contains any refreshed region shall contain only coding units that are coded in an intra coding mode or inter-layer prediction from slice segments belonging to the union of gdrRefreshedSliceSegmentSet and upSwitchingRefreshedSliceSegmentSet.
– For each picture included in the gdrPicSet, the syntax elements in gdrRefreshedSliceSegmentSet shall be constrained such that no samples or motion vector values outside of the union of gdrRefreshedSliceSegmentSet and upSwitchingRefreshedSliceSegmentSet are used for inter prediction or inter-layer prediction in the decoding process of any samples within gdrRefreshedSliceSegmentSet.
– For any picture that follows the picture lastPicInSet in output order, the syntax elements in the slice segments of the picture shall be constrained such that no samples or motion vector values outside of the union of gdrRefreshedSliceSegmentSet and upSwitchingRefreshedSliceSegmentSet are used for inter prediction or inter-

layer prediction in the decoding process of the picture other than those of the other pictures that follow the picture lastPicInSet in output order.

Modify subclause E.2.1 as follows:

Annex E

Video usability information

(This annex forms an integral part of this Recommendation | International Standard)

E.2 VUI semantics

E.2.1 VUI parameters semantics

The specifications in clause E.2.1 apply with the following modifications and additions.

video_signal_type_present_flag equal to 1 specifies that video_format, video_full_range_flag and colour_description_present_flag are present. video_signal_type_present_flag equal to 0, specifies that video_format, video_full_range_flag and colour_description_present_flag are not present. It is a requirement of bitstream conformance that, when nuh_layer_id is greater than 0, video_signal_type_present_flag shall be equal to 0.

When a current picture with nuh_layer_id layerIdCurr greater than 0 refers to an SPS containing the VUI parameter syntax structure, the values of video_format, video_full_range_flag, colour_primaries, transfer_characteristics, and matrix_coeffs are inferred as follows:

– If the nuh_layer_id of the active SPS for the layer with nuh_layer_id equal to layerIdCurr is equal to 0, the values of video_format, video_full_range_flag, colour_primaries, transfer_characteristics, and matrix_coeffs are inferred to be equal to video_vps_format, video_full_range_vps_flag, colour_primaries_vps, transfer_characteristics_vps, and matrix_coeffs_vps, respectively, of the vps_video_signal_info_idx[j]-th video_signal_info( ) syntax structure in the active VPS where j is equal to LayerIdxInVps[layerIdCurr] and the values of video_format, video_full_range_flag, colour_primaries, transfer_characteristics, and matrix_coeffs of the active SPS for the layer with nuh_layer_id equal to layerIdCurr are ignored.

  NOTE – The values are inferred from the VPS when a non-base layer refers to an SPS that is also referred to by the base layer, in which case the SPS has nuh_layer_id equal to 0. For the base layer, the values of these parameters in the active SPS for the base layer apply.

– Otherwise (the nuh_layer_id of the active SPS for the layer with nuh_layer_id equal to layerIdCurr is greater than zero), values of video_format, video_full_range_flag, colour_primaries, transfer_characteristics, and matrix_coeffs are inferred to be equal to video_vps_format, video_full_range_vps_flag, colour_primaries_vps, transfer_characteristics_vps, and matrix_coeffs_vps, respectively, of the vps_video_signal_info_idx[j]-th video_signal_info( ) syntax structure in the active VPS, where j is equal to LayerIdxInVps[layerIdCurr].

[Ed. (GT) Consider shortening duplicated inference specification above. What should happen when VPS VUI is not present?]

E.3.2 HRD parameters semantics

The specifications in clause E.3.2 apply with the following modifications and additions.

initial_cpb_removal_delay_length_minus1 plus 1 specifies the length, in bits, of the nal_initial_cpb_removal_delay[i], nal_initial_cpb_removal_offset[i], vcl_initial_cpb_removal_delay[i], and vcl_initial_cpb_removal_offset[i] syntax elements of the buffering period SEI message. Additionally, initial_cpb_removal_delay_length_minus1 plus 1 within the j-th hrd_parameters( ) syntax structure in the VPS specifies the length, in bits, of the nal_initial_arrival_delay[i] and vcl_initial_arrival_delay[i] syntax elements of the bitstream partition initial arrival time SEI message that is contained in a bitstream partition nesting SEI message within a scalable nesting SEI message with nesting_op_idx[0] equal to hrd_layer_set_idx[j]. When the initial_cpb_removal_delay_length_minus1 syntax element is not present, it is inferred to be equal to 23.

Annex F

Common specifications for multi-layer extensions

(This annex forms an integral part of this Recommendation | International Standard)

This annex specifies the common syntax, semantics and decoding processes for multi-layer video coding extensions.

F.1 Scope

Common syntax, semantics and decoding processes for multi-layer video coding extensions are specified in this annex with reference made to clauses 2-9 and Annexes A-E and G.

F.2 Normative references

The specifications in clause 2 apply with the following additions to subclause 2.4:

– ISO/IEC 10646:2003, *Information technology − Universal Multiple-Octet Coded Character Set (UCS)*.

F.3 Definitions

[Ed. (JO): Could be better to add this directly in clause 3. This can still be done with the new edition.]

For the purpose of this annex, the following definitions apply in addition to the definitions in clause 3. These definitions are either not present in clause 3 or replace definitions in clause 3.

[Ed. (YK&MH&CY): Definitions should be checked and potentially refined, including: BLA AU, IDR AU, CRA AU, output order, picture order count, RADL AU, RASL AU, (reference picture), STSA AU, TSA AU.]

F.3.1 **additional layer set**: a set of *layers* of a *bitstream* with a set of *layers* of one or more *non-base layer subtrees*.

F.3.2 **alternative output layer**: A *layer* that is a *direct reference layer* or an *indirect reference layer* of an *output layer* and which may include a *picture* that may be output when no picture of the *output layer* is present in the *access unit* containing the *picture*.

F.3.3 **associated IRAP picture:** The previous *IRAP picture* in *decoding order* within the same *layer* (if present).

F.3.4 **auxiliary picture**: A *picture* that has no normative effect on the *decoding process* of *primary pictures*, and with a nuh_layer_id value such that AuxId[nuh_layer_id] is greater than 0.

F.3.5 **auxiliary picture layer**: a *layer* with a nuh_layer_id value such that AuxId[nuh_layer_id] is greater than 0.

F.3.6 **base layer:** A *layer* in which all *VCL NAL units* have nuh_layer_id equal to 0.

F.3.7 **coded picture:** A *coded representation* of a *picture* comprising *VCL NAL units* with a particular value of nuh_layer_id within an *access unit* and containing all *coding tree units* of the *picture*. [Ed. (CY): consider defining picture by associating nuh_layer_id. In HEVC base, picture is defined as arrays of luma and chroma samples, however, it is often associated with other properties, e.g., coding tree units. So to be absolutely precise, it might be clearer and applicable to define picture as follows: *picture*: An array of *luma* samples in monochrome format or an array of *luma* samples and two corresponding arrays of *chroma* samples in 4:2:0, 4:2:2, and 4:4:4 colour format with the same value of nuh_layer_id.]

F.3.8 **coded video sequence (CVS):** A sequence of *access units* that consists, in decoding order, of an *initial IRAP access unit*, followed by zero or more *access units* that are not *initial IRAP access units*, including all subsequent *access units* up to but not including any subsequent *access unit* that is an *initial IRAP access unit*.

F.3.9 **collocated sample:** A sample TBD. [Ed. (GT) Maybe it is easier to define a collocated position and require collocated samples to have it?]

F.3.10 **cross-layer random access skip (CL-RAS) picture**: a *picture* with nuh_layer_id equal to layerId such that LayerInitializedFlag[layerId] is equal to 0 when the decoding process for starting the decoding of a coded picture with nuh_layer_id greater than 0 is invoked.

F.3.11 **direct predicted layer**: A *layer* for which another *layer* is a *direct reference layer*.

F.3.12 **direct reference layer:** A *layer* that may be used for inter-layer prediction of another *layer*.

F.3.13 **independent layer**: a *layer* that does not have *direct reference layers.*

F.3.14 **indirect predicted layer**: A *layer* for which another *layer* is an *indirect reference layer*.

F.3.15 **indirect reference layer:** A *layer* that is not a *direct reference layer* of a second *layer* but is a *direct reference layer* of a third *layer* that is a *direct reference layer* or indirect reference *layer* of a *direct reference layer* of the second *layer*.

F.3.16 **initial intra random access point (IRAP) access unit**: An *IRAP access unit* in which the *coded picture* with nuh_layer_id equal to 0 has NoRaslOutputFlag equal to 1.

F.3.17 **inter-layer prediction:** A *prediction* in a manner that is dependent on data elements (e.g. sample values or motion vectors) of *reference pictures* with a different value of nuh_layer_id than that of the current *picture*.

F.3.18 **intra random access point (IRAP) access unit**: An *access unit* in which the *coded picture* with nuh_layer_id equal to 0 is an *IRAP picture*.

F.3.19 **layer subtree**: a subset of the *layers* of a *layer tree* including all the *direct and indirect reference layers* of the *layers* within the subset.

F.3.20 **layer tree**: A set of *layers* such that each *layer* in the set of *layers* is a *direct or indirected predicted layer* or a *direct or indirect reference layer* of at least one other *layer* in the set of *layers* and no *layer* outside the set of *layers* is a *direct or indirected predicted layer* or a *direct or indirect reference layer* of any *layer* in the set of *layers*.

F.3.21 **leading picture:** A *picture* that is in the same *layer* as the *associated IRAP picture* and precedes the *associated IRAP picture* in *output order*.

F.3.22 **non-base layer:** A *layer* in which all *VCL NAL units* have the same nuh_layer_id value greater than 0.

F.3.23 **non-base layer subtree**: a *layer subtree* that does not include the *base layer*.

F.3.24 **picture order count (POC):** A variable that is associated with each *picture* and that uniquely identifies the associated *picture* among all *pictures* with the same value of nuh_layer_id in the *CVS*, and, when the associated *picture* is to be output from the *decoded picture buffer*, indicates the position of the associated *picture* in *output order* relative to the *output order* positions of the other *pictures* with the same value of nuh_layer_id in the same *CVS* that are to be output from the *decoded picture buffer*.

F.3.25 **picture order count (POC) resetting period:** A sequence of access units in decoding order, starting with an access unit with poc_reset_idc equal to 1 or 2 and a particular value of poc_reset_period_id and including all access units that either have the same value of poc_reset_period_id or have poc_reset_idc equal to 0.

F.3.26 **picture order count (POC) resetting picture:** A picture that is the first picture, in decoding order, of a layer of a POC resetting period.

F.3.27 **primary picture**: a *picture* with nuh_layer_id value such that AuxId[nuh_layer_id] is equal to 0.

F.3.28 **primary picture layer**: a *layer* with a nuh_layer_id value such that AuxId[nuh_layer_id] is equal to 0.

F.3.29 **reference layer picture:** A *picture* in a *direct reference layer* which is used for inter-layer prediction of the current *picture* and is in the same access unit as the *current picture*.

F.3.30 **reference picture list:** A list of reference pictures that is used for inter prediction or inter-layer prediction of a P or B slice.

F.3.31 **trailing picture:** A *picture* that is in the same *layer* as the *associated IRAP picture* and follows the *associated IRAP picture* in *output order*.

F.3.32 **output time:** A time when a *decoded picture* is to be output as specified in Annex C, if the timing information is present in the *coded video sequence*. [Ed.: Consider adding this definition in clause 3 of the main specification containing both version 1 and Annex F specifications.]

F.3.33 **view:** A sequence of pictures associated with the same value of ViewOrderIdx.

NOTE – A view typically represents a sequence of pictures captured by one camera.

F.4 Abbreviations

The specifications in clause 4 apply.

F.5 Conventions

The specifications in clause 5 apply.

F.6 Source, coded, decoded and output data formats, scanning processes, and neighbouring relationships

The specifications in clause 6 apply.

F.7 Syntax and semantics

This clause specifies syntax and semantics for CVSs that conform to one or more of the profiles specified in this annex.

F.7.1 Method of specifying syntax in tabular form

The specifications in subclause 7.1 apply.

F.7.2 Specification of syntax functions, categories, and descriptors

The specifications in subclause 7.2 apply, with the following additions:

– st(v): null-terminated string encoded in UTF-8 characters. The parsing process is specified as follows: st(v) reads and returns the next set of bytes from the bitstream until, exclusive, the next byte that is equal to 0x00, and advances the bitstream pointer by (stringLength + 1) * 8 bit positions, where stringLength is equal to the number of bytes returned..

more_data_in_slice_segment_header_extension( ) is specified as follows:

– If (the current position in the slice_segment_header( ) syntax structure) − (the position immediately following slice_segment_header_extension_length) is less than (slice_segment_header_extension_length * 8), the return value of more_data_in_slice_segment_header_extension( ) is equal to TRUE.

– Otherwise, the return value of more_data_in_slice_segment_header_extension( ) is equal to FALSE.

F.7.3 Syntax in tabular form

F.7.3.1 NAL unit syntax

The specifications in subclause 7.3.1 apply.

F.7.3.1.1 General NAL unit syntax

The specifications in subclause 7.3.1.1 apply.

F.7.3.1.2 NAL unit header syntax

The specifications in subclause 7.3.1.2 apply.

F.7.3.2 Raw byte sequence payloads and RBSP trailing bits syntax

F.7.3.2.1 Video parameter set RBSP

video_parameter_set_rbsp( ) {	**Descriptor**
vps_video_parameter_set_id	u(4)
vps_base_layer_internal_flag	u(1)
vps_reserved_one_bit	u(1)
vps_max_layers_minus1	u(6)
vps_max_sub_layers_minus1	u(3)
vps_temporal_id_nesting_flag	u(1)
vps_reserved_0xffff_16bits	u(16)
profile_tier_level(1, vps_max_sub_layers_minus1)	
vps_sub_layer_ordering_info_present_flag	u(1)
for(i = (vps_sub_layer_ordering_info_present_flag ? 0 : vps_max_sub_layers_minus1); i <= vps_max_sub_layers_minus1; i++) {	
vps_max_dec_pic_buffering_minus1[i]	ue(v)
vps_max_num_reorder_pics[i]	ue(v)
vps_max_latency_increase_plus1[i]	ue(v)
}	
vps_max_layer_id	u(6)
vps_num_layer_sets_minus1	ue(v)
for(i = 1; i <= vps_num_layer_sets_minus1; i++)	
for(j = 0; j <= vps_max_layer_id; j++)	
layer_id_included_flag[i][j]	u(1)
vps_timing_info_present_flag	u(1)
if(vps_timing_info_present_flag) {	
vps_num_units_in_tick	u(32)
vps_time_scale	u(32)
vps_poc_proportional_to_timing_flag	u(1)
if(vps_poc_proportional_to_timing_flag)	
vps_num_ticks_poc_diff_one_minus1	ue(v)
vps_num_hrd_parameters	ue(v)
for(i = 0; i < vps_num_hrd_parameters; i++) {	
hrd_layer_set_idx[i]	ue(v)
if(i > 0)	
cprms_present_flag[i]	u(1)
hrd_parameters(cprms_present_flag[i], vps_max_sub_layers_minus1)	
}	
}	
vps_extension_flag	u(1)
if(vps_extension_flag) {	
while(!byte_aligned( ))	
vps_extension_alignment_bit_equal_to_one	u(1)

vps_extension( )	
vps_extension2_flag	u(1)
if(vps_extension2_flag)	
while(more_rbsp_data( ))	
vps_extension_data_flag	u(1)
}	
rbsp_trailing_bits( )	
}	

F.7.3.2.1.1 Video parameter set extension syntax

vps_extension( ) {	Descriptor
splitting_flag	u(1)
for(i = 0, NumScalabilityTypes = 0; i < 16; i++) {	
scalability_mask_flag[i]	u(1)
NumScalabilityTypes += scalability_mask_flag[i]	
}	
for(j = 0; j < (NumScalabilityTypes − splitting_flag); j++)	
dimension_id_len_minus1[j]	u(3)
vps_nuh_layer_id_present_flag	u(1)
for(i = 1; i <= MaxLayersMinus1; i++) {	
if(vps_nuh_layer_id_present_flag)	
layer_id_in_nuh[i]	u(6)
if(!splitting_flag)	
for(j = 0; j < NumScalabilityTypes; j++)	
dimension_id[i][j]	u(v)
}	
view_id_len	u(4)
if(view_id_len > 0)	
for(i = 0; i < NumViews; i++)	
view_id_val[i]	u(v)
for(i = 1; i <= MaxLayersMinus1; i++)	
for(j = 0; j < i; j++)	
direct_dependency_flag[i][j]	u(1)
vps_sub_layers_max_minus1_present_flag	u(1)
if(vps_sub_layers_max_minus1_present_flag)	
for(i = 0; i <= MaxLayersMinus1; i++)	
sub_layers_vps_max_minus1[i]	u(3)
max_tid_ref_present_flag	u(1)
if(max_tid_ref_present_flag)	
for(i = 0; i < MaxLayersMinus1; i++)	
for(j = i + 1; j <= MaxLayersMinus1; j++)	
if(direct_dependency_flag[j][i])	
max_tid_il_ref_pics_plus1[i][j]	u(3)
all_ref_layers_active_flag	u(1)
vps_num_profile_tier_level_minus1	ue(v)
for(ptlIdx = 1; ptlIdx <= vps_num_profile_tier_level_minus1; ptlIdx ++) {	
vps_profile_present_flag[ptlIdx]	u(1)
profile_tier_level(vps_profile_present_flag[ptlIdx], vps_max_sub_layers_minus1)	
}	
if(NumIndependentLayers > 1)	
num_add_layer_sets	ue(v)
for(i = 0; i < num_add_layer_sets; i++)	
for(j = 1; j < NumIndependentLayers; j++)	
highest_layer_idx_plus1[i][j]	u(v)
if(NumLayerSets > 1) {	
num_add_olss	ue(v)

default_output_layer_idc	u(2)
}	
NumOutputLayerSets = num_add_olss + NumLayerSets	
for(i = 1; i < NumOutputLayerSets; i++) {	
if(i >= NumLayerSets)	
layer_set_idx_for_ols_minus1[i]	u(v)
if(i > vps_num_layer_sets_minus1 || defaultOutputLayerIdc == 2)	
for(j = 0; j < NumLayersInIdList[OlsIdxToLsIdx[i]]; j++)	
output_layer_flag[i][j]	u(1)
profile_level_tier_idx[i]	u(v)
if(NumOutputLayersInOutputLayerSet[i] == 1 && NumDirectRefLayers[OlsHighestOutputLayerId[i]] > 0)	
alt_output_layer_flag[i]	u(1)
}	
vps_num_rep_formats_minus1	ue(v)
for(i = 0; i <= vps_num_rep_formats_minus1; i++)	
rep_format( )	
if(vps_num_rep_formats_minus1 > 0)	
rep_format_idx_present_flag	u(1)
if(rep_format_idx_present_flag)	
for(i = vps_base_layer_internal_flag ? 1 : 0; i <= MaxLayersMinus1; i++)	
vps_rep_format_idx[i]	u(v)
max_one_active_ref_layer_flag	u(1)
vps_poc_lsb_aligned_flag	u(1)
for(i = 1; i <= MaxLayersMinus1; i++)	
if(NumDirectRefLayers[layer_id_in_nuh[i]] == 0)	
poc_lsb_not_present_flag[i]	u(1)
vps_reserved_zero_flag	u(1)
dpb_size( )	
direct_dep_type_len_minus2	ue(v)
default_direct_dependency_flag	u(1)
if(default_direct_dependency_flag)	
default_direct_dependency_type	u(v)
else {	
for(i = vps_base_layer_internal_flag ? 1 : 2; i <= MaxLayersMinus1; i++)	
for(j = vps_base_layer_internal_flag ? 0 : 1; j < i; j++)	
if(direct_dependency_flag[i][j])	
direct_dependency_type[i][j]	u(v)
}	
vps_non_vui_extension_length	ue(v)
for(i = 1; i <= vps_non_vui_extension_length; i++)	
vps_non_vui_extension_data_byte	u(8)
vps_vui_present_flag	u(1)
if(vps_vui_present_flag) {	
while(!byte_aligned( ))	
vps_vui_alignment_bit_equal_to_one	u(1)
vps_vui( )	
}	
}	

F.7.3.2.1.2 Representation format syntax

[Ed. (YK): The syntax and semantics for rep_format( ), dpb_size( ), and vps_vui( ) should probably have one-level-higher section titles, similarly as profile_tier_level( ).]

rep_format( ) {	Descriptor
pic_width_vps_in_luma_samples	u(16)
pic_height_vps_in_luma_samples	u(16)
chroma_and_bit_depth_vps_present_flag	u(1)
if(chroma_and_bit_depth_vps_present_flag) {	
chroma_format_vps_idc	u(2)
if(chroma_format_vps_idc = = 3)	
separate_colour_plane_vps_flag	u(1)
bit_depth_vps_luma_minus8	u(4)
bit_depth_vps_chroma_minus8	u(4)
}	
}	

F.7.3.2.1.3 DPB size syntax

dpb_size( ) {	
for(i = 1; i < NumOutputLayerSets; i++) {	
currLsIdx = OlsIdxToLsIdx[i]	
sub_layer_flag_info_present_flag[i]	u(1)
for(j = 0; j <= MaxSubLayersInLayerSetMinus1[currLsIdx]; j++) {	
if(j > 0 && sub_layer_flag_info_present_flag[i])	
sub_layer_dpb_info_present_flag[i][j]	u(1)
if(sub_layer_dpb_info_present_flag[i][j]) {	
for(k = 0; k < NumLayersInIdList[currLsIdx]; k++)	
max_vps_dec_pic_buffering_minus1[i][k][j]	ue(v)
max_vps_num_reorder_pics[i][j]	ue(v)
max_vps_latency_increase_plus1[i][j]	ue(v)
}	
}	
}	
}	

F.7.3.2.1.4 VPS VUI syntax

vps_vui( ){	Descriptor
cross_layer_pic_type_aligned_flag	u(1)
if(!cross_layer_pic_type_aligned_flag)	
cross_layer_irap_aligned_flag	u(1)
if(cross_layer_irap_aligned_flag)	
all_layers_idr_aligned_flag	u(1)
bit_rate_present_vps_flag	u(1)
pic_rate_present_vps_flag	u(1)
if(bit_rate_present_vps_flag || pic_rate_present_vps_flag)	
for(i = vps_base_layer_internal_flag ? 0 : 1; i <= vps_num_layer_sets_minus1; i++)	
for(j = 0; j <= MaxSubLayersInLayerSetMinus1[i]; j++) {	
if(bit_rate_present_vps_flag)	
bit_rate_present_flag[i][j]	u(1)
if(pic_rate_present_vps_flag)	
pic_rate_present_flag[i][j]	u(1)
if(bit_rate_present_flag[i][j]) {	
avg_bit_rate[i][j]	u(16)
max_bit_rate[i][j]	u(16)
}	
if(pic_rate_present_flag[i][j]) {	
constant_pic_rate_idc[i][j]	u(2)
avg_pic_rate[i][j]	u(16)
}	
}	
video_signal_info_idx_present_flag	u(1)
if(video_signal_info_idx_present_flag)	
vps_num_video_signal_info_minus1	u(4)
for(i = 0; i <= vps_num_video_signal_info_minus1; i++)	
video_signal_info( )	
if(video_signal_info_idx_present_flag && vps_num_video_signal_info_minus1 > 0)	
for(i = 1; i <= MaxLayersMinus1; i++)	
vps_video_signal_info_idx[i]	u(4)
tiles_not_in_use_flag	u(1)
if(!tiles_not_in_use_flag) {	
for(i = vps_base_layer_internal_flag ? 0 : 1; i <= MaxLayersMinus1; i++) {	
tiles_in_use_flag[i]	u(1)
if(tiles_in_use_flag[i])	
loop_filter_not_across_tiles_flag[i]	u(1)
}	
for(i = vps_base_layer_internal_flag ? 1 : 2; i <= MaxLayersMinus1; i++)	
for(j = 0; j < NumDirectRefLayers[layer_id_in_nuh[i]]; j++) {	
layerIdx = LayerIdxInVps[RefLayerId[layer_id_in_nuh[i]][j]]	
if(tiles_in_use_flag[i] && tiles_in_use_flag[layerIdx])	
tile_boundaries_aligned_flag[i][j]	u(1)
}	
}	

wpp_not_in_use_flag	u(1)
if(!wpp_not_in_use_flag)	
for(i = vps_base_layer_internal_flag ? 0 : 1; i <= MaxLayersMinus1; i++)	
wpp_in_use_flag[i]	u(1)
vps_vui_reserved_zero_3bits	u(3)
ilp_restricted_ref_layers_flag	u(1)
if(ilp_restricted_ref_layers_flag)	
for(i = 1; i <= MaxLayersMinus1; i++)	
for(j = 0; j < NumDirectRefLayers[layer_id_in_nuh[i]]; j++)	
if(vps_base_layer_internal_flag || RefLayerId[layer_id_in_nuh[i]][j] > 0) {	
min_spatial_segment_offset_plus1[i][j]	ue(v)
if(min_spatial_segment_offset_plus1[i][j] > 0) {	
ctu_based_offset_enabled_flag[i][j]	u(1)
if(ctu_based_offset_enabled_flag[i][j])	
min_horizontal_ctu_offset_plus1[i][j]	ue(v)
}	
}	
vps_vui_bsp_hrd_present_flag	u(1)
if(vps_vui_bsp_hrd_present_flag)	
vps_vui_bsp_hrd_parameters( )	
for(i = 1; i <= MaxLayersMinus1; i++)	
if(NumDirectRefLayers[layer_id_in_nuh[i]] == 0)	
base_layer_parameter_set_compatibility_flag[i]	u(1)
}	

F.7.3.2.1.5 Video signal info syntax

video_signal_info( ) {	**Descriptor**
video_vps_format	u(3)
video_full_range_vps_flag	u(1)
colour_primaries_vps	u(8)
transfer_characteristics_vps	u(8)
matrix_coeffs_vps	u(8)
}	

F.7.3.2.1.6 VPS VUI bitstream partition HRD parameters syntax

vps_vui_bsp_hrd_parameters( ){	**Descriptor**
vps_num_bsp_hrd_parameters_minus1	ue(v)
for(i = 0; i <= vps_num_bsp_hrd_parameters_minus1; i++) {	
if(i > 0)	
bsp_cprms_present_flag[i]	u(1)
hrd_parameters(bsp_cprms_present_flag[i], vps_max_sub_layers_minus1)	
}	
for(h = 1; h <= vps_num_layer_sets_minus1; h++) {	
num_bitstream_partitions[h]	ue(v)
for(i = 0; i < num_bitstream_partitions[h]; i++)	
for(j = 0; j < NumLayersInIdList[h]; j++)	
layer_in_bsp_flag[h][i][j]	u(1)
if(num_bitstream_partitions[h] > 0) {	
num_bsp_sched_combinations_minus1[h]	ue(v)
for(i = 0; i <= num_bsp_sched_combinations_minus1[h]; i++)	
for(j = 0; j < num_bitstream_partitions[h]; j++) {	
bsp_comb_hrd_idx[h][i][j]	u(v)
bsp_comb_sched_idx[h][i][j]	ue(v)
}	
}	
}	
}	

F.7.3.2.2 Sequence parameter set RBSP syntax

seq_parameter_set_rbsp( ) {	Descriptor
sps_video_parameter_set_id	u(4)
if(nuh_layer_id == 0) {	
sps_max_sub_layers_minus1	u(3)
sps_temporal_id_nesting_flag	u(1)
profile_tier_level(1, sps_max_sub_layers_minus1)	
}	
sps_seq_parameter_set_id	ue(v)
if(nuh_layer_id > 0) {	
update_rep_format_flag	u(1)
if(update_rep_format_flag)	
sps_rep_format_idx	u(8)
} else {	
chroma_format_idc	ue(v)
if(chroma_format_idc == 3)	
separate_colour_plane_flag	u(1)
pic_width_in_luma_samples	ue(v)
pic_height_in_luma_samples	ue(v)
}	
conformance_window_flag	u(1)
if(conformance_window_flag) {	
conf_win_left_offset	ue(v)
conf_win_right_offset	ue(v)
conf_win_top_offset	ue(v)
conf_win_bottom_offset	ue(v)
}	
if(nuh_layer_id == 0) {	
bit_depth_luma_minus8	ue(v)
bit_depth_chroma_minus8	ue(v)
}	
log2_max_pic_order_cnt_lsb_minus4	ue(v)
if(nuh_layer_id == 0) {	
sps_sub_layer_ordering_info_present_flag	u(1)
for(i = (sps_sub_layer_ordering_info_present_flag ? 0 : sps_max_sub_layers_minus1); i <= sps_max_sub_layers_minus1; i++) {	
sps_max_dec_pic_buffering_minus1[i]	ue(v)
sps_max_num_reorder_pics[i]	ue(v)
sps_max_latency_increase_plus1[i]	ue(v)
}	
}	
log2_min_luma_coding_block_size_minus3	ue(v)
log2_diff_max_min_luma_coding_block_size	ue(v)
log2_min_transform_block_size_minus2	ue(v)
log2_diff_max_min_transform_block_size	ue(v)
max_transform_hierarchy_depth_inter	ue(v)
max_transform_hierarchy_depth_intra	ue(v)
scaling_list_enabled_flag	u(1)

if(scaling_list_enabled_flag) {	
if(nuh_layer_id > 0)	
sps_infer_scaling_list_flag	u(1)
if(sps_infer_scaling_list_flag)	
sps_scaling_list_ref_layer_id	u(6)
else {	
sps_scaling_list_data_present_flag	u(1)
if(sps_scaling_list_data_present_flag)	
scaling_list_data( )	
}	
}	
amp_enabled_flag	u(1)
sample_adaptive_offset_enabled_flag	u(1)
pcm_enabled_flag	u(1)
if(pcm_enabled_flag) {	
pcm_sample_bit_depth_luma_minus1	u(4)
pcm_sample_bit_depth_chroma_minus1	u(4)
log2_min_pcm_luma_coding_block_size_minus3	ue(v)
log2_diff_max_min_pcm_luma_coding_block_size	ue(v)
pcm_loop_filter_disabled_flag	u(1)
}	
num_short_term_ref_pic_sets	ue(v)
for(i = 0; i < num_short_term_ref_pic_sets; i++)	
short_term_ref_pic_set(i)	
long_term_ref_pics_present_flag	u(1)
if(long_term_ref_pics_present_flag) {	
num_long_term_ref_pics_sps	ue(v)
for(i = 0; i < num_long_term_ref_pics_sps; i++) {	
lt_ref_pic_poc_lsb_sps[i]	u(v)
used_by_curr_pic_lt_sps_flag[i]	u(1)
}	
}	
sps_temporal_mvp_enabled_flag	u(1)
strong_intra_smoothing_enabled_flag	u(1)
vui_parameters_present_flag	u(1)
if(vui_parameters_present_flag)	
vui_parameters( )	
sps_extension_present_flag	u(1)
if(sps_extension_present_flag) {	
sps_range_extensions_flag	u(1)
sps_multilayer_extension_flag	u(1)
sps_extension_6bits	u(6)
}	
if(sps_range_extensions_flag)	
sps_range_extensions( )	
if(sps_multilayer_extension_flag)	
sps_multilayer_extension( )	
if(sps_extension_6bits)	

while(more_rbsp_data( ))	
sps_extension_data_flag	u(1)
rbsp_trailing_bits( )	
}	

F.7.3.2.2.1 Sequence parameter set multilayer extension syntax

sps_multilayer_extension( ) {	**Descriptor**
inter_view_mv_vert_constraint_flag	u(1)
num_scaled_ref_layer_offsets	ue(v)
for(i = 0; i < num_scaled_ref_layer_offsets; i++) {	
scaled_ref_layer_id[i]	u(6)
scaled_ref_layer_left_offset[scaled_ref_layer_id[i]]	se(v)
scaled_ref_layer_top_offset[scaled_ref_layer_id[i]]	se(v)
scaled_ref_layer_right_offset[scaled_ref_layer_id[i]]	se(v)
scaled_ref_layer_bottom_offset[scaled_ref_layer_id[i]]	se(v)
sps_multilayer_ext_reserved_zero_flag[scaled_ref_layer_id[i]]	u(1)
}	
}	

F.7.3.2.3 Picture parameter set RBSP syntax

pic_parameter_set_rbsp( ) {	**Descriptor**
pps_pic_parameter_set_id	ue(v)
pps_seq_parameter_set_id	ue(v)
dependent_slice_segments_enabled_flag	u(1)
output_flag_present_flag	u(1)
num_extra_slice_header_bits	u(3)
sign_data_hiding_enabled_flag	u(1)
cabac_init_present_flag	u(1)
num_ref_idx_l0_default_active_minus1	ue(v)
num_ref_idx_l1_default_active_minus1	ue(v)
init_qp_minus26	se(v)
constrained_intra_pred_flag	u(1)
transform_skip_enabled_flag	u(1)
cu_qp_delta_enabled_flag	u(1)
if(cu_qp_delta_enabled_flag)	
diff_cu_qp_delta_depth	ue(v)
pps_cb_qp_offset	se(v)
pps_cr_qp_offset	se(v)
pps_slice_chroma_qp_offsets_present_flag	u(1)
weighted_pred_flag	u(1)
weighted_bipred_flag	u(1)
transquant_bypass_enabled_flag	u(1)
tiles_enabled_flag	u(1)
entropy_coding_sync_enabled_flag	u(1)
if(tiles_enabled_flag) {	
num_tile_columns_minus1	ue(v)
num_tile_rows_minus1	ue(v)
uniform_spacing_flag	u(1)
if(!uniform_spacing_flag) {	
for(i = 0; i < num_tile_columns_minus1; i++)	
column_width_minus1[i]	ue(v)
for(i = 0; i < num_tile_rows_minus1; i++)	
row_height_minus1[i]	ue(v)
}	
loop_filter_across_tiles_enabled_flag	u(1)
}	
pps_loop_filter_across_slices_enabled_flag	u(1)
deblocking_filter_control_present_flag	u(1)
if(deblocking_filter_control_present_flag) {	
deblocking_filter_override_enabled_flag	u(1)
pps_deblocking_filter_disabled_flag	u(1)
if(!pps_deblocking_filter_disabled_flag) {	
pps_beta_offset_div2	se(v)
pps_tc_offset_div2	se(v)
}	
}	

if(nuh_layer_id > 0)	
pps_infer_scaling_list_flag	u(1)
if(pps_infer_scaling_list_flag)	
pps_scaling_list_ref_layer_id	u(6)
else {	
pps_scaling_list_data_present_flag	u(1)
if(pps_scaling_list_data_present_flag)	
scaling_list_data( )	
}	
lists_modification_present_flag	u(1)
log2_parallel_merge_level_minus2	ue(v)
slice_segment_header_extension_present_flag	u(1)
pps_extension_present_flag	u(1)
if(pps_extension_present_flag) {	
pps_range_extensions_flag	u(1)
pps_multilayer_extension_flag	u(1)
pps_extension_6bits	u(6)
}	
if(pps_range_extensions_flag)	
pps_range_extensions( )	
if(pps_multilayer_extension_flag) {	
poc_reset_info_present_flag	u(1)
pps_extension_reserved_zero_flag	u(1)
}	
if(pps_extension_6bits)	
while(more_rbsp_data( ))	
pps_extension_data_flag	u(1)
rbsp_trailing_bits( )	
}	

F.7.3.2.4 Supplemental enhancement information RBSP syntax

The specifications in subclause 7.3.2.4 apply.

F.7.3.2.5 Access unit delimiter RBSP syntax

The specifications in subclause 7.3.2.5 apply.

F.7.3.2.6 End of sequence RBSP syntax

The specifications in subclause 7.3.2.6 apply.

F.7.3.2.7 End of bitstream RBSP syntax

The specifications in subclause 7.3.2.7 apply.

F.7.3.2.8 Filler data RBSP syntax

The specifications in subclause 7.3.2.8 apply.

F.7.3.2.9 Slice segment layer RBSP syntax

The specifications in subclause 7.3.2.9 apply.

F.7.3.2.10 RBSP slice segment trailing bits syntax

The specifications in subclause 7.3.2.10 apply.

F.7.3.2.11 RBSP trailing bits syntax

The specifications in subclause 7.3.2.11 apply.

F.7.3.2.12 Byte alignment syntax

The specifications in subclause 7.3.2.12 apply.

F.7.3.3 Profile, tier and level syntax

profile_tier_level(profilePresentFlag, maxNumSubLayersMinus1) {	**Descriptor**
if(profilePresentFlag) {	
general_profile_space	u(2)
general_tier_flag	u(1)
general_profile_idc	u(5)
for(j = 0; j < 32; j++)	
general_profile_compatibility_flag[j]	u(1)
general_progressive_source_flag	u(1)
general_interlaced_source_flag	u(1)
general_non_packed_constraint_flag	u(1)
general_frame_only_constraint_flag	u(1)
general_reserved_zero_44bits	u(44)
}	
general_level_idc	u(8)
for(i = 0; i < maxNumSubLayersMinus1; i++) {	
sub_layer_profile_present_flag[i]	u(1)
sub_layer_level_present_flag[i]	u(1)
}	
if(maxNumSubLayersMinus1 > 0)	
for(i = maxNumSubLayersMinus1; i < 8; i++)	
reserved_zero_2bits[i]	u(2)
for(i = 0; i < maxNumSubLayersMinus1; i++) {	
if(sub_layer_profile_present_flag[i]) {	
sub_layer_profile_space[i]	u(2)
sub_layer_tier_flag[i]	u(1)
sub_layer_profile_idc[i]	u(5)
for(j = 0; j < 32; j++)	
sub_layer_profile_compatibility_flag[i][j]	u(1)
sub_layer_progressive_source_flag[i]	u(1)
sub_layer_interlaced_source_flag[i]	u(1)
sub_layer_non_packed_constraint_flag[i]	u(1)
sub_layer_frame_only_constraint_flag[i]	u(1)
sub_layer_reserved_zero_44bits[i]	u(44)
}	
if(sub_layer_level_present_flag[i])	
sub_layer_level_idc[i]	u(8)
}	
}	

F.7.3.4 Scaling list data syntax

The specifications in subclause 7.3.4 apply.

F.7.3.5 Supplemental enhancement information message syntax

The specifications in subclause 7.3.5 apply.

F.7.3.6 Slice segment header syntax

F.7.3.6.1 General slice segment header syntax

slice_segment_header( ) {	**Descriptor**
first_slice_segment_in_pic_flag	u(1)
if(nal_unit_type >= BLA_W_LP && nal_unit_type <= RSV_IRAP_VCL23)	
no_output_of_prior_pics_flag	u(1)
slice_pic_parameter_set_id	ue(v)
if(!first_slice_segment_in_pic_flag) {	
if(dependent_slice_segments_enabled_flag)	
dependent_slice_segment_flag	u(1)
slice_segment_address	u(v)
}	
if(!dependent_slice_segment_flag) {	
i = 0	
if(num_extra_slice_header_bits > i) {	
i++	
discardable_flag	u(1)
}	
if(num_extra_slice_header_bits > i) {	
i++	
cross_layer_bla_flag	u(1)
}	
for(~~i = 1~~; i < num_extra_slice_header_bits; i++)	
slice_reserved_flag[i]	u(1)
slice_type	ue(v)
if(output_flag_present_flag)	
pic_output_flag	u(1)
if(separate_colour_plane_flag = = 1)	
colour_plane_id	u(2)
if((nuh_layer_id > 0 && !poc_lsb_not_present_flag[LayerIdxInVPS[nuh_layer_id]]) || (nal_unit_type != IDR_W_RADL && nal_unit_type != IDR_N_LP))	
slice_pic_order_cnt_lsb	u(v)
if(nal_unit_type != IDR_W_RADL && nal_unit_type != IDR_N_LP) {	
short_term_ref_pic_set_sps_flag	u(1)
if(!short_term_ref_pic_set_sps_flag)	
short_term_ref_pic_set(num_short_term_ref_pic_sets)	
else if(num_short_term_ref_pic_sets > 1)	
short_term_ref_pic_set_idx	u(v)
if(long_term_ref_pics_present_flag) {	
if(num_long_term_ref_pics_sps > 0)	
num_long_term_sps	ue(v)
num_long_term_pics	ue(v)
for(i = 0; i < num_long_term_sps + num_long_term_pics; i++) {	
if(i < num_long_term_sps) {	
if(num_long_term_ref_pics_sps > 1)	
lt_idx_sps[i]	u(v)
} else {	

poc_lsb_lt[i]	u(v)
used_by_curr_pic_lt_flag[i]	u(1)
}	
delta_poc_msb_present_flag[i]	u(1)
if(delta_poc_msb_present_flag[i])	
delta_poc_msb_cycle_lt[i]	ue(v)
}	
}	
if(sps_temporal_mvp_enabled_flag)	
slice_temporal_mvp_enabled_flag	u(1)
}	
if(nuh_layer_id > 0 && !all_ref_layers_active_flag && NumDirectRefLayers[nuh_layer_id] > 0) {	
inter_layer_pred_enabled_flag	u(1)
if(inter_layer_pred_enabled_flag && NumDirectRefLayers[nuh_layer_id] > 1) {	
if(!max_one_active_ref_layer_flag)	
num_inter_layer_ref_pics_minus1	u(v)
if(NumActiveRefLayerPics != NumDirectRefLayers[nuh_layer_id])	
for(i = 0; i < NumActiveRefLayerPics; i++)	
inter_layer_pred_layer_idc[i]	u(v)
}	
}	
if(sample_adaptive_offset_enabled_flag) {	
slice_sao_luma_flag	u(1)
slice_sao_chroma_flag	u(1)
}	
if(slice_type = = P || slice_type = = B) {	
num_ref_idx_active_override_flag	u(1)
if(num_ref_idx_active_override_flag) {	
num_ref_idx_l0_active_minus1	ue(v)
if(slice_type = = B)	
num_ref_idx_l1_active_minus1	ue(v)
}	
if(lists_modification_present_flag && NumPicTotalCurr > 1)	
ref_pic_lists_modification( )	
if(slice_type = = B)	
mvd_l1_zero_flag	u(1)
if(cabac_init_present_flag)	
cabac_init_flag	u(1)
if(slice_temporal_mvp_enabled_flag) {	
if(slice_type = = B)	
collocated_from_l0_flag	u(1)
if((collocated_from_l0_flag && num_ref_idx_l0_active_minus1 > 0) || (!collocated_from_l0_flag && num_ref_idx_l1_active_minus1 > 0))	
collocated_ref_idx	ue(v)
}	
if((weighted_pred_flag && slice_type = = P) || (weighted_bipred_flag && slice_type = = B))	
pred_weight_table( )	
five_minus_max_num_merge_cand	ue(v)

}	
slice_qp_delta	se(v)
if(pps_slice_chroma_qp_offsets_present_flag) {	
slice_cb_qp_offset	se(v)
slice_cr_qp_offset	se(v)
}	
if(deblocking_filter_override_enabled_flag)	
deblocking_filter_override_flag	u(1)
if(deblocking_filter_override_flag) {	
slice_deblocking_filter_disabled_flag	u(1)
if(!slice_deblocking_filter_disabled_flag) {	
slice_beta_offset_div2	se(v)
slice_tc_offset_div2	se(v)
}	
}	
if(pps_loop_filter_across_slices_enabled_flag && (slice_sao_luma_flag || slice_sao_chroma_flag || !slice_deblocking_filter_disabled_flag))	
slice_loop_filter_across_slices_enabled_flag	u(1)
}	
if(tiles_enabled_flag || entropy_coding_sync_enabled_flag) {	
num_entry_point_offsets	ue(v)
if(num_entry_point_offsets > 0) {	
offset_len_minus1	ue(v)
for(i = 0; i < num_entry_point_offsets; i++)	
entry_point_offset_minus1[i]	u(v)
}	
}	
if(slice_segment_header_extension_present_flag) {	
slice_segment_header_extension_length	ue(v)
if(poc_reset_info_present_flag)	
poc_reset_idc	u(2)
if(poc_reset_idc != 0)	
poc_reset_period_id	u(6)
if(poc_reset_idc = = 3) {	
full_poc_reset_flag	u(1)
poc_lsb_val	u(v)
}	
if(!PocMsbValRequiredFlag && vps_poc_lsb_aligned_flag)	
poc_msb_val_present_flag	u(1)
if(poc_msb_val_present_flag)	
poc_msb_val	ue(v)
while(more_data_in_slice_segment_header_extension( ))	
slice_segment_header_extension_data_bit	u(1)
}	
byte_alignment( )	
}	

F.7.3.6.2 Reference picture list modification syntax

The specifications in subclause 7.3.6.2 apply.

F.7.3.6.3 Weighted prediction parameters syntax

The specifications in subclause 7.3.6.3 apply.

F.7.3.7 Short-term reference picture set syntax

The specifications in subclause 7.3.7 apply.

F.7.3.8 Slice segment data syntax

F.7.3.8.1 General slice segment data syntax

The specifications in subclause 7.3.8.1 apply.

F.7.3.8.2 Coding tree unit syntax

The specifications in subclause 7.3.8.2 apply.

F.7.3.8.3 Sample adaptive offset syntax

The specifications in subclause 7.3.8.3 apply.

F.7.3.8.4 Coding quadtree syntax

The specifications in subclause 7.3.8.4 apply.

F.7.3.8.5 Coding unit syntax

The specifications in subclause 7.3.8.5 apply.

F.7.3.8.6 Prediction unit syntax

The specifications in subclause 7.3.8.6 apply.

F.7.3.8.7 PCM sample syntax

The specifications in subclause 7.3.8.7 apply.

F.7.3.8.8 Transform tree syntax

The specifications in subclause 7.3.8.8 apply.

F.7.3.8.9 Motion vector difference syntax

The specifications in subclause 7.3.8.9 apply.

F.7.3.8.10 Transform unit syntax

The specifications in subclause 7.3.8.10 apply.

F.7.3.8.11 Residual coding syntax

The specifications in subclause 7.3.8.11 apply.

F.7.4 Semantics

F.7.4.1 General

F.7.4.2 NAL unit semantics

F.7.4.2.1 General NAL unit semantics

The specifications in subclause 7.4.2.1 apply.

F.7.4.2.2 NAL unit header semantics

The specifications in subclause 7.4.2.2 apply with following modifications and additions.

nal_unit_type specifies the type of RBSP data structure contained in the NAL unit as specified in Table 7 1.

The variable CraOrBlaPicFlag is derived as follows:

CraOrBlaPicFlag = (nal_unit_type = = BLA_W_LP || nal_unit_type = = BLA_N_LP ||
nal_unit_type = = BLA_W_RADL || nal_unit_type = = CRA_NUT)

NOTE 1 – When a picture picA that is a CRA picture and belongs to a layer with nuh_layer_id equal to layerId is present in a bitstream and pictures belonging to the layer with nuh_layer_id equal to layerId and precede, in decoding order, the picture picA are dropped due to layer down-switching followed by layer up-switching, the RASL pictures associated with the picture picA, if any, may have some reference pictures that may not be available for reference unless one of the following conditions is true:

– The access unit auA containing the picture picA is an IRAP access unit, and the picture with nuh_layer_id equal to 0 in the access unit auA, if any, has NoClrasOutputFlag equal to 1.

– The value of HandleCraAsBlaFlag is equal to 1 for the CRA picture picA.

nuh_layer_id specifies the identifier of the layer. The value of nuh_layer_id shall be in the range of 0 to 62, inclusive. The value of 63 may be specified in the future by ITU-T | ISO/IEC. Decoders shall ignore all data that follow the value 63 for nuh_layer_id in a NAL unit.

NOTE 2 – It is anticipated that in a future super multiview coding extension of this specification, the value of 63 for nuh_layer_id will be used to indicate an extended layer identifier.

When nal_unit_type is equal to AUD_NUT, the value of nuh_layer_id shall be equal to the minimum of the nuh_layer_id values of all VCL NAL units in the access unit.

When nal_unit_type is equal to VPS_NUT, the value of nuh_layer_id shall be equal to 0. Decoders shall ignore NAL units with nal_unit_type equal to VPS_NUT and nuh_layer_id greater than 0. [Ed. (YK): Check the need of adding a wording like "Although the value of nuh_layer_id is required to be equal to 0 when nal_unit_type is equal to VPS_NUT in this version of this Specification, decoders shall allow other values of nuh_layer_id in the range of 0 to 62, inclusive, to appear in the syntax when nal_unit_type is equal to VPS_NUT."]

When nal_unit_type is equal to PPS_NUT and the NAL unit contains the active PPS for a layer layerA with nuh_layer_id equal to nuhLayerIdA, the value of nuh_layer_id shall be equal to 0, nuhLayerIdA, or the nuh_layer_id of a direct or indirect reference layer of layerA.

When nal_unit_type is equal to SPS_NUT and the NAL unit contains the active SPS for a layer layerA with nuh_layer_id equal to nuhLayerIdA, the value of nuh_layer_id shall be equal to 0, nuhLayerIdA, or the nuh_layer_id of a direct or indirect reference layer of layerA.

When nal_unit_type is equal to EOS_NUT, the value of nuh_layer_id shall be equal to 0. Decoders shall ignore (i.e. remove from the bitstream and discard) all NAL units with nal_unit type equal to EOS_NUT and nuh_layer_id greater than 0. [Ed. (YK): Check the need of adding the wording like "Although the value of nuh_layer_id is required to be equal to 0 when nal_unit_type is equal to EOB_NUT in this version of this Specification, decoders shall allow other values of nuh_layer_id in the range of 0 to 62, inclusive, to appear in the syntax when nal_unit_type is equal to EOB_NUT."]

When nal_unit_type is equal to EOB_NUT, the value of nuh_layer_id shall be equal to 0. Decoders shall ignore (i.e. remove from the bitstream and discard) all NAL units with nal_unit type equal to EOB_NUT and nuh_layer_id greater than 0. [Ed. (YK): Check the need of adding the wording like "Although the value of nuh_layer_id is required to be equal to 0 when nal_unit_type is equal to EOB_NUT in this version of this Specification, decoders shall allow other values of nuh_layer_id in the range of 0 to 62, inclusive, to appear in the syntax when nal_unit_type is equal to EOB_NUT."]

nuh_temporal_id_plus1 minus 1 specifies a temporal identifier for the NAL unit. The value of nuh_temporal_id_plus1 shall not be equal to 0.

The variable TemporalId is specified as follows:

$$TemporalId = nuh\_temporal\_id\_plus1 - 1 \quad (8\text{-}26)$$

If nal_unit_type is in the range of BLA_W_LP to RSV_IRAP_VCL23, inclusive, i.e. the coded slice segment belongs to an IRAP picture, TemporalId shall be equal to 0. Otherwise, if nal_unit_type is equal to TSA or TSA_N, TemporalId shall not be equal to 0. Otherwise, when nuh_layer_id is equal to 0 and nal_unit_type is equal to STSA_R or STSA_N, TemporalId shall not be equal to 0.

The value of TemporalId shall be the same for all VCL NAL units of an access unit. The value of TemporalId of an access unit is the value of the TemporalId of the VCL NAL units of the access unit.

The value of TemporalId for non-VCL NAL units is constrained as follows:

– If nal_unit_type is equal to VPS_NUT or SPS_NUT, TemporalId shall be equal to 0 and the TemporalId of the access unit containing the NAL unit shall be equal to 0.

– Otherwise if nal_unit_type is equal to EOS_NUT or EOB_NUT, TemporalId shall be equal to 0.

– Otherwise, if nal_unit_type is equal to AUD_NUT or FD_NUT, TemporalId shall be equal to the TemporalId of the access unit containing the NAL unit.

– Otherwise, TemporalId shall be greater than or equal to the TemporalId of the access unit containing the NAL unit.

NOTE 3 – When the NAL unit is a non-VCL NAL unit, the value of TemporalId is equal to the minimum value of the TemporalId values of all access units to which the non-VCL NAL unit applies. When nal_unit_type is equal to PPS_NUT, TemporalId may be greater than or equal to the TemporalId of the containing access unit, as all PPSs may be included in the beginning of a bitstream, wherein the first coded picture has TemporalId equal to 0. When nal_unit_type is equal to PREFIX_SEI_NUT or SUFFIX_SEI_NUT, TemporalId may be greater than or equal to the TemporalId of the containing access unit, as an SEI NAL unit may contain information, e.g. in a buffering period SEI message or a picture timing SEI message, that applies to a bitstream subset that includes access units for which the TemporalId values are greater than the TemporalId of the access unit containing the SEI NAL unit.

F.7.4.2.3 Encapsulation of an SODB within an RBSP (informative)

The specifications in subclause 7.4.2.3 apply.

F.7.4.2.4 Order of NAL units and association to coded pictures, access units, and coded video sequences

F.7.4.2.4.1 General

The specifications in subclause 7.4.2.4.1 apply with the following additions.

A coded picture with nuh_layer_id equal to nuhLayerIdA shall precede, in decoding order, all coded pictures with nuh_layer_id greater than nuhLayerIdA in the same access unit.

F.7.4.2.4.2 Order of VPS, SPS and PPS RBSPs and their activation

The specifications in subclause 7.4.2.4.2 apply with the following additions.

The contents of the hrd_parameters( ) syntax structure shall remain unchanged within a sequence of activated SPS RBSPs, in their activation order, from any activated SPS RBSP until the end of the bitstream or up to but excluding an SPS RBSP that is activated within the next access unit in which at least one of the following conditions is true:

– The access unit includes a picture for each nuh_layer_id value in TargetDecLayerIdList and each picture in the access unit is an IDR picture.

– The access unit includes an IRAP picture with nuh_layer_id equal to 0 for which NoClrasOutputFlag is equal to 1.

An activated VPS RBSP shall remain active until the end of the bitstream or until it is deactivated by another VPS RBSP in an access unit in which at least one of the following conditions is true:

– The access unit includes a picture for each nuh_layer_id value in TargetDecLayerIdList and each picture in the access unit is an IDR picture.

– The access unit includes an IRAP picture with nuh_layer_id equal to 0 for which NoClrasOutputFlag is equal to 1.

An activated SPS RBSP for a particular layer with nuh_layer_id greater than 0 shall remain active for a sequence of pictures in decoding order with that nuh_layer_id value starting from a picture, inclusive, that is an IRAP picture with NoRaslOutputFlag equal to 1 or for which FirstPicInLayerDecodedFlag[nuh_layer_id] is equal to 0, until the next picture, exclusive, that is an IRAP picture with NoRaslOutputFlag equal to 1 or for which FirstPicInLayerDecodedFlag[nuh_layer_id] is equal to 0.

Any SPS NAL unit containing the value of sps_seq_parameter_set_id for the active SPS RBSP for a particular non-base layer shall have the same content as that of the active SPS RBSP for the particular non-base layer unless it follows the last coded picture for which the active SPS RBSP for the particular non-base layer is required to be active for the particular non-base layer and precedes the first NAL unit that activates an SPS RBSP with the same value of seq_parameter_set_id.

During operation of the decoding process for NAL units of a non-base layer, the values of parameters of the active VPS RBSP, the active SPS RBSP for the non-base layer, and the active PPS RBSP for the non-base layer are considered in effect. For interpretation of SEI messages applicable to a coded picture of a non-base layer, the values of the active VPS RBSP, the active SPS RBSP for the non-base layer, and the active PPS RBSP for the non-base layer for the operation of the decoding process for the VCL NAL units of the coded picture are considered in effect unless otherwise specified in the SEI message semantics.

F.7.4.2.4.3 Order of access units and their association to CVS

The specifications in subclause 7.4.2.4.3 apply with the following modification:

Replace

It is a requirement of bitstream conformance that, when present, the next access unit after an access unit that contains an end of sequence NAL unit or an end of bitstream NAL unit shall be an IRAP access unit, which may be an IDR access unit, a BLA access unit, or a CRA access unit.

with the following (removing ", which may be an IDR access unit, a BLA access unit, or a CRA access unit"):

It is a requirement of bitstream conformance that, when present, the next access unit after an access unit that contains an end of sequence NAL unit or an end of bitstream NAL unit shall be an IRAP access unit.

F.7.4.2.4.4 Order of NAL units and coded pictures and association to access units

This clause specifies the order of NAL units and coded pictures and their association to access unit for CVSs that contain NAL units with nuh_layer_id greater than 0 that are decoded using the decoding processes specified in Annex F, Annex G and Annex H.

An access unit consists of one or more coded pictures with different values of nuh_layer_id and zero or more non-VCL NAL units. The association of VCL NAL units to coded pictures is described in subclause 7.4.2.4.5.

The first access unit in the bitstream starts with the first NAL unit of the bitstream.

A VCL NAL unit is the first VCL NAL unit of an access unit, when all of the following conditions are true: [Ed. (YK): These conditions seem sufficient but more than necessary for a VCL NAL unit to be the first VCL NAL unit of an AU. For example, it seems possible to have back-to-back AUs in the same POC resetting period and having the same PicOrderCntVal.]

– first_slice_segment_in_pic_flag is equal to 1.
– At least one of the following conditions is true:
  – The previous picture in decoding order belongs to a different POC resetting period than the picture containing the VCL NAL unit.
  – PicOrderCntVal derived for the VCL NAL unit differs from the PicOrderCntVal of the previous picture in decoding order.

NOTE 1 – Additionally, the following conditions could but need not be used:

  – The nuh_layer_id value of the VCL NAL unit is equal to 0.
  – vps_poc_lsb_aligned_flag is equal to 1 and the slice_pic_order_cnt_lsb value of the VCL NAL unit differs from the slice_pic_order_cnt_lsb value of the previous VCL NAL unit in decoding order.

The first of any of the following NAL units specifies the start of a new access unit:

– Access unit delimiter NAL unit (when present).
– The first NAL unit (when present), in decoding order, of a contiguous sequence of one or more of any of the following NAL units in any order, when the sequence of NAL units immediately precedes the first VCL NAL unit of an access unit:
  – VPS NAL unit (when present)
  – SPS NAL unit (when present)
  – PPS NAL unit (when present)
  – Prefix SEI NAL unit (when present)
  – NAL units with nal_unit_type in the range of RSV_NVCL41..RSV_NVCL44 (when present)
  – NAL units with nal_unit_type in the range of UNSPEC48..UNSPEC55 (when present)
– The first VCL NAL unit of an access unit (always present).

The order of the coded pictures and non-VCL NAL units within an access unit shall obey the following constraints:

– When an access unit delimiter NAL unit is present, it shall be the first NAL unit. There shall be at most one access unit delimiter NAL unit in any access unit.
– When any prefix SEI NAL units are present, they shall not follow the last VCL NAL unit of the access unit.
– NAL units having nal_unit_type equal to FD_NUT or SUFFIX_SEI_NUT, or in the range of RSV_NVCL45..RSV_NVCL47 or UNSPEC56..UNSPEC63 shall not precede the first VCL NAL unit of the access unit.
– When an end of sequence NAL unit is present, it shall be the last NAL unit in the access unit other than an end of bitstream NAL unit (when present).

– When an end of bitstream NAL unit is present, it shall be the last NAL unit in the access unit.

NOTE 2 – VPS NAL units, SPS NAL units, PPS NAL units, prefix SEI NAL units, or NAL units with nal_unit_type in the range of RSV_NVCL41..RSV_NVCL44 or UNSPEC48..UNSPEC55, may be present in an access unit, but cannot follow the last VCL NAL unit of the access unit, as this condition would specify the start of a new access unit.

F.7.4.2.4.5 Order of VCL NAL units and association to coded pictures

The specifications in subclause 7.4.2.4.5 apply.

F.7.4.2.4.6 Order of VCL NAL units and association to picture units

[Ed. (MH): The exact specification of a picture unit is missing. There is a decision to add such text, as response to Proposal 2.2-4 of JCTVC-Q0183. The decision is documented in the BoG notes JCTVC-Q0223 as follows: "agreed in spirit. Additional text is also needed to define which NAL units are associated with a picture unit."]

F.7.4.3 Raw byte sequence payloads, trailing bits, and byte alignment semantics

F.7.4.3.1 Video parameter set RBSP semantics

The specifications in subclause 7.4.3.1 apply with following modifications and additions:

– layerSetLayerIdList *is replaced by* LayerSetLayerIdList.

– numLayersInIdList *is replaced by* NumLayersInIdList.

– *Remove the semantics of* vps_reserved_three_2bits.

– *Replace*

"Each operation point is identified by the associated layer identifier list, denoted as OpLayerIdList, which consists of the list of nuh_layer_id values of all NAL units included in the operation point, in increasing order of nuh_layer_id values, and a variable OpTid, which is equal to the highest TemporalId of all NAL units included in the operation point."

with

"Each operation point is identified by the associated layer identifier list, denoted as OpLayerIdList, which consists of the list of nuh_layer_id values of all NAL units included in the operation point, in increasing order of nuh_layer_id values, and a variable OpTid, which is equal to the highest TemporalId of all NAL units included in the operation point. Each output operation point is associated with an operation point, a list of nuh_layer_id values of the output layers, in increasing order of nuh_layer_id values, denoted as OptLayerIdList, and the OpTid of the associated operation point. The OpLayerIdList of the operation point associated with an output operation point is also referred to as the OpLayerIdList of the output operation point."

vps_base_layer_internal_flag equal to 0 specifies that the base layer is provided by an external means not specified in this Specification. vps_base_layer_internal_flag equal to 1 specifies that the base layer is provided in the bitstream.

When vps_base_layer_internal_flag is equal to 0, the following applies:

– The value of vps_sub_layer_ordering_info_present_flag shall be equal to 0.

– The values of vps_max_dec_pic_buffering_minus1[i], vps_max_num_reorder_pics[i], and vps_max_latency_increase_plus1[i] shall all be equal to 0 for all possible values of i.

– Decoders shall ignore the values of vps_sub_layer_ordering_info_present_flag, vps_max_dec_pic_buffering_minus1[i], vps_max_num_reorder_pics[i], and vps_max_latency_increase_plus1[i].

– The value of hrd_layer_set_idx[i] shall be greater than 0.

vps_reserved_one_bit shall be equal to 1 in bitstreams conforming to this version of this Specification. The value 0 for vps_reserved_one_bit is reserved for future use by ITU-T | ISO/IEC. Decoders shall ignore the value of vps_reserved_one_bit.

vps_max_layers_minus1 plus 1 specifies the maximum allowed number of layers in the CVS. vps_max_layers_minus1 shall be less than 63 in bitstreams conforming to this version of this Specification. The value of 63 for vps_max_layers_minus1 is reserved for future use by ITU-T | ISO/IEC. Although the value of vps_max_layers_minus1 is required to be less than 63 in this version of this Specification, decoders shall allow a value of vps_max_layers_minus1 equal to 63 to appear in the syntax.

NOTE – It is anticipated that in a future super multiview coding extension of this specification, the value of 63 for vps_max_layers_minus1 will be used to indicate an extended number of layers.

The variable MaxLayersMinus1 is set equal to Min(62, vps_max_layers_minus1).

vps_max_layer_id specifies the maximum allowed value of nuh_layer_id of all NAL units in the CVS. vps_max_layer_id shall be less than 63 in bitstreams conforming to this version of this Specification. The value of 63 for vps_max_layer_id is reserved for future use by ITU-T | ISO/IEC. Although the value of vps_max_layer_id is required to be less than 63 in this version of this Specification, decoders shall allow a value of vps_max_layer_id equal to 63 to appear in the syntax.

vps_num_layer_sets_minus1 plus 1 specifies the number of layer sets that are specified by the VPS. The value of vps_num_layer_sets_minus1 shall be in the range of 0 to 1023, inclusive.

vps_num_hrd_parameters specifies the number of hrd_parameters( ) syntax structures present in the VPS RBSP. The value of vps_num_hrd_parameters shall be in the range of 0 to vps_num_layer_sets_minus1 + 1, inclusive.

hrd_layer_set_idx[i] specifies the index, into the list of layer sets specified by the VPS, of the layer set to which the i-th hrd_parameters( ) syntax structure in the VPS applies. The value of hrd_layer_set_idx[i] shall be in the range of (vps_base_layer_internal_flag ? 0 : 1) to vps_num_layer_sets_minus1, inclusive.

It is a requirement of bitstream conformance that the value of hrd_layer_set_idx[i] shall not be equal to the value of hrd_layer_set_idx[j] for any value of j not equal to i.

vps_extension_flag equal to 0 specifies that no vps_extension( ) syntax structure is present in the VPS RBSP syntax structure. vps_extension_flag equal to 1 specifies that the vps_extension( ) syntax structure is present in the VPS RBSP syntax structure. When MaxLayersMinus1 is greater than 0, vps_extension_flag shall be equal to 1.

vps_extension_alignment_bit_equal_to_one shall be equal to 1.

vps_extension2_flag equal to 0 specifies that no vps_extension_data_flag syntax elements are present in the VPS RBSP syntax structure. vps_extension2_flag shall be equal to 0 in bitstreams conforming to this version of this Specification. The value of 1 for vps_extension2_flag is reserved for future use by ITU-T | ISO/IEC. Decoders shall ignore all data that follow the value 1 for vps_extension2_flag in a VPS NAL unit.

F.7.4.3.1.1 Video parameter set extension semantics

splitting_flag equal to 1 indicates that the dimension_id[i][j] syntax elements are not present and that the binary representation of the nuh_layer_id value in the NAL unit header are split into NumScalabilityTypes segments with lengths, in bits, according to the values of dimension_id_len_minus1[j] and that the values of dimension_id[LayerIdxInVps[nuh_layer_id]][j] are inferred from the NumScalabilityTypes segments. splitting_flag equal to 0 indicates that the syntax elements dimension_id[i][j] are present.

NOTE 1 – When splitting_flag is equal to 1, scalable identifiers can be derived from the nuh_layer_id syntax element in the NAL unit header by a bit masked copy. The respective bit mask for the i-th scalable dimension is defined by the value of the dimension_id_len_minus1[i] syntax element and dimBitOffset[i] as specified in the semantics of dimension_id_len_minus1[j].

scalability_mask_flag[i] equal to 1 indicates that dimension_id syntax elements corresponding to the i-th scalability dimension in Table F-1 are present. scalability_mask_flag[i] equal to 0 indicates that dimension_id syntax elements corresponding to the i-th scalability dimension are not present.

Table F-1 – Mapping of ScalabiltyId to scalability dimensions

scalability mask index	Scalability dimension	ScalabilityId mapping
0	Reserved	
1	Multiview	View Order Index
2	Reserved	
3	Auxiliary	AuxId
4-15	Reserved	

NOTE 2 – It is anticipated that in future 3D extensions of this Specification, scalability mask index 0 will be used to indicate depth maps. It is anticipated that in future scalability extensions of this Specification, scalability mask index 2 will be used to indicate spatial/SNR scalability.

dimension_id_len_minus1[j] plus 1 specifies the length, in bits, of the dimension_id[i][j] syntax element.

When splitting_flag is equal to 1, the following applies:

– The variable dimBitOffset[0] is set equal to 0 and for j in the range of 1 to NumScalabilityTypes − 1, inclusive, dimBitOffset[j] is derived as follows:

$$dimBitOffset[\,j\,] = \sum_{dimIdx=0}^{j-1} \big(dimension\_id\_len\_minus1[\,dimIdx\,] + 1 \big) \tag{F-1}$$

– The value of dimension_id_len_minus1[NumScalabilityTypes − 1] is inferred to be equal to 5 − dimBitOffset[NumScalabilityTypes − 1].

– The value of dimBitOffset[NumScalabilityTypes] is set equal to 6.

It is a requirement of bitstream conformance that when NumScalabilityTypes is greater than 0, dimBitOffset[NumScalabilityTypes − 1] shall be less than 6.

vps_nuh_layer_id_present_flag equal to 1 specifies that layer_id_in_nuh[i] for i from 0 to MaxLayersMinus1, inclusive, are present. vps_nuh_layer_id_present_flag equal to 0 specifies that layer_id_in_nuh[i] for i from 0 to MaxLayersMinus1, inclusive, are not present.

layer_id_in_nuh[i] specifies the value of the nuh_layer_id syntax element in VCL NAL units of the i-th layer. For i in the range of 0 to MaxLayersMinus1, inclusive, when layer_id_in_nuh[i] is not present, the value is inferred to be equal to i.

When i is greater than 0, layer_id_in_nuh[i] shall be greater than layer_id_in_nuh[i − 1].

For i from 0 to MaxLayersMinus1, inclusive, the variable LayerIdxInVps[layer_id_in_nuh[i]] is set equal to i.

dimension_id[i][j] specifies the identifier of the j-th present scalability dimension type of the i-th layer. The number of bits used for the representation of dimension_id[i][j] is dimension_id_len_minus1[j] + 1 bits.

Depending on splitting_flag, the following applies:

– If splitting_flag is equal to 1, for i from 0 to MaxLayersMinus1, inclusive, and j from 0 to NumScalabilityTypes − 1, inclusive, dimension_id[i][j] is inferred to be equal to ((layer_id_in_nuh[i] & ((1 << dimBitOffset[j + 1]) − 1)) >> dimBitOffset[j]).

– Otherwise (splitting_flag is equal to 0), for j from 0 to NumScalabilityTypes − 1, inclusive, dimension_id[0][j] is inferred to be equal to 0.

The variable ScalabilityId[i][smIdx] specifying the identifier of the smIdx-th scalability dimension type of the i-th layer, the variable ViewOrderIdx[layer_id_in_nuh[i]] specifying the view order index of the i-th layer, and the variable ViewScalExtLayerFlag[layer_id_in_nuh[i]] specifying whether the i-th layer is a view scalability extension layer are derived as follows:

```
NumViews = 1
for( i = 0; i  <=  MaxLayersMinus1; i++ ) {
    lId = layer_id_in_nuh[ i ]
    for( smIdx= 0, j = 0; smIdx < 16; smIdx++ )
        if( scalability_mask_flag[ smIdx ] )
            ScalabilityId[ i ][ smIdx ] = dimension_id[ i ][ j++ ]
    ViewOrderIdx[ lId ] = ScalabilityId[ i ][ 1 ]
    if( i > 0 ) {
        newViewFlag = 1
        for( j = 0; j < i; j++ )
            if( ViewOrderIdx[ lId ]  = =  ViewOrderIdx[ layer_id_in_nuh[ j ] ] )
              newViewFlag = 0
        NumViews += newViewFlag
    }
    ViewScalExtLayerFlag[ lId ] = ( ViewOrderIdx[ lId ] > 0 )
    AuxId[ lId ] = ScalabilityId[ i ][ 3 ]
}
```

AuxId[lId] equal to 0 specifies the layer with nuh_layer_id equal to lId does not contain auxiliary pictures. AuxId[lId] greater than 0 specifies the type of auxiliary pictures in layer with nuh_layer_id equal to lId as specified in Table F-2.

Table F-2 – Mapping of AuxId to the type of auxiliary pictures

AuxId	Name of AuxId	Type of auxiliary pictures	SEI message describing interpretation of auxiliary pictures
1	AUX_ALPHA	Alpha plane	Alpha channel information
2	AUX_DEPTH	Depth picture	Depth representation information
3..127		Reserved	
128..143		Unspecified	
144..255		Reserved	

NOTE 3 – The interpretation of auxiliary pictures associated with AuxId in the range of 128 to 143, inclusive, is specified through means other than the AuxId value.

AuxId[lId] shall be in the range of 0 to 2, inclusive, or 128 to 143, inclusive, for bitstreams conforming to this version of this Specification. Although the value of AuxId[lId] shall be in the range of 0 to 2, inclusive, or 128 to 143, inclusive, in this version of this Specification, decoders shall allow values of AuxId[lId] in the range of 0 to 255, inclusive.

SEI messages may describe the interpretation of auxiliary pictures, including their possible association with one or more primary pictures.

NOTE 4 – Unless constrained by the semantics of the SEI messages specifying the interpretation of auxiliary pictures, it is allowed to have two layers with nuh_layer_id values layerIdA and layerIdB such that AuxId[layerIdA] is equal to AuxId[layerIdB], both being greater than 0, and to have all values of ScalabilityId[LayerIdxInVps[layerIdA]][i] equal to ScalabilityId[LayerIdxInVps[layerIdB]][i] for each value of i in the range of 0 to 15, inclusive. SEI messages specifying the interpretation of auxiliary pictures may specify that a picture with nuh_layer_id equal to layerIdA and a picture with nuh_layer_id equal to layerIdB in the same access unit may both be associated with the same primary picture.

view_id_len specifies the length, in bits, of the view_id_val[i] syntax element. The value of view_id_len shall be greater than or equal to Ceil(Log2 (NumViews)). [Ed. (GT): Regarding that currently two different views are not required to have different view_id_val values the last constraint is not necessary.]

view_id_val[i] specifies the view identifier of the i-th view specified by the VPS. The length of the view_id_val[i] syntax element is view_id_len bits. When not present, the value of view_id_val[i] is inferred to be equal to 0.

For each layer with nuh_layer_id equal to nuhLayerId, the value ViewId[nuhLayerId] is set equal to view_id_val[ViewOrderIdx[nuhLayerId]].

direct_dependency_flag[i][j] equal to 0 specifies that the layer with index j is not a direct reference layer for the layer with index i. direct_dependency_flag[i][j] equal to 1 specifies that the layer with index j may be a direct reference layer for the layer with index i. When direct_dependency_flag[i][j] is not present for i and j in the range of 0 to MaxLayersMinus1, it is inferred to be equal to 0.

The variables NumDirectRefLayers[i] and RefLayerId[i][j] are derived as follows:

```
for( i = 0; i  <=  MaxLayersMinus1; i++ ) {
    iNuhLId = layer_id_in_nuh[ i ]
    NumDirectRefLayers[ iNuhLId ] = 0
    for( j = 0; j < i; j++ )
        if( direct_dependency_flag[ i ][ j ] )
            RefLayerId[ iNuhLId ][ NumDirectRefLayers[ iNuhLId ]++ ] = layer_id_in_nuh[ j ]
}
```

The variable NumRefLayers[i] is derived as follows:

– NumRefLayers[i] is first initialized to 0 for all values of i in the range of 0 and 62, inclusive.

– For each layer with nuh_layer_id equal to currLayerId, and for all values of j in the range of 0 to 62, inclusive, the variable recursiveRefLayerFlag[currLayerId][j] is first initialized to 0. The variable recursiveRefLayerFlag[currLayerId][j] is then modified using the function setRefLayerFlags(currLayerId), specified as follows:

```
for( j = 0; j < NumDirectRefLayers[ currLayerId ]; j++ ) {
    refLayerId = RefLayerId[ currLayerId ][ j ]
    recursiveRefLayerFlag[ currLayerId ][ refLayerId ] = 1
    for( k = 0; k < 63; k++ )
        recursiveRefLayerFlag[ currLayerId ][ k ] =
```

```
                recursiveRefLayerFlag[ currLayerId ][ k ] || recursiveRefLayerFlag[ refLayerId ][ k ]
    }
```

– NumRefLayers[i] is modified as follows:

```
    for( i = 0; i <= vps_max_layers_minus1; i++ ) {
        iNuhLId = layer_id_in_nuh[ i ]
        setRefLayerFlags( iNuhLId )
        for( j = 0; j < 63; j++ )
            NumRefLayers[ iNuhLId ] += recursiveRefLayerFlag[ iNuhLId ][ j ]
    }
```

The variables NumPredictedLayers[i] and PredictedLayerId[i][j] are derived as follows:

```
    for( i = 0; i < MaxLayersMinus1; i++ ) {
        iNuhLId = layer_id_in_nuh[ i ]
        for( j = iNuhLId + 1, predIdx = 0; j < 63; j++ )
            if( recursiveRefLayerFlag[ j ][ iNuhLId ] )
                PredictedLayerId[ iNuhLId ][ predIdx++ ] = j
        NumPredictedLayers[ iNuhLId ] = predIdx
    }
```

The variables NumIndependentLayers, NumLayersInTreePartition[i], and TreePartitionLayerIdList[i][j] for i in the range of 0 to NumIndependentLayers − 1, inclusive, and j in the range of 0 to NumLayersInTreePartition[i] − 1, inclusive, are derived as follows:

```
    for( i = 0; i <= MaxLayersMinus1; i++ )
        countedLayerIdxFlag[ i ] = 0
    for( i = 0, k = 0; i <= MaxLayersMinus1; i++ ) {
        iNuhLId = layer_id_in_nuh[ i ]
        if( NumDirectRefLayers[ iNuhLId ] == 0 ) {
            TreePartitionLayerIdList[ k ][ 0 ] = iNuhLId
            NumLayersInTreePartition[ k ] = 1
            for( j = 0; j < NumPredictedLayers[ iNuhLId ]; j++ )
                if( !countedLayerIdxFlag[ LayerIdxInVps[ PredictedLayerId[ iNuhLId ][ j ] ] ] ) {
                    TreePartitionLayerIdList[ k ][ NumLayersInTreePartition[ k ] ] = PredictedLayerId[ iNuhLId ][ j ]
                    NumLayersInTreePartition[ k ]++
                    countedLayerIdxFlag[ LayerIdxInVps[ PredictedLayerId[ iNuhLId ][ j ] ] ] = 1
                }
            k++
        }
        NumIndependentLayers = k
    }
```

It is a requirement of bitstream conformance that AuxId[RefLayerId[nuhLayerIdA][j]] for any values of nuhLayerIdA and j shall be equal to AuxId[nuhLayerIdA], when AuxId[nuhLayerIdA] is in the range of 0 to 2, inclusive.

NOTE 5 – In other words, no prediction takes place between layers with a different value of AuxId, when AuxId is in the range of 0 to 2, inclusive.

vps_sub_layers_max_minus1_present_flag equal to 1 specifies that the syntax elements sub_layers_vps_max_minus1[i] are present. vps_sub_layers_max_minus1_present_flag equal to 0 specifies that the syntax elements sub_layers_vps_max_minus1[i] are not present.

sub_layers_vps_max_minus1[i] plus 1 specifies the maximum number of temporal sub-layers that may be present in the CVS for the layer with nuh_layer_id layerId equal to layer_id_in_nuh[i] such that layerId is greater than or equal to (vps_base_layer_internal_flag ? 0 : 1). When vps_base_layer_internal_flag is equal to 0, sub_layers_vps_max_minus1[0] constrains the access units for which a decoded picture with nuh_layer_id equal to 0 may be provided by external means as follows: a decoded picture with nuh_layer_id equal to 0 cannot be provided by external means for decoding of an access unit with TemporalId greater than sub_layers_vps_max_minus1[0]. The value of sub_layers_vps_max_minus1[i] shall be in the range of 0 to vps_max_sub_layers_minus1, inclusive. When not present, sub_layers_vps_max_minus1[i] is inferred to be equal to vps_max_sub_layers_minus1.

The variable MaxSubLayersInLayerSetMinus1[i] is derived as follows:

```
    for( i = 0; i < NumLayerSets; i++ ) {
        maxSlMinus1 = 0
        for( k = 0; k < NumLayersInIdList[ i ]; k++ ) {
```

```
            lId = LayerSetLayerIdList[ i ][ k ]                                    (F-2)
            maxSlMinus1 = Max( maxSLMinus1, sub_layers_vps_max_minus1[ LayerIdxInVps[ lId ] ] )
        }
        MaxSubLayersInLayerSetMinus1[ i ] = maxSlMinus1
    }
```

max_tid_ref_present_flag equal to 1 specifies that the syntax element max_tid_il_ref_pics_plus1[i][j] is present. max_tid_ref_present_flag equal to 0 specifies that the syntax element max_tid_il_ref_pics_plus1[i][j] is not present.

max_tid_il_ref_pics_plus1[i][j] equal to 0 specifies that non-IRAP pictures with nuh_layer_id equal to layer_id_in_nuh[i] are not used as reference for inter-layer prediction for pictures with nuh_layer_id equal to layer_id_in_nuh[j]. max_tid_il_ref_pics_plus1[i][j] greater than 0 specifies that pictures with nuh_layer_id equal to layer_id_in_nuh[i] and TemporalId greater than max_tid_il_ref_pics_plus1[i][j] − 1 are not used as reference for inter-layer prediction for pictures with nuh_layer_id equal to layer_id_in_nuh[j]. When not present, max_tid_il_ref_pics_plus1[i][j] is inferred to be equal to 7.

all_ref_layers_active_flag equal to 1 specifies that for each picture referring to the VPS, the reference layer pictures that belong to all direct reference layers of the layer containing the picture and that might be used for inter-layer prediction as specified by the values of sub_layers_vps_max_minus1[i] and max_tid_il_ref_pics_plus1[i][j] are present in the same access unit as the picture and are included in the inter-layer reference picture set of the picture. all_ref_layers_active_flag equal to 0 specifies that the above restriction may or may not apply. [Ed. (GT): Consider renaming the syntax element, since not all reference layers are active anymore.]

vps_num_profile_tier_level_minus1 plus 1 specifies the number of profile_tier_level( ) syntax structures in the VPS. The value of vps_num_profile_tier_level_minus1 shall be in the range of 0 to 63, inclusive.

vps_profile_present_flag[i] equal to 1 specifies that profile and tier information is present in the i-th profile_tier_level( ) syntax structure. vps_profile_present_flag[i] equal to 0 specifies that profile and tier information is not present in the i-th profile_tier_level( ) syntax structure and is inferred.

num_add_layer_sets specifies the number of additional layer sets. When not present, num_add_layer_sets is inferred to be equal to 0. num_add_layer_sets shall be in the range of 0 to 1023, inclusive.

The variable NumLayerSets is derived as follows:

```
NumLayerSets = vps_num_layer_sets_minus1 + 1 + num_add_layer_sets
```

When num_add_layer_sets is greater than 0, the variables FirstAddLayerSetIdx and LastAddLayerSetIdx are derived as follows:

```
FirstAddLayerSetIdx = vps_num_layer_sets_minus1 + 1
LastAddLayerSetIdx = FirstAddLayerSetIdx + num_add_layer_sets − 1
```

When num_add_layer_sets is greater than 0, it is a requirement of bitstream conformance that the following applies:

– When the non-base layer subtree extraction process of subclause F.10.2 is applied with the input variable lsIdx equal to vps_num_layer_sets_minus1 + 1 + i for any value of i in the range of 0 to num_add_layer_sets − 1, inclusive, and NumLayersInIdList[lsIdx] is equal to 1, the output of the process of subclause F.10.2 shall be a conforming bitstream except that the output bitstream is not required to contain any VPS NAL units.

– When the non-base layer subtree extraction process of subclause F.10.2 is applied with the input variable lsIdx equal to vps_num_layer_sets_minus1 + 1 + i for any value of i in the range of 0 to num_add_layer_sets − 1, inclusive, and NumLayersInIdList[lsIdx] is greater than 1, the output of the process of subclause F.10.2 shall be a conforming bitstream.

highest_layer_idx_plus1[i][j] specifies the values of NumLayersInIdList[vps_num_layer_sets_minus1 + 1 + i] and LayerSetLayerIdList[vps_num_layer_sets_minus1 + 1 + i][layerNum] and is used to infer layer_id_included_flag[vps_num_layer_sets_minus1 + 1 + i][layerId] as follows:

```
layerNum = 0
lsIdx = vps_num_layer_sets_minus1 + 1 + i
for( layerId = 0; layerId  <=  62; layerId++ )
    layer_id_included_flag[ lsIdx ][ layerId ] = 0 [ Ed. (GT), Assignment to syntax element should be changed. ]
for( treeIdx = 1; treeIdx < NumIndependentLayers; treeIdx++ )
    for( layerCnt = 0; layerCnt < highest_layer_idx_plus1[ i ][ j ]; layerCnt++ ) {
        LayerSetLayerIdList[ lsIdx ][ layerNum ] = TreePartitionLayerIdList[ treeIdx ][ layerCnt ]
        layer_id_included_flag[ lsIdx ][ TreePartitionLayerIdList[ treeIdx ][ layerCnt ] ] = 1
        layerNum++
```

```
        }
    NumLayersInIdList[ lsIdx ] = layerNum
```

The value of highest_layer_idx_plus1[i][j] shall be in the range of 0 to NumLayersInTreePartition[j], inclusive.

The length of highest_layer_idx_plus1[i][j] is equal to Ceil(Log2(NumLayersInTreePartition[j] + 1)).

It is a requirement of bitstream conformance that NumLayersInIdList[vps_num_layer_sets_minus1 + 1 + i] shall be greater than 0.

AssignedBaseLayerId[vps_num_layer_sets_minus1 + 1 + i] is set equal to the smallest nuh_layer_id value in NumLayersInIdList[vps_num_layer_sets_minus1 + 1 + i].

It is a requirement of bitstream conformance that each SPS or PPS that is active for the layer with nuh_layer_id equal to AssignedBaseLayerId[vps_num_layer_sets_minus1 + 1 + i] shall have nuh_layer_id equal to 0.

num_add_olss specifies the number of OLSs in addition to the first NumLayerSets OLSs specified by the VPS. The value of num_add_olss shall be in the range of 0 to 1023, inclusive. When not present, the value of num_add_olss is inferred to be equal to 0.

default_output_layer_idc specifies the derivation of the output layers for the OLSs with index in the range of 1 to vps_num_layer_sets_minus1, inclusive. default_output_layer_idc equal to 0 specifies that all layers in each of the OLSs with index in the range of 1 to vps_num_layer_sets_minus1, inclusive, are output layers of their respective OLSs. default_output_layer_idc equal to 1 specifies that only the layer with the highest value of nuh_layer_id such that nuh_layer_id equal to nuhLayerIdA and AuxId[nuhLayerIdA] equal to 0 in each of the OLSs with index in the range of 1 to vps_num_layer_sets_minus1, inclusive, is an output layer of its OLS. default_output_layer_idc equal to 2 specifies that the output layers for the OLSs with index in the range of 1 to vps_num_layer_sets_minus1, inclusive, are specified with the syntax elements output_layer_flag[i][j]. The value of 3 for default_output_layer_idc is reserved for future use by ITU-T | ISO/IEC. Although the value of default_output_layer_idc is required to be less than 3 in this version of this Specification, decoders shall allow a value of default_output_layer_idc equal to 3 to appear in the syntax.

The variable defaultOutputLayerIdc is set equal to Min(default_output_layer_idc, 2).

layer_set_idx_for_ols_minus1[i] plus 1 specifies the index of the layer set for the i-th OLS. The value of layer_set_idx_for_ols_minus1[i] shall be in the range of 0 to NumLayerSets – 2, inclusive. The length of the layer_set_idx_for_ols_minus1[i] syntax element is Ceil(Log2(NumLayerSets – 1)) bits.

For i in the range of 0 to NumOutputLayerSets - 1, inclusive, the variable OlsIdxToLsIdx[i] is derived as specified in the following:

```
OlsIdxToLsIdx[ i ] =  ( i < NumLayerSets ) ? i : layer_set_idx_for_ols_minus1[ i ] + 1        (F-3)
```

output_layer_flag[i][j] equal to 1 specifies that the j-th layer in the i-th OLS is an output layer. output_layer_flag[i][j] equal to 0 specifies that the j-th layer in the i-th OLS is not an output layer.

The value of output_layer_flag[0][0] is inferred to be equal to 1.

When defaultOutputLayerIdc is equal to 0 or 1, for i in the range of 0 to vps_num_layer_sets_minus1, inclusive, and j in the range of 0 to NumLayersInIdList[OlsIdxToLsIdx[i]] − 1, inclusive, the variable OutputLayerFlag[i][j] is derived as follows:

– If defaultOutputLayerIdc is equal to 0 or LayerSetLayerIdList[OlsIdxToLsIdx[i]][j] is equal to nuhLayerIdA, with nuhLayerIdA being the highest value in LayerSetLayerIdList[OlsIdxToLsIdx[i]] with AuxId[nuhLayerIdA] equal to 0, OutputLayerFlag[i][j] is set equal to 1.

– Otherwise, OutputLayerFlag[i][j] is set equal to 0.

For i in the range of (defaultOutputLayerIdc = = 2) ? 0 : (vps_num_layer_sets_minus1 + 1) to NumOutputLayerSets − 1, inclusive, and j in the range of 0 to NumLayersInIdList[OlsIdxToLsIdx[i]] − 1, inclusive, the variable OutputLayerFlag[i][j] is set equal to output_layer_flag[i][j].

The variable NumOutputLayersInOutputLayerSet[i] is derived as follows:

```
NumOutputLayersInOutputLayerSet[ i ] = 0
for( j = 0 ; j < NumLayersInIdList[ OlsIdxToLsIdx[ i ] ]; j++) {
    NumOutputLayersInOutputLayerSet[ i ] += OutputLayerFlag[ i ][ j ]
    if( OutputLayerFlag[ i ][ j ] )
        OlsHighestOutputLayerId[ i ] = LayerSetLayerIdList[ OlsIdxToLsIdx[ i ] ][ j ]
```

It is a requirement of bitstream conformance that NumOutputLayersInOutputLayerSet[i] shall be greater than 0 for i in the range of 0 to NumOutputLayers − 1, inclusive.

profile_level_tier_idx[i] specifies the index, into the list of profile_tier_level( ) syntax structures in the VPS, of the profile_tier_level( ) syntax structure that applies to i-th OLS. When num_add_layer_sets is greater than 0 and OlsIdxToLsIdx[i] is in the range of FirstAddLayerSetIdx to LastAddLayerSetIdx, inclusive, the profile_tier_level( ) syntax structure applies to the output of the non-base layer subtree extraction process of subclause F.10.2 with the input variable lsIdx set equal to OlsIdxToLsIdx[i], where the active VPSs of the output bitstream outBitstream, if any, shall contain an OLS specifying the output of the same layers as the i-th OLS of the current VPS. [Ed. (MH): The sentence could be editorially improved to more specifically state that the new base layer had nuh_layer_id equal to AssignedBaseLayerId in the inBitstream.] The length of the profile_level_tier_idx[i] syntax element is Ceil(Log2(vps_num_profile_tier_level_minus1 + 1)) bits. The value of profile_level_tier_idx[0] is inferred to be equal to 0. The value of profile_level_tier_idx[i] for i in the range of 1 to NumOutputLayerSet − 1, inclusive, shall be in the range of (vps_base_layer_internal_flag ? 0 : 1) to vps_num_profile_tier_level_minus1, inclusive.

alt_output_layer_flag[i] equal to 0 specifies that an alternative output layer is not used for any output layer in the i-th OLS. alt_output_layer_flag[i] equal to 1 specifies that an alternative output layer may be used for the output layer in the i-th OLS.

– If NumOutputLayersInOutputLayerSet[i] is equal to 1 and NumDirectRefLayers[OlsHighestOutputLayerId[i]] is greater than 0, the variable AltOptLayerFlag[i] is set equal to alt_output_layer_flag[i].

– Otherwise, the variable AltOptLayerFlag[i] is set equal to 0.

AltOptLayerFlag[0] is set equal to 0.

NOTE 6 – When AltOptLayerFlag[olsIdx] is equal to 0, pictures that are not at the output layers of the OLS with index olsIdx are not output. When AltOptLayerFlag[olsIdx] is equal to 1 and a picture at the output layer of the OLS with index olsIdx is not present in an access unit or has PicOutputFlag equal to 0, a picture with highest nuh_layer_id among those pictures of the access unit for which PicOutputFlag is equal to 1 and which has nuh_layer_id value among the nuh_layer_id values of the direct and indirect reference layers of the output layer is output.

For each value of olsIdx in the range of 0 to NumOutputLayerSets − 1, inclusive, the following applies:

– When AltOptLayerFlag[olsIdx] is equal to 1, the value of pic_output_flag shall be the same in the slice headers of an access unit that have nuh_layer_id value equal to OlsHighestOutputLayerId[olsIdx] or equal to the nuh_layer_id value of any direct or indirect reference layer of the layer with nuh_layer_id equal to OlsHighestOutputLayerId[olsIdx].

– Let olsBitstream be the output of the sub-bitstream extraction process with inputs of the current bitstream, TemporalId equal to 7 and layerIdListTarget equal to LayerSetLayerIdList[OlsIdxToLsIdx[olsIdx]]. Let truncatedOlsBitstream be olsBitstream or be formed from the olsBitstream by removing access units preceding, in decoding order, any access unit with an IRAP picture having nuh_layer_id equal to 0. It is a requirement of bitstream conformance that when AltOptLayerFlag[olsIdx] is equal to 1, a bitstream that is formed by removing, from the truncatedOlsBitstream, any coded picture that is not used as a reference for prediction for any other picture and is not the only coded picture of an access unit is a conforming bitstream.

NOTE 7 – When AltOptLayerFlag[olsIdx] is equal to 1, encoders are required to set the values of max_vps_dec_pic_buffering_minus1[i][k][j] such that these values suffice also when pictures of an alternative output layer are marked as "needed for output" in the HRD.

vps_num_rep_formats_minus1 plus 1 specifies the number of the following rep_format( ) syntax structures in the VPS. The value of vps_num_rep_formats_minus1 shall be in the range of 0 to 255, inclusive.

rep_format_idx_present_flag equal to 1 specifies that the syntax elements vps_rep_format_idx[i] are present. rep_format_idx_present_flag equal to 0 specifies that the syntax elements vps_rep_format_idx[i] are not present. When not present, the value of rep_format_idx_present_flag is inferred to be equal to 0.

vps_rep_format_idx[i] specifies the index, into the list of rep_format( ) syntax structures in the VPS, of the rep_format( ) syntax structure that applies to the layer with nuh_layer_id equal to layer_id_in_nuh[i]. When not present, the value of vps_rep_format_idx[i] is inferred to be equal to Min(i, vps_num_rep_formats_minus1). The value of vps_rep_format_idx[i] shall be in the range of 0 to vps_num_rep_formats_minus1, inclusive. The number of bits used for the representation of vps_rep_format_idx[i] is Ceil(Log2(vps_num_rep_formats_minus1 + 1)).

max_one_active_ref_layer_flag equal to 1 specifies that at most one picture is used for inter-layer prediction for each picture in the CVS. max_one_active_ref_layer_flag equal to 0 specifies that more than one picture may be used for inter-layer prediction for each picture in the CVS.

vps_poc_lsb_aligned_flag equal to 0 specifies that the value of slice_pic_order_cnt_lsb may or may not be the same in different pictures of an access unit. vps_poc_lsb_aligned_flag equal to 1 specifies that the value of slice_pic_order_cnt_lsb is the same in all pictures of an access unit. Additionally, the value of vps_poc_lsb_aligned_flag affects the decoding process for picture order count in subclause F.8.3.1. When not present, vps_poc_lsb_aligned_flag is inferred to be equal to 0.

poc_lsb_not_present_flag[i] equal to 1 specifies that the slice_pic_order_cnt_lsb syntax element is not present in the slice headers of IDR pictures with nuh_layer_id equal to layer_id_in_nuh[i] in the CVS. poc_lsb_not_present_flag[i] equal to 0 specifies that slice_pic_order_cnt_lsb syntax element may or may not be present in the slice headers of IDR pictures with nuh_layer_id equal to layer_id_in_nuh[i] in the CVS. When not present, poc_lsb_not_present_flag[i] is inferred to be equal to 0.

It is a requirement of bitstream conformance that when poc_lsb_not_present_flag[i] is equal to 1, for any picture picA that has nuh_layer_id equal to layer_id_in_nuh[i] and refers to the VPS, the following applies:

– When slice_pic_order_cnt_lsb is greater than 0, poc_reset_idc shall not be equal to 2.

– When full_poc_reset_flag is equal to 1, poc_lsb_val shall be equal to 0.

[Ed. (GT) Consider moving above constraints to semantics of poc_reset_idc and poc_lsb_val]

vps_reserved_zero_flag shall be equal to 0 in bitstreams conforming to this version of this Specification. Other value for vps_reserved_zero_flag are reserved for future use by ITU-T | ISO/IEC. Decoders shall ignore the value of vps_reserved_zero_flag.

[Ed. (JC): The vps_reserved_zero_flag will be used for the syntax cross_layer_phase_alignment_flag in the SHVC draft.]

direct_dep_type_len_minus2 plus 2 specifies the number of bits of the direct_dependency_type[i][j] and the default_direct_dependency_type syntax elements. In bitstreams conforming to this version of this Specification the value of direct_dep_type_len_minus2 shall be equal 0. Although the value of direct_dep_type_len_minus2 shall be equal to 0 in this version of this Specification, decoders shall allow other values of direct_dep_type_len_minus2 in the range of 0 to 30, inclusive, to appear in the syntax.

default_direct_dependency_flag equal to 1 specifies that the syntax element direct_dependency_type[i][j] is not present and inferred from default_direct_dependency_type. default_direct_dependency_flag equal to 0 indicates that the syntax element direct_dependency_type[i][j] is present.

default_direct_dependency_type, when present, specifies the inferred value of direct_dependency_type[i][j]. The length of the default_direct_dependency_type syntax element is direct_dep_type_len_minus2 + 2 bits. Although the value of default_direct_dependency_type is required to be in the range of 0 to 2, inclusive, in this version of this Specification, decoders shall allow values of default_direct_dependency_type in the range of 3 to $2^{32} - 2$, inclusive, to appear in the syntax.

direct_dependency_type[i][j] indicates the type of dependency between the layer with nuh_layer_id equal layer_id_in_nuh[i] and the layer with nuh_layer_id equal to layer_id_in_nuh[j]. direct_dependency_type[i][j] equal to 0 indicates that the layer with nuh_layer_id equal to layer_id_in_nuh[j] is used for inter-layer sample prediction but not for inter-layer motion prediction of the layer with nuh_layer_id equal layer_id_in_nuh[i]. direct_dependency_type[i][j] equal to 1 indicates that the layer with nuh_layer_id equal to layer_id_in_nuh[j] is used for inter-layer motion prediction but not for inter-layer sample prediction of the layer with nuh_layer_id equal layer_id_in_nuh[i]. direct_dependency_type[i][j] equal to 2 indicates that the layer with nuh_layer_id equal to layer_id_in_nuh[j] is used for both inter-layer motion prediction and inter-layer sample prediction of the layer with nuh_layer_id equal layer_id_in_nuh[i]. The length of the direct_dependency_type[i][j] syntax element is direct_dep_type_len_minus2 + 2 bits. Although the value of direct_dependency_type[i][j] shall be in the range of 0 to 2, inclusive, in this version of this Specification, decoders shall allow values of direct_dependency_type[i][j] in the range of 3 to $2^{32} - 2$, inclusive, to appear in the syntax.

When vps_base_layer_internal_flag is equal to 1 and direct_dependency_type[i][j] is not present, the value of direct_dependency_type[i][j] is inferred to be equal to default_direct_dependency_type.

When vps_base_layer_internal_flag is equal to 0, the value of direct_dependency_type[i][0] for i in the range of 1 to MaxLayersMinus1, inclusive, is inferred to be equal to 0.

The variables VpsInterLayerSamplePredictionEnabled[i][j] and VpsInterLayerMotionPredictionEnabled[i][j] are derived as follows:

$$VpsInterLayerSamplePredictionEnabled[i][j] = (direct\_dependency\_type[i][j] + 1) \& 0x1 \quad \text{(F-4)}$$

$$VpsInterLayerMotionPredictionEnabled[i][j] = (direct\_dependency\_type[i][j] + 1) \& 0x2 \quad \text{(F-5)}$$

vps_non_vui_extension_length specifies the length of the non-VUI VPS extension data following this syntax element and before vps_vui_present_flag, in bytes. The value of vps_non_vui_extension_length shall be in the range of 0 to 4096, inclusive.

vps_non_vui_extension_data_byte may have any value. Decoders shall ignore the value of vps_non_vui_extension_data_byte. Its value does not affect decoder conformance to profiles specified in this version of this Specification.

vps_vui_present_flag equal to 1 specifies that the vps_vui( ) syntax structure is present in the VPS. vps_vui_present_flag equal to 0 specifies that the vps_vui( ) syntax structure is not present in the VPS.

vps_vui_alignment_bit_equal_to_one shall be equal to 1.

F.7.4.3.1.2 Representation format semantics

chroma_and_bit_depth_vps_present_flag equal to 1 specifies that the syntax elements chroma_format_vps_idc, bit_depth_vps_luma_minus8, and bit_depth_vps_chroma_minus8 are present and that the syntax element separate_colour_plane_vps_flag might be present. chroma_and_bit_depth_vps_present_flag equal to 0 specifies that the syntax elements chroma_format_vps_idc, separate_colour_plane_vps_flag, bit_depth_vps_luma_minus8, and bit_depth_vps_chroma_minus8 are not present and are inferred from the previous rep_format( ) syntax structure in the VPS. The value of chroma_and_bit_depth_vps_present_flag of the first rep_format( ) syntax structure in the VPS shall be equal to 1.

pic_width_vps_in_luma_samples, **pic_height_vps_in_luma_samples**, **chroma_format_vps_idc**, **separate_colour_plane_vps_flag**, **bit_depth_vps_luma_minus8**, and **bit_depth_vps_chroma_minus8** are used for inference of the values of the SPS syntax elements pic_width_in_luma_samples, pic_height_in_luma_samples, chroma_format_idc, separate_colour_plane_flag, bit_depth_luma_minus8, and bit_depth_chroma_minus8, respectively, for each SPS that refers to the VPS. When not present in the i-th rep_format( ) syntax structure in the VPS, the value of each of these syntax elements is inferred to be equal to the value of the corresponding syntax element in the (i − 1)-th rep_format( ) syntax structure in the VPS. For each of these syntax elements, all constraints, if any, that apply to the value of the corresponding SPS syntax element also apply. [Ed. (GT) Consider explicit constraints here.].

F.7.4.3.1.3 DPB size semantics

For the lsIdx-th layer set, the number of sub-DPBs is NumLayersInIdList[lsIdx], and for each layer with a particular value of nuh_layer_id in the layer set, the sub-DPB with index layerIdx is assigned, where LayerSetLayerIdList[lsIdx][layerIdx] is equal to nuh_layer_id.

sub_layer_flag_info_present_flag[i] equal to 1 specifies that sub_layer_dpb_info_present_flag[i][j] is present for i in the range of 1 to MaxSubLayersInLayerSetMinus1[OlsIdxToLsIdx[i]], inclusive. sub_layer_flag_info_present_flag[i] equal to 0 specifies that, for each value of j greater than 0, sub_layer_dpb_info_present_flag[i][j] is not present and the value is inferred to be equal to 0.

sub_layer_dpb_info_present_flag[i][j] equal to 1 specifies that max_vps_dec_pic_buffering_minus1[i][k][j] is present for k in the range of 0 to NumLayersInIdList[OlsIdxToLsIdx[i]] − 1, inclusive, for the j-th sub-layer, and max_vps_num_reorder_pics[i][j] and max_vps_latency_increase_plus1[i][j] are present for the j-th sub-layer. sub_layer_dpb_info_present_flag[i][j] equal to 0 specifies that the values of max_vps_dec_pic_buffering_minus1[i][k][j] are equal to max_vps_dec_pic_buffering_minus1[i][k][j − 1] for k in the range of 0 to NumLayersInIdList[OlsIdxToLsIdx[i]] − 1, inclusive, and that the values max_vps_num_reorder_pics[i][j] and max_vps_latency_increase_plus1[i][j] are set equal to max_vps_num_reorder_pics[i][j − 1] and max_vps_latency_increase_plus1[i][j − 1], respectively. The value of sub_layer_dpb_info_present_flag[i][0] for any possible value of i is inferred to be equal to 1. When not present, the value of sub_layer_dpb_info_present_flag[i][j] for j greater than 0 and any possible value of i, is inferred to be equal to be equal to 0.

max_vps_dec_pic_buffering_minus1[i][k][j] plus 1 specifies the maximum number of decoded pictures, of the k-th layer for the CVS in the i-th OLS, that need to be stored in the DPB when HighestTid is equal to j. When j is greater than 0, max_vps_dec_pic_buffering_minus1[i][k][j] shall be greater than or equal to max_vps_dec_pic_buffering_minus1[i][k][j − 1]. When max_vps_dec_pic_buffering_minus1[i][k][j] is not present for j in the range of 1 to MaxSubLayersInLayerSetMinus1[OlsIdxToLsIdx[i]], inclusive, it is inferred to be equal to max_vps_dec_pic_buffering_minus1[i][k][j − 1]. The value of max_vps_dec_pic_buffering_minus1[0][0][j] is inferred to be equal to sps_max_dec_pic_buffering_minus1[j] of the active SPS of the base layer. [Ed. (YK): Consider adding a note to say that, within the scope of this VPS, the inference needs to be performed again when a new SPS is activated for the base layer that has a different value of sps_max_dec_pic_buffering_minus1[j], or other editorial changes if such inference is not appropriate. Similarly for the inferences of max_vps_num_reorder_pics[0][j] and max_vps_latency_increase_plus1[0][j] in below.]

max_vps_num_reorder_pics[i][j] specifies, when HighestTid is equal to j, the maximum allowed number of access units containing a picture with PicOutputFlag equal to 1 that can precede any access unit auA that contains a picture with PicOutputFlag equal to 1 in the i-th OLS in the CVS in decoding order and follow the access unit auA that contains a picture with PicOutputFlag equal to 1 in output order. When max_vps_num_reorder_pics[i][j] is not present for j in

the range of 1 to MaxSubLayersInLayerSetMinus1[OlsIdxToLsIdx[i]], inclusive, due to sub_layer_dpb_info_present_flag[i][j] being equal to 0, it is inferred to be equal to max_vps_num_reorder_pics[i][j − 1]. The value of max_vps_num_reorder_pics[0][j] is inferred to be equal to sps_max_num_reorder_pics[j] of the active SPS of the base layer.

max_vps_latency_increase_plus1[i][j] not equal to 0 is used to compute the value of VpsMaxLatencyPictures[i][j], which, when HighestTid is equal to j, specifies the maximum number of access units containing a picture with PicOutputFlag equal to 1 in the i-th OLS that can precede any access unit auA that contains a picture with PicOutputFlag equal to 1 in the CVS in output order and follow the access unit auA that contains a picture with PicOutputFlag equal to 1 in decoding order. When max_vps_latency_increase_plus1[i][j] is not present for j in the range of 1 to MaxSubLayersInLayerSetMinus1[OlsIdxToLsIdx[i]], inclusive, due to sub_layer_dpb_info_present_flag[i][j] being equal to 0, it is inferred to be equal to max_vps_latency_increase_plus1[i][j − 1]. The value of max_vps_latency_increase_plus1[0][j] is inferred to be equal to sps_max_latency_increase_plus1[j] of the active SPS of the base layer.

When max_vps_latency_increase_plus1[i][j] is not equal to 0, the value of VpsMaxLatencyPictures[i][j] is specified as follows:

$$VpsMaxLatencyPictures[i][j] = max\_vps\_num\_reorder\_pics[i][j] + max\_vps\_latency\_increase\_plus1[i][j] - 1 \quad \text{(F-6)}$$

When max_vps_latency_increase_plus1[i][j] is equal to 0, no corresponding limit is expressed. The value of max_vps_latency_increase_plus1[i][j] shall be in the range of 0 to $2^{32} − 2$, inclusive.

F.7.4.3.1.4 VPS VUI semantics

cross_layer_pic_type_aligned_flag equal to 1 specifies that within a CVS that refers to the VPS, all VCL NAL units that belong to an access unit have the same value of nal_unit_type. cross_layer_pic_type_aligned_flag equal to 0 specifies that within a CVS that refers to the VPS, all VCL NAL units in each access unit may or may not have the same value of nal_unit_type.

cross_layer_irap_aligned_flag equal to 1 specifies that IRAP pictures in the CVS are cross-layer aligned, i.e. when a picture pictureA of a layer layerA in an access unit is an IRAP picture, each picture pictureB in the same access unit that belongs to a direct reference layer of layerA or that belongs to a layer for which layerA is a direct reference layer of that layer is an IRAP picture and the VCL NAL units of pictureB have the same value of nal_unit_type as that of pictureA. cross_layer_irap_aligned_flag equal to 0 specifies that the above restriction may or may not apply. When not present, the value of cross_layer_irap_aligned_flag is inferred to be equal to vps_vui_present_flag.

all_layers_idr_aligned_flag equal to 1 indicates that within each access unit for which the VCL NAL units refer to the VPS, when one picture is an IRAP picture, all the pictures in the same access unit are IDR pictures and have the same value of nal_unit_type. all_layers_idr_aligned_flag equal to 0 specifies that the above restriction may or may not apply. When not present, the value of all_layers_idr_aligned_flag is inferred to be equal to 0.

bit_rate_present_vps_flag equal to 1 specifies that the syntax element bit_rate_present_flag[i][j] is present. bit_rate_present_vps_flag equal to 0 specifies that the syntax element bit_rate_present_flag[i][j] is not present.

pic_rate_present_vps_flag equal to 1 specifies that the syntax element pic_rate_present_flag[i][j] is present. pic_rate_present_vps_flag equal to 0 specifies that the syntax element pic_rate_present_flag[i][j] is not present.

bit_rate_present_flag[i][j] equal to 1 specifies that the bit rate information for the j-th subset of the i-th layer set is present. bit_rate_present_flag[i] equal to 0 specifies that the bit rate information for the j-th subset of the i-th layer set is not present. The j-th subset of a layer set is the output of the sub-bitstream extraction process when it is invoked with the layer set, j, and the layer identifier list associated with the layer set as inputs. When not present, the value of bit_rate_present_flag[i][j] is inferred to be equal to 0.

pic_rate_present_flag[i][j] equal to 1 specifies that picture rate information for the j-th subset of the i-th layer set is present. pic_rate_present_flag[i][j] equal to 0 specifies that picture rate information for the j-th subset of the i-th layer set is not present. When not present, the value of pic_rate_present_flag[i][j] is inferred to be equal to 0.

avg_bit_rate[i][j] indicates the average bit rate of the j-th subset of the i-th layer set, in bits per second. The value is given by BitRateBPS(avg_bit_rate[i][j]) with the function BitRateBPS( ) being specified as follows:

$$BitRateBPS(x) = (x \,\&\, (2^{14} - 1)) * 10^{(2 + (x >> 14))} \quad \text{(F-7)}$$

The average bit rate is derived according to the access unit removal time specified in clause F.13. In the following, bTotal is the number of bits in all NAL units of the j-th subset of the i-th layer set, t_1 is the removal time (in seconds) of the first access unit to which the VPS applies, and t_2 is the removal time (in seconds) of the last access unit (in decoding order) to which the VPS applies. With x specifying the value of avg_bit_rate[i][j], the following applies:

– If t_1 is not equal to t_2, the following condition shall be true:

$$(x \,\&\, (2^{14} - 1)) == \text{Round}(\text{bTotal} \div ((t_2 - t_1) * 10^{(2 + (x >> 14))})) \quad \text{(F-8)}$$

– Otherwise (t_1 is equal to t_2), the following condition shall be true:

$$(x \,\&\, (2^{14} - 1)) == 0 \quad \text{(F-9)}$$

max_bit_rate_layer[i][j] indicates an upper bound for the bit rate of the j-th subset of the i-th layer set in any one-second time window of access unit removal time as specified in clause F.13. The upper bound for the bit rate in bits per second is given by BitRateBPS(max_bit_rate_layer[i][j]). The bit rate values are derived according to the access unit removal time specified in clause F.13. In the following, t_1 is any point in time (in seconds), t_2 is set equal to $t_1 + 1 \div 100$, and bTotal is the number of bits in all NAL units of access units with a removal time greater than or equal to t_1 and less than t_2. With x specifying the value of max_bit_rate_layer[i][j], the following condition shall be obeyed for all values of t_1:

$$(x \,\&\, (2^{14} - 1)) >= \text{bTotal} \div ((t_2 - t_1) * 10^{(2 + (x >> 14))}) \quad \text{(F-10)}$$

constant_pic_rate_idc[i][j] indicates whether the picture rate of the j-th subset of the i-th layer set is constant. In the following, a temporal segment tSeg is any set of two or more consecutive access units, in decoding order, of the j-th subset of the i-th layer set, auTotal(tSeg) is the number of access units in the temporal segment tSeg, t_1(tSeg) is the removal time (in seconds) of the first access unit (in decoding order) of the temporal segment tSeg, t_2(tSeg) is the removal time (in seconds) of the last access unit (in decoding order) of the temporal segment tSeg, and avgPicRate(tSeg) is the average picture rate in the temporal segment tSeg, and is specified as follows:

$$\text{avgPicRate}(\text{tSeg}) == \text{Round}(\text{auTotal}(\text{tSeg}) * 256 \div (t_2(\text{tSeg}) - t_1(\text{tSeg}))) \quad \text{(F-11)}$$

If the j-th subset of the i-th layer set only contains one or two access units or the value of avgPicRate(tSeg) is constant over all the temporal segments, the picture rate is constant; otherwise, the picture rate is not constant.

constant_pic_rate_idc[i][j] equal to 0 indicates that the picture rate of the j-th subset of the i-th layer set is not constant. constant_pic_rate_idc[i][j] equal to 1 indicates that the picture rate of the j-th subset of the i-th layer set is constant. constant_pic_rate_idc[i][j] equal to 2 indicates that the picture rate of the j-th subset of the i-th layer set may or may not be constant. The value of constant_pic_rate_idc[i][j] shall be in the range of 0 to 2, inclusive.

avg_pic_rate[i] indicates the average picture rate, in units of picture per 256 seconds, of the j-th subset of the layer set. With auTotal being the number of access units in the j-th subset of the i-th layer set, t_1 being the removal time (in seconds) of the first access unit to which the VPS applies, and t_2 being the removal time (in seconds) of the last access unit (in decoding order) to which the VPS applies, the following applies:

– If t_1 is not equal to t_2, the following condition shall be true:

$$\text{avg\_pic\_rate}[i] == \text{Round}(\text{auTotal} * 256 \div (t_2 - t_1)) \quad \text{(F-12)}$$

– Otherwise (t_1 is equal to t_2), the following condition shall be true:

$$\text{avg\_pic\_rate}[i] == 0 \quad \text{(F-13)}$$

tiles_not_in_use_flag equal to 1 indicates that the value of tiles_enabled_flag is equal to 0 for each PPS that is referred to by at least one picture referring to the VPS. tiles_not_in_use_flag equal to 0 indicates that such a restriction may or may not apply. When not present, the value of tiles_not_in_use_flag is inferred to be equal to 0.

tiles_in_use_flag[i] equal to 1 indicates that the value of tiles_enabled_flag is equal to 1 for each PPS that is referred to by at least one picture of the i-th layer specified by the VPS. tiles_in_use_flag[i] equal to 0 indicates that such a restriction may or may not apply. When not present, the value of tiles_in_use_flag[i] is inferred to be equal to 0.

loop_filter_not_across_tiles_flag[i] equal to 1 indicates that the value of loop_filter_across_tiles_enabled_flag is equal to 0 for each PPS that is referred to by at least one picture of the i-th layer specified by the VPS. loop_filter_not_across_tiles_flag[i] equal to 0 indicates that such a restriction may or may not apply. When not present, the value of loop_filter_not_across_tiles_flag[i] is inferred to be equal to 0.

tile_boundaries_aligned_flag[i][j] equal to 1 indicates that, when any two samples of one picture of the i-th layer specified by the VPS belong to one tile, the two collocated samples, when both present in the picture of the j-th direct reference layer of the i-th layer, belong to one tile, and when any two samples of one picture of the i-th layer belong to different tiles, the two collocated samples, when both present in the picture of the j-th direct reference layer of the i-th layer belong to different tiles. tile_boundaries_aligned_flag equal to 0 indicates that such a restriction may or may not apply. When not present, the value of tile_boundaries_aligned_flag[i][j] is inferred to be equal to 0.

wpp_not_in_use_flag equal to 1 indicates that the value of entropy_coding_sync_enabled_flag is equal to 0 for each PPS that is referred to by at least one picture referring to the VPS. wpp_not_in_use_flag equal to 0 indicates that such a restriction may or may not apply. When not present, the value of wpp_not_in_use_flag is inferred to be equal to 0.

wpp_in_use_flag[i] equal to 1 indicates that the value of entropy_coding_sync_enabled_flag is equal to 1 for each PPS that is referred to by at least one picture of the i-th layer specified by the VPS. wpp_in_use_flag[i] equal to 0 indicates that such a restriction may or may not apply. When not present, the value of wpp_in_use_flag[i] is inferred to be equal to 0.

vps_vui_reserved_zero_3bits shall be equal to 0 in bitstreams conforming to this version of this Specification. Other values for vps_vui_reserved_zero_3bits are reserved for future use by ITU-T | ISO/IEC. Decoders shall ignore the value of vps_vui_reserved_zero_3bits.

[Ed. (JC): The vps_vui_reserved_zero_3bits will be used for the syntax elements single_layer_for_non_irap_flag, higher_layer_irap_skip_flag and vert_phase_position_in_use_flag in the SHVC draft.]

ilp_restricted_ref_layers_flag equal to 1 indicates that additional restrictions on inter-layer prediction as specified below apply for each direct reference layer of each layer specified by the VPS. ilp_restricted_ref_layers_flag equal to 0 indicates that additional restrictions on inter-layer prediction may or may not apply.

[Ed. (YK): Consider using better syntax element names for min_spatial_segment_offset_plus1[i][j], ctu_based_offset_enabled_flag[i][j], and min_horizontal_ctu_offset_plus1[i][j].]

The variables refCtbLog2SizeY[i][j], refPicWidthInCtbsY[i][j], and refPicHeightInCtbsY[i][j] are set equal to CtbLog2SizeY, PicWidthInCtbsY, and PicHeightInCtbsY, respectively, of the j-th direct reference layer of the i-th layer.

min_spatial_segment_offset_plus1[i][j] indicates the spatial region, in each picture of the j-th direct reference layer of the i-th layer, that is not used for inter-layer prediction for decoding of any picture of the i-th layer, by itself or together with min_horizontal_ctu_offset_plus1[i][j], as specified below. The value of min_spatial_segment_offset_plus1[i][j] shall be in the range of 0 to refPicWidthInCtbsY[i][j] * refPicHeightInCtbsY[i][j], inclusive. When not present, the value of min_spatial_segment_offset_plus1[i][j] is inferred to be equal to 0.

ctu_based_offset_enabled_flag[i][j] equal to 1 specifies that the spatial region, in units of CTUs, in each picture of the j-th direct reference layer of the i-th layer, that is not used for inter-layer prediction for decoding of any picture of the i-th layer is indicated by min_spatial_segment_offset_plus1[i][j] and min_horizontal_ctu_offset_plus1[i][j] together. ctu_based_offset_enabled_flag[i][j] equal to 0 specifies that the spatial region, in units of slice segments, tiles, or CTU rows, in each picture of the j-th direct reference layer of the i-th layer, that is not used for inter-layer prediction for decoding of any picture of the i-th layer is indicated by min_spatial_segment_offset_plus1[i] only. When not present, the value of ctu_based_offset_enabled_flag[i] is inferred to be equal to 0.

min_horizontal_ctu_offset_plus1[i][j], when ctu_based_offset_enabled_flag[i][j] is equal to 1, indicates the spatial region, in each picture of the j-th direct reference layer of the i-th layer, that is not used for inter-layer prediction for decoding of any picture of the i-th layer, together with min_spatial_segment_offset_plus1[i][j], as specified below. The value of min_horizontal_ctu_offset_plus1[i][j] shall be in the range of 0 to refPicWidthInCtbsY[i][j], inclusive.

When ctu_based_offset_enabled_flag[i][j] is equal to 1, the variable minHorizontalCtbOffset[i][j] is derived as follows:

$$minHorizontalCtbOffset[i][j] = (min\_horizontal\_ctu\_offset\_plus1[i][j] > 0) ? \quad (F\text{-}14)$$
$$(min\_horizontal\_ctu\_offset\_plus1[i][j] - 1) : (refPicWidthInCtbsY[i][j] - 1)$$

The variables curCtbLog2SizeY[i], curPicWidthInCtbsY[i], and curPicHeightInCtbsY[i] are set equal to CtbLog2SizeY, PicWidthInCtbsY, and PicHeightInCtbsY, respectively, of the i-th layer.

The variable colCtbAddr[i][j] that denotes the raster scan address of the collocated CTU, in a picture in the j-th direct reference layer of the i-th layer, of the CTU with raster scan address equal to ctbAddr in a picture of the i-th layer is derived as follows [Ed. (YK): Define "collocated CTU".]:

$$xAddrOfCtb[i][j] = (ctbAddr \% curPicWidthInCtbsY) << curCtbLog2SizeY \quad (F\text{-}15)$$

$$yAddrOfCtb[i][j] = (ctbAddr / curPicWidthInCtbsY) << curCtbLog2SizeY \quad (F\text{-}16)$$

$$xColCtb[i][j] = xAddrOfCtb[i][j] >> refCtbLog2SizeY[i][j] \quad (F\text{-}17)$$

$$yColCtb[i][j] = yAddrOfCtb[i][j] >> refCtbLog2SizeY[i][j] \quad (F\text{-}18)$$

$$colCtbAddr[i][j] = xColCtb[i][j] + (yColCtb[i][j] * refPicWidthInCtbsY[i][j]) \quad (F\text{-}19)$$

When min_spatial_segment_offset_plus1[i][j] is greater than 0, it is a requirement of bitstream conformance that the following shall apply:

- If ctu_based_offset_enabled_flag[i][j] is equal to 0, exactly one of the following applies:
  - In each PPS referred to by a picture in the j-th direct reference layer of the i-th layer, tiles_enabled_flag is equal to 0 and entropy_coding_sync_enabled_flag is equal to 0, and the following applies:
    - Let slice segment A be any slice segment of a picture of the i-th layer and ctbAddr be the raster scan address of the last CTU in slice segment A. Let slice segment B be the slice segment that belongs to the same access unit as slice segment A, belongs to the j-th direct reference layer of the i-th layer, and contains the CTU with raster scan address colCtbAddr[i][j]. Let slice segment C be the slice segment that is in the same picture as slice segment B and follows slice segment B in decoding order, and between slice segment B and that slice segment there are min_spatial_segment_offset_plus1[i] - 1 slice segments in decoding order. When slice segment C is present, the syntax elements of slice segment A are constrained such that no sample or syntax elements values in slice segment C or any slice segment of the same picture following C in decoding order are used for inter-layer prediction in the decoding process of any samples within slice segment A.
  - In each PPS referred to by a picture in the j-th direct reference layer of the i-th layer, tiles_enabled_flag is equal to 1 and entropy_coding_sync_enabled_flag is equal to 0, and the following applies:
    - Let tile A be any tile in any picture picA of the i-th layer and ctbAddr be the raster scan address of the last CTU in tile A. Let tile B be the tile that is in the picture picB belonging to the same access unit as picA and belonging to the j-th direct reference layer of the i-th layer and that contains the CTU with raster scan address colCtbAddr[i][j]. Let tile C be the tile that is also in picB and follows tile B in decoding order, and between tile B and that tile there are min_spatial_segment_offset_plus1[i] - 1 tiles in decoding order. When slice segment C is present, the syntax elements of tile A are constrained such that no sample or syntax elements values in tile C or any tile of the same picture following C in decoding order are used for inter-layer prediction in the decoding process of any samples within tile A.
  - In each PPS referred to by a picture in the j-th direct reference layer of the i-th layer, tiles_enabled_flag is equal to 0 and entropy_coding_sync_enabled_flag is equal to 1, and the following applies:
    - Let CTU row A be any CTU row in any picture picA of the i-th layer and ctbAddr be the raster scan address of the last CTU in CTU row A. Let CTU row B be the CTU row that is in the picture picB belonging to the same access unit as picA and belonging to the j-th direct reference layer of the i-th layer and that contains the CTU with raster scan address colCtbAddr[i][j]. Let CTU row C be the CTU row that is also in picB and follows CTU row B in decoding order, and between CTU row B and that CTU row there are min_spatial_segment_offset_plus1[i] - 1 CTU rows in decoding order. When CTU row C is present, the syntax elements of CTU row A are constrained such that no sample or syntax elements values in CTU row C or row of the same picture following C are used for inter-layer prediction in the decoding process of any samples within CTU row A.
- Otherwise (ctu_based_offset_enabled_flag[i][j] is equal to 1), the following applies:
  - The variable refCtbAddr[i][j] is derived as follows:

$$xOffset[i][j] = ((xColCtb[i][j] + minHorizontalCtbOffset[i][j]) > (refPicWidthInCtbsY[i][j] - 1)) ? (refPicWidthInCtbsY[i][j] - 1 - xColCtb[i][j]) : (minHorizontalCtbOffset[i][j]) \quad (F\text{-}20)$$

$$yOffset[i][j] = (min\_spatial\_segment\_offset\_plus1[i][j] - 1) * refPicWidthInCtbsY[i][j] \quad (F\text{-}21)$$

$$refCtbAddr[i][j] = colCtbAddr[i][j] + xOffset[i][j] + yOffset[i][j] \quad (F\text{-}22)$$

  - Let CTU A be any CTU in any picture picA of the i-th layer, and ctbAddr be the raster scan address ctbAddr of CTU A. Let CTU B be a CTU that is in the picture belonging to the same access unit as picA and belonging to the j-th direct reference layer of the i-th layer and that has raster scan address greater than refCtbAddr[i][j]. When CTU B is present, the syntax elements of CTU A are constrained such that no sample or syntax elements values in CTU B are used for inter-layer prediction in the decoding process of any samples within CTU A.

video_signal_info_idx_present_flag equal to 1 specifies that the syntax elements vps_num_video_signal_info_minus1, and vps_video_signal_info_idx[i] are present. video_signal_info_idx_present_flag equal to 0 specifies that the syntax elements vps_num_video_signal_info_minus1, and vps_video_signal_info_idx[i] are not present.

vps_num_video_signal_info_minus1 plus 1 specifies the number of the following video_signal_info( ) syntax

structures in the VPS. When not present, the value of vps_num_video_signal_info_minus1 is inferred to be equal to MaxLayersMinus1.

vps_video_signal_info_idx[i] specifies the index, into the list of video_signal_info( ) syntax structures in the VPS, of the video_signal_info( ) syntax structure that applies to the layer with nuh_layer_id equal to layer_id_in_nuh[i]. When vps_video_signal_info_idx[i] is not present, vps_video_signal_info_idx[i] is inferred to be equal to (video_signal_info_idx_present_flag ? 0 : i). The value of vps_video_signal_info_idx[i] shall be in the range of 0 to vps_num_video_signal_info_minus1, inclusive.

vps_vui_bsp_hrd_present_flag equal to 0 specifies that no bitstream partition HRD parameters are present in the VPS VUI. vps_vui_bsp_hrd_present_flag equal to 1 specifies that bitstream partition HRD parameters are present in the VPS VUI.

base_layer_parameter_set_compatibility_flag[i] equal to 1 specifies that the following constraints apply to the layer with nuh_layer_id equal to layer_id_in_nuh[i]. base_layer_parameter_set_compatibility_flag[i] equal to 0 specifies that the following constraints may or may not apply to the layer with nuh_layer_id equal to layer_id_in_nuh[i].

- Each coded slice segment NAL unit with nuh_layer_id value equal to layer_id_in_nuh[i] referring to the VPS shall refer to a PPS with nuh_layer_id value equal to 0.
- Each coded slice segment NAL unit with nuh_layer_id value equal to layer_id_in_nuh[i] referring to the VPS shall refer to a SPS with nuh_layer_id value equal to 0.
- The values of chroma_format_idc, separate_colour_plane_flag, pic_width_in_luma_samples, pic_height_in_luma_samples, bit_depth_luma_minus8, and bit_depth_chroma_minus8, respectively, of the active SPS for the layer with nuh_layer_id equal to layer_id_in_nuh[i] shall be the same as the values of chroma_format_idc, separate_colour_plane_flag, pic_width_in_luma_samples, pic_height_in_luma_samples, bit_depth_luma_minus8, and bit_depth_chroma_minus8, respectively, of the vps_rep_format_idx[i]-th rep_format( ) syntax structure in the active VPS.

F.7.4.3.1.5 Video signal info semantics

video_vps_format, **video_full_range_vps_flag**, **colour_primaries_vps**, **transfer_characteristics_vps**, **matrix_coeffs_vps** are used for inference of the values of the SPS VUI syntax elements video_format, video_full_range_flag, colour_primaries, transfer_characteristics, matrix_coeffs respectively, for each SPS that refers to the VPS.

For each of these syntax elements, all constraints, if any, that apply to the value of the corresponding SPS VUI syntax element also apply.

F.7.4.3.1.6 VPS VUI bitstream partition HRD parameters semantics

vps_num_bsp_hrd_parameters_minus1 plus 1 specifies the number of hrd_parameters( ) syntax structures present within the vps_vui_bsp_hrd_parameters( ) syntax structure. [Ed. (MH): Add the allowed value range for this syntax element.]

bsp_cprms_present_flag[i] equal to 1 specifies that the HRD parameters that are common for all sub-layers are present in the i-th hrd_parameters( ) syntax structure in the vps_vui_bsp_hrd_parameters( ) syntax structure. bsp_cprms_present_flag[i] equal to 0 specifies that the HRD parameters that are common for all sub-layers are not present in the i-th hrd_parameters( ) syntax structure in the vps_vui_bsp_hrd_parameters( ) syntax structure and are derived to be the same as the (i − 1)-th hrd_parameters( ) syntax structure in the in the vps_vui_bsp_hrd_parameters( ) syntax structure. bsp_cprms_present_flag[0] is inferred to be equal to 1.

num_bitstream_partitions[h] specifies the number of bitstream partitions for which HRD parameters are specified for the layer set with index h. [Ed. (MH): Add the allowed value range for this syntax element.]

layer_in_bsp_flag[h][i][j] specifies that the layer with index j is a part of bitstream partition with index i within the layer set with index h.

It is a requirement of bitstream conformance that the following constraints apply:

- The bitstream partition with index j shall not include direct or indirect reference layers of any layers in bitstream partition i for any values of i and j in the range of 0 to num_bitstream_partitions[h] − 1, inclusive, such that i is less than j.
- When vps_base_layer_internal_flag is equal to 0 and layer_in_bsp_flag[h][i][0] is equal to 1 for any value of h in the range of 1 to vps_num_layer_sets_minus1, inclusive, and any value of i in the range of 0 to num_bitstream_partitions[h] − 1, inclusive, the value of layer_in_bsp_flag[h][i][j] for at least one value of j in the range of 1 to NumLayersInIdList[h] − 1, inclusive, shall be equal to 1.

[Ed. (GT): The following item corresponds to items 5/6 in Q0101 and might, according to meeting notes, require further alignment for the case that the base layer is externally specified.]

- When num_bitstream_partitions[h] is equal to 1 for any value of h in the range 1 to vps_num_layer_set_minus1, inclusive, the value of layer_in_bsp_flag[h][0][j] should be equal to 0 for at least one value of j in the range 0 to NumLayersInIdList[h] − 1, inclusive. [Ed. (MH): Supposedly "should" in this sentence is meant to be "shall", as otherwise the sentence would not specify a constraint.] [Ed. (MH): It should be considered whether a constraint that "num_bitstream_partitions[h] shall not be equal to 1" would be better.]

- For any value of h in the range 1 to vps_num_layer_set_minus1, inclusive, the value of layer_in_bsp_flag[h][i][j] shall be equal to 1 for at most one value of i in the range of 0 to num_bitstream_partitions[h] − 1, inclusive. [Ed. (MH): I think "at most" should be replaced by "exactly", because a partitioning specifies the mapping of each layer to a bitstream partition.]

num_bsp_sched_combinations_minus1[h] plus 1 specifies the number of combinations of delivery schedules and hrd_parameters( ) specified for bitstream partitions for the layer set with index h. [Ed. (MH): Add the allowed value range for this syntax element.]

The variable SchedCombCnt[h] is set equal to num_bsp_sched_combinations_minus1[h] + 1.

bsp_comb_hrd_idx[h][i][j] specifies the index of hrd_parameters( ) within the vps_vui_bsp_hrd_parameters( ) syntax structure used in the i-th combination of a delivery schedule and hrd_parameters( ) specified for the bitstream partition with index j and for the layer set with index h. The length of the bsp_comb_hrd_idx[h][i][j] syntax element is Ceil(Log2(vps_num_bsp_hrd_parameters_minus1 + 1)) bits. The value of bsp_comb_hrd_idx[h][i][j] shall be in the range of 0 to vps_num_bsp_hrd_parameters_minus1, inclusive.

bsp_comb_sched_idx[h][i][j] specifies the index of a delivery schedule within the hrd_parameters( ) syntax structure with the index bsp_comb_hrd_idx[h][i][j] that is used in the i-th combination of a delivery schedule and hrd_parameters( ) specified for the bitstream partition with index j and for the layer set with index h. The value of bsp_comb_sched_idx[h][i][j] shall be in the range of 0 to cpb_cnt_minus1[HighestTid], inclusive, where cpb_cnt_minus1[HighestTid] is found in the sub_layer_hrd_parameters(HighestTid) syntax structure from the hrd_parameters( ) syntax structure corresponding to the index bsp_comb_hrd_idx[h][i][j]. [Ed. (YK): Both forms of "sub_layer_hrd_parameters(HighestTid)" and "sub_layer_hrd_parameters( )" are used in the document for referencing of the syntax structure. Check whether it would be better to consistently use just one of them.]

F.7.4.3.2 Sequence parameter set RBSP semantics

The specifications in subclause 7.4.3.2 apply, with following additions and modifications.

sps_max_sub_layers_minus1 plus 1 specifies the maximum number of temporal sub-layers that may be present in each CVS referring to the SPS. The value of sps_max_sub_layers_minus1 shall be in the range of 0 to 6, inclusive. When not present sps_max_sub_layers_minus1 is inferred to be equal to vps_max_sub_layers_minus1.

sps_temporal_id_nesting_flag, when sps_max_sub_layers_minus1 is greater than 0, specifies whether inter prediction is additionally restricted for CVSs referring to the SPS. When vps_temporal_id_nesting_flag is equal to 1, sps_temporal_id_nesting_flag shall be equal to 1. When sps_max_sub_layers_minus1 is equal to 0, sps_temporal_id_nesting_flag shall be equal to 1. When not present, the value of sps_temporal_id_nesting_flag is inferred as follows:

– If sps_max_sub_layers_minus1 is greater than 0, the value of sps_temporal_id_nesting_flag is inferred to be equal to vps_temporal_id_nesting_flag.

– Otherwise, the value of sps_temporal_id_nesting_flag is inferred to be equal to 1.

NOTE 1 – The syntax element sps_temporal_id_nesting_flag is used to indicate that temporal up-switching, i.e. switching from decoding up to any TemporalId tIdN to decoding up to any TemporalId tIdM that is greater than tIdN, is always possible in the CVS.

update_rep_format_flag equal to 1 specifies that sps_rep_format_idx is present and that the sps_rep_format_idx-th rep_format( ) syntax structures in the active VPS applies to the layers that refer to this SPS. update_rep_format_flag equal to 0 specifies that sps_rep_format_idx is not present. When not present, the value of update_rep_format_flag is inferred to be equal to 0. When the value of vps_num_rep_formats_minus1 in the active VPS is equal to 0, it is a requirement of bitstream conformance that the value of update_rep_format_flag shall be equal to 0.

sps_rep_format_idx specifies the index, into the list of rep_format( ) syntax structures in the VPS, of the rep_format( ) syntax structure that applies to the layers that refer to this SPS. When not present, the value of sps_rep_format_idx is inferred to be equal to 0. The value of sps_rep_format_idx shall be in the range of 0 to vps_num_rep_formats_minus1, inclusive. [Ed. (GT): Inferences to 0 seems not to be necessary. We might consider to infer it to vps_rep_format_idx[LayerIdxInVps[layerIdCurr]], when not present.]

When a current picture with nuh_layer_id layerIdCurr greater than 0 refers to an SPS, the values of chroma_format_idc, separate_colour_plane_flag, pic_width_in_luma_samples, pic_height_in_luma_samples, bit_depth_luma_minus8, and bit_depth_chroma_minus8 are inferred or constrained as follows:

– The variable repFormatIdx is derived as follows:
  – If update_rep_format_flag is equal to 0, the variable repFormatIdx is set equal to vps_rep_format_idx[LayerIdxInVps[layerIdCurr]].
  – Otherwise, (update_rep_format_flag is equal to 1), the variable repFormatIdx is set equal to sps_rep_format_idx.
– If the nuh_layer_id of the active SPS for the layer with nuh_layer_id equal to layerIdCurr is equal to 0, the values of chroma_format_idc, separate_colour_plane_flag, pic_width_in_luma_samples, pic_height_in_luma_samples, bit_depth_luma_minus8, and bit_depth_chroma_minus8 are inferred to be equal to chroma_format_vps_idc, separate_colour_plane_vps_flag, pic_width_vps_in_luma_samples, pic_height_vps_in_luma_samples, bit_depth_vps_luma_minus8, and bit_depth_vps_chroma_minus8, respectively, of the repFormatIdx-th rep_format( ) syntax structure in the active VPS and the values of chroma_format_idc, separate_colour_plane_flag, pic_width_in_luma_samples, pic_height_in_luma_samples, bit_depth_luma_minus8, and bit_depth_chroma_minus8 of the active SPS for the layer with nuh_layer_id equal to layerIdCurr are ignored.

  NOTE 2 – The values are inferred from the VPS when a non-base layer refers to an SPS that is also referred to by the base layer, in which case the SPS has nuh_layer_id equal to 0. For the base layer, the values of these parameters in the active SPS for the base layer apply.

– Otherwise (the nuh_layer_id of the active SPS for the layer with nuh_layer_id equal to layerIdCurr is greater than zero), the following applies:
  – The values of chroma_format_idc, separate_colour_plane_flag, pic_width_in_luma_samples, pic_height_in_luma_samples, bit_depth_luma_minus8, and bit_depth_chroma_minus8 are inferred to be equal to chroma_format_vps_idc, separate_colour_plane_vps_flag, pic_width_vps_in_luma_samples, pic_height_vps_in_luma_samples, bit_depth_vps_luma_minus8, and bit_depth_vps_chroma_minus8, respectively, of the repFormatIdx-th rep_format( ) syntax structure in the active VPS.
  – When update_rep_format_flag is equal to 1, it is a requirement of bitstream conformance that the value of chroma_format_idc, separate_colour_plane_flag, pic_width_in_luma_samples, pic_height_in_luma_samples, bit_depth_luma_minus8, or bit_depth_chroma_minus8 shall be less than or equal to chroma_format_vps_idc, separate_colour_plane_vps_flag, pic_width_vps_in_luma_samples, pic_height_vps_in_luma_samples, bit_depth_vps_luma_minus8, or bit_depth_vps_chroma_minus8, respectively, of the vps_rep_format_idx[j]-th rep_format( ) syntax structure in the active VPS, where j is equal to LayerIdxInVps[layerIdCurr].

chroma_format_idc specifies the chroma sampling relative to the luma sampling as specified in subclause 6.2. The value of chroma_format_idc shall be in the range of 0 to 3, inclusive. The value of chroma_format_idc shall be less than or equal to chroma_format_vps_idc. [Ed. (GT): These requirements seem to be redundant now. We should consider to remove them.]

It is a requirement of bitstream conformance that when AuxId[lId] is equal to AUX_ALPHA or AUX_DEPTH, chroma_format_idc shall be equal to 0 in the active SPS for the layer with nuh_layer_id equal to lId.

separate_colour_plane_flag equal to 1 specifies that the three colour components of the 4:4:4 chroma format are coded separately. separate_colour_plane_flag equal to 0 specifies that the colour components are not coded separately. When separate_colour_plane_flag is not present, it is inferred to be equal to 0. When separate_colour_plane_flag is equal to 1, the coded picture consists of three separate components, each of which consists of coded samples of one colour plane (Y, Cb, or Cr) and uses the monochrome coding syntax. In this case, each colour plane is associated with a specific colour_plane_id value. The value of separate_colour_plane_flag shall be less than or equal to separate_colour_plane_vps_flag

NOTE 3 – There is no dependency in decoding processes between the colour planes having different colour_plane_id values. For example, the decoding process of a monochrome picture with one value of colour_plane_id does not use any data from monochrome pictures having different values of colour_plane_id for inter prediction.

Depending on the value of separate_colour_plane_flag, the value of the variable ChromaArrayType is assigned as follows:

– If separate_colour_plane_flag is equal to 0, ChromaArrayType is set equal to chroma_format_idc.
– Otherwise (separate_colour_plane_flag is equal to 1), ChromaArrayType is set equal to 0.

pic_width_in_luma_samples specifies the width of each decoded picture in units of luma samples. pic_width_in_luma_samples shall not be equal to 0 and shall be an integer multiple of MinCbSizeY. The value of pic_width_in_luma_samples shall be less than or equal to pic_width_vps_in_luma_samples.

pic_height_in_luma_samples specifies the height of each decoded picture in units of luma samples. pic_height_in_luma_samples shall not be equal to 0 and shall be an integer multiple of MinCbSizeY. The value of pic_height_in_luma_samples shall be less than or equal to pic_height_vps_in_luma_samples.

bit_depth_luma_minus8 specifies the bit depth of the samples of the luma array $BitDepth_Y$ and the value of the luma quantization parameter range offset $QpBdOffset_Y$ as follows:

$$BitDepth_Y = 8 + bit\_depth\_luma\_minus8 \quad (F-23)$$

$$QpBdOffset_Y = 6 * bit\_depth\_luma\_minus8 \quad (F-24)$$

bit_depth_luma_minus8 shall be in the range of 0 to 6, inclusive. bit_depth_luma_minus8 shall be less than or equal to bit_depth_vps_luma_minus8.

bit_depth_chroma_minus8 specifies the bit depth of the samples of the chroma arrays $BitDepth_C$ and the value of the chroma quantization parameter range offset $QpBdOffset_C$ as follows:

$$BitDepth_C = 8 + bit\_depth\_chroma\_minus8 \quad (F-25)$$

$$QpBdOffset_C = 6 * bit\_depth\_chroma\_minus8 \quad (F-26)$$

bit_depth_chroma_minus8 shall be in the range of 0 to 6, inclusive. bit_depth_chroma_minus8 shall be less than or equal to bit_depth_vps_chroma_minus8.

sps_max_dec_pic_buffering_minus1[i] plus 1 specifies the maximum required size of the decoded picture buffer for the CVS in units of picture storage buffers when HighestTid is equal to i. The value of sps_max_dec_pic_buffering_minus1[i] shall be in the range of 0 to MaxDpbSize − 1 (as specified in subclause A.4), inclusive. When i is greater than 0, sps_max_dec_pic_buffering_minus1[i] shall be greater than or equal to sps_max_dec_pic_buffering_minus1[i − 1]. The value of sps_max_dec_pic_buffering_minus1[i] shall be less than or equal to vps_max_dec_pic_buffering_minus1[i] for each value of i. When sps_max_dec_pic_buffering_minus1[i] is not present for i in the range of 0 to sps_max_sub_layers_minus1 − 1, inclusive, due to sps_sub_layer_ordering_info_present_flag being equal to 0, it is inferred to be equal to sps_max_dec_pic_buffering_minus1[sps_max_sub_layers_minus1].

When sps_max_dec_pic_buffering_minus1[i] is not present for i in the range of 0 to sps_max_sub_layers_minus1, inclusive, due to nuh_layer_id being greater than 0, for a layer that refers to the SPS and has nuh_layer_id equal to currLayerId, the value of sps_max_dec_pic_buffering_minus1[i] is inferred to be equal to max_vps_dec_pic_buffering_minus1[TargetOlsIdx][layerIdx][i] of the active VPS, where layerIdx is equal to the value such that LayerSetLayerIdList[TargetDecLayerSetIdx][layerIdx] is equal to currLayerId.

sps_infer_scaling_list_flag equal to 1 specifies that the syntax elements of the scaling list data syntax structure of the SPS are inferred to be equal to those of the SPS that is active for the layer with nuh_layer_id equal to sps_scaling_list_ref_layer_id. sps_infer_scaling_list_flag equal to 0 specifies that the syntax elements of the scaling list data syntax structure are not inferred. When not present, the value of sps_infer_scaling_list_flag is inferred to be 0.

sps_scaling_list_ref_layer_id specifies the value of the nuh_layer_id of the layer for which the active SPS is associated with the same scaling list data as the current SPS.

The value of sps_scaling_list_ref_layer_id shall be in the range of 0 to 62, inclusive.

When vps_base_layer_internal_flag is equal to 0, it is a requirement of bitstream conformance that the value of sps_scaling_list_ref_layer_id, when present, shall be greater than 0. [Ed. (JB): Should an inference value be added when not present?]

It is a requirement of bitstream conformance that, when an SPS with nuh_layer_id equal to nuhLayerIdA is active for a layer with nuh_layer_id equal to nuhLayerIdB and sps_infer_scaling_list_flag in the SPS is equal to 1, sps_infer_scaling_list_flag shall be equal to 0 for the SPS that is active for the layer with nuh_layer_id equal to sps_scaling_list_ref_layer_id. [Ed. (YK): This constraint is not necessarily needed. It would be nice to allow for all SPSs recursively infer the scaling list data from the lowest HEVC layer, when desirable, as that does not impose any additional decoder complexity anyway.]

It is a requirement of bitstream conformance that, when an SPS with nuh_layer_id equal to nuhLayerIdA is active for a layer with nuh_layer_id equal to nuhLayerIdB, the layer with nuh_layer_id equal to sps_scaling_list_ref_layer_id shall be a direct or indirect reference layer of the layer with nuh_layer_id equal to nuhLayerIdB.

sps_scaling_list_data_present_flag equal to 1 specifies that the scaling list data syntax structure is present in the SPS. sps_scaling_list_data_present_flag equal to 0 specifies that the scaling list data syntax structure is not present in the SPS. When not present, the value of sps_scaling_list_data_present_flag is inferred to be equal to 0.

sps_extension_present_flag equal to 1 specifies that the syntax elements sps_range_extensions_flag, sps_multilayer_extension_flag, and sps_extension_6bits are present in the SPS RBSP syntax structure. sps_extension_present_flag equal to 0 specifies that these syntax elements are not present.

sps_range_extensions_flag equal to 1 specifies that the sps_range_extensions( ) syntax structure is present in the SPS RBSP syntax structure. sps_range_extensions_flag equal to 0 specifies that the sps_range_extensions( ) syntax structure is not present. When not present, the value of sps_range_extensions_flag is inferred to be equal to 0.

sps_multilayer_extension_flag equal to 1 specifies that the sps_multilayer_extension( ) syntax structure is present in the SPS RBSP syntax structure. sps_multilayer_extension_flag equal to 0 specifies that the sps_multilayer_extension( ) syntax structure is not present. When not present, the value of sps_multilayer_extension_flag is inferred to be equal to 0.

sps_extension_6bits equal to 0 specifies that no sps_extension_data_flag syntax elements are present in the SPS RBSP syntax structure. When present, sps_extension_6bits shall be equal to 0 in bitstreams conforming to this version of this Specification. Values of sps_extension_6bits not equal to 0 are reserved for future use by ITU-T | ISO/IEC. Decoders shall allow the value of sps_extension_6bits to be not equal to 0 and shall ignore all sps_extension_data_flag syntax elements in an SPS NAL unit. When not present, the value of sps_extension_6bits is inferred to be equal to 0.

F.7.4.3.2.1 Sequence parameter set multilayer extension semantics

inter_view_mv_vert_constraint_flag equal to 1 specifies that vertical component of motion vectors used for inter-layer prediction are constrained in the CVS. When inter_view_mv_vert_constraint_flag is equal to 1, the vertical component of the motion vectors used for inter-layer prediction shall be equal to or less than 56 in units of luma samples. When inter_view_mv_vert_constraint_flag is equal to 0, no constraint for of the vertical component of the motion vectors used for inter-layer prediction is signalled by this flag. When not present, the inter_view_mv_vert_constraint_flag is inferred to be equal to 0.

num_scaled_ref_layer_offsets specifies the number of sets of scaled reference layer offset parameters that are present in the SPS. The value of num_scaled_ref_layer_offsets shall be in the range of 0 to 62, inclusive. [Ed. (JB): Should consider if this constraint should be further restricted. Is there a limit on the number of direct reference layers? (MH): If that is desirable, we should specify the range like this: "in the range of 0 to highestActiveLayerId, inclusive, where the variable highestActiveLayerId is equal to the greatest value of nuh_layer_id of any picture for which this SPS is the active SPS".]

The i-th scaled reference layer offset parameters specify the spatial correspondence of a picture referring to this SPS relative to an associated inter-layer picture with nuh_layer_id equal to scaled_ref_layer_id[i]. If the layer with nuh_layer_id equal to scaled_ref_layer_id[i] is a direct reference layer of the current picture, the associated inter-layer picture is the picture that is or could be included in the reference picture lists of the current picture. Otherwise, the associated inter-layer picture is any picture with nuh_layer_id equal to scaled_ref_layer_id[i]. [Ed. (MH): If the term associated inter-layer picture becomes needed in other parts of the specification too, move the definition to F.3.]

NOTE 1 – When spatial scalability is in use, the associated inter-layer picture is a resampled picture of a direct reference layer.

NOTE 2 – scaled_ref_layer_id[i] need not be among the direct reference layers for example when the spatial correspondence of an auxiliary picture to its associated primary picture is specified.

scaled_ref_layer_id[i] specifies the nuh_layer_id value of the associated inter-layer picture for which scaled_ref_layer_left_offset[i], scaled_ref_layer_top_offset[i], scaled_ref_layer_right_offset[i] and scaled_ref_layer_bottom_offset[i] are specified. The value of scaled_ref_layer_id[i] shall be less than the nuh_layer_id of any layer for which this SPS is the active SPS. [Ed. (MH): A constraint that scaled reference offsets shall not be used for Stereo Main profile was added in the profile specification.]

scaled_ref_layer_left_offset[scaled_ref_layer_id[i]] specifies the horizontal offset between the top-left luma sample of the associated inter-layer picture with nuh_layer_id equal to scaled_ref_layer_id[i] and the top-left luma sample of the current picture in units of two luma samples. When not present, the value of scaled_ref_layer_left_offset[scaled_ref_layer_id[i]] is inferred to be equal to 0.

scaled_ref_layer_top_offset[scaled_ref_layer_id[i]] specifies the vertical offset between the top-left luma sample of the associated inter-layer picture with nuh_layer_id equal to scaled_ref_layer_id[i] and the top-left luma sample of the current picture in units of two luma samples. When not present, the value of scaled_ref_layer_top_offset[scaled_ref_layer_id[i]] is inferred to be equal to 0.

scaled_ref_layer_right_offset[scaled_ref_layer_id[i]] specifies the horizontal offset between the bottom-right luma sample of the associated inter-layer picture with nuh_layer_id equal to scaled_ref_layer_id[i] and the bottom-right luma sample of the current picture in units of two luma samples. When not present, the value of scaled_ref_layer_right_offset[scaled_ref_layer_id[i]] is inferred to be equal to 0.

scaled_ref_layer_bottom_offset[scaled_ref_layer_id[i]] specifies the vertical offset between the bottom-right luma sample of the associated inter-layer picture with nuh_layer_id equal to scaled_ref_layer_id[i] and the bottom-right luma sample of the current picture in units of two luma samples. When not present, the value of

scaled_ref_layer_bottom_offset[scaled_ref_layer_id[i]] is inferred to be equal to 0.

sps_multilayer_ext_reserved_zero_flag[scaled_ref_layer_id[i]] shall be equal to 0 in bitstreams conforming to this version of this Specification. Other value for sps_multilayer_ext_reserved_zero_flag[scaled_ref_layer_id[i]] are reserved for future use by ITU-T | ISO/IEC. Decoders shall ignore the value of sps_multilayer_extension_reserved_zero_flag[scaled_ref_layer_id[i]].

[Ed. (JC): The sps_multilayer_ext_reserved_zero_flag will be used for the syntax vert_phase_position_enable_flag in the SHVC draft.]

F.7.4.3.3 Picture parameter set RBSP semantics

The specifications in subclause 7.4.3.3 apply, with the following modifications:

num_extra_slice_header_bits specifies the number of extra slice header bits that are present in the slice header RBSP for coded pictures referring to the PPS. num_extra_slice_header_bits shall be in the range of 0 to 2, inclusive, in bitstreams conforming to this version of this Specification. Other values for num_extra_slice_header_bits are reserved for future use by ITU-T | ISO/IEC. However, decoders shall allow num_extra_slice_header_bits to have any value.

pps_infer_scaling_list_flag equal to 1 specifies that the syntax elements of the scaling list data syntax structure of the PPS are inferred to be equal to those of the PPS that is active for the layer with nuh_layer_id equal to pps_scaling_list_ref_layer_id. pps_infer_scaling_list_flag equal to 0 specifies that the syntax elements of the scaling list data syntax structure of the PPS are not inferred. When not present, the value of pps_infer_scaling_list_flag is inferred to be 0.

pps_scaling_list_ref_layer_id specifies the value of the nuh_layer_id of the layer for which the active PPS has the same scaling list data as the current PPS.

The value of pps_scaling_list_ref_layer_id shall be in the range of 0 to 62, inclusive.

When vps_base_layer_internal_flag is equal to 0, it is a requirement of bitstream conformance that pps_scaling_list_ref_layer_id, when present, shall be greater than 0. [Ed. (JB): Should an inference value be added when not present?]

It is a requirement of bitstream conformance that, when a PPS with nuh_layer_id equal to nuhLayerIdA is active for a layer with nuh_layer_id equal to nuhLayerIdB and pps_infer_scaling_list_flag in the PPS is equal to 1, pps_infer_scaling_list_flag shall be equal to 0 for the PPS that is active for the layer with nuh_layer_id equal to pps_scaling_list_ref_layer_id.

It is a requirement of bitstream conformance that, when a PPS with nuh_layer_id equal to nuhLayerIdA is active for a layer with nuh_layer_id equal to nuhLayerIdB, the layer with nuh_layer_id equal to pps_scaling_list_ref_layer_id shall be a direct or indirect reference layer of the layer with nuh_layer_id equal to nuhLayerIdB.

pps_scaling_list_data_present_flag equal to 1 specifies that parameters are present in the PPS to modify the scaling lists specified by the active SPS. pps_scaling_list_data_present_flag equal to 0 specifies that the scaling list data used for the pictures referring to the PPS are inferred to be equal to those specified by the active SPS. When scaling_list_enabled_flag is equal to 0, the value of pps_scaling_list_data_present_flag shall be equal to 0. When scaling_list_enabled_flag is equal to 1, sps_scaling_list_data_present_flag is equal to 0, and pps_scaling_list_data_present_flag is equal to 0, the default scaling list data are used to derive the array ScalingFactor as specified in subclause 7.4.5.

pps_extension_present_flag equal to 1 specifies that the syntax elements pps_range_extensions_flag, pps_multilayer_extension_flag, and pps_extension_6bits, are present in the PPS RBSP syntax structure. pps_extension_present_flag equal to 0 specifies that these syntax elements are not present.

pps_range_extensions_flag equal to 1 specifies that the pps_range_extensions( ) syntax structure is present in the PPS RBSP syntax structure. pps_range_extensions_flag equal to 0 specifies that the pps_range_extensions( ) syntax structure is not present. When not present, the value of pps_range_extensions_flag is inferred to be equal to 0.

pps_multilayer_extension_flag equal to 1 specifies that the poc_reset_info_present_flag and pps_extension_reserved_zero_flag syntax elements are present in the PPS RBSP syntax structure. pps_multilayer_extension_flag equal to 0 specifies that the poc_reset_info_present_flag and pps_extension_reserved_zero_flag syntax elements are not present. When not present, the value of pps_multilayer_extension_flag is inferred to be equal to 0.

pps_extension_6bits equal to 0 specifies that no pps_extension_data_flag syntax elements are present in the PPS RBSP syntax structure. When present, pps_extension_6bits shall be equal to 0 in bitstreams conforming to this version of this Specification. Values of pps_extension_6bits not equal to 0 are reserved for future use by ITU-T | ISO/IEC. Decoders shall allow the value of pps_extension_6bits to be not equal to 0 and shall ignore all pps_extension_data_flag syntax elements in a PPS NAL unit. When not present, the value of pps_extension_6bits is inferred to be equal to 0.

poc_reset_info_present_flag equal to 0 specifies that the syntax element poc_reset_idc is not present in the slice segment headers of the slices referring to the PPS. poc_reset_info_present_flag equal to 1 specifies that the syntax element poc_reset_idc is present in the slice segment headers of the slices referring to the PPS. When not present, the value of poc_reset_info_present_flag is inferred to be equal to 0.

pps_extension_reserved_zero_flag shall be equal to 0 in bitstreams conforming to this version of this Specification. Other value for pps_extension_reserved_zero_flag are reserved for future use by ITU-T | ISO/IEC. Decoders shall ignore the value of pps_extension_reserved_zero_flag.

[Ed. (JC): The pps_extension_reserved_zero_flag will be used for the syntax colour_mapping_enabled_flag in the SHVC draft.]

F.7.4.3.4 Supplemental enhancement information RBSP semantics

The specifications in subclause 7.4.3.4 apply.

F.7.4.3.5 Access unit delimiter RBSP semantics

The specifications in subclause 7.4.3.5 apply.

F.7.4.3.6 End of sequence RBSP semantics

The specifications in subclause 7.4.3.6 apply.

F.7.4.3.7 End of bitstream RBSP semantics

The specifications in subclause 7.4.3.7 apply.

F.7.4.3.8 Filler data RBSP semantics

The specifications in subclause 7.4.3.8 apply.

F.7.4.3.9 Slice segment layer RBSP semantics

The specifications in subclause 7.4.3.9 apply.

F.7.4.3.10 RBSP slice segment trailing bits semantics

The specifications in subclause 7.4.3.10 apply.

F.7.4.3.11 RBSP trailing bits semantics

The specifications in subclause 7.4.3.11 apply.

F.7.4.3.12 Byte alignment semantics

The specifications in subclause 7.4.3.12 apply.

F.7.4.4 Profile, tier and level semantics

If vps_base_layer_internal_flag is equal to 0 and the profile_tier_level( ) syntax structure is the first profile_tier_level( ) syntax structure in the VPS, all bits in the syntax structure shall be equal to 0 and decoders shall ignore the syntax structure. Otherwise, the semantics of the profile_tier_level( ) syntax structure are specified by the remaining part of the current subclause.

The profile_tier_level( ) syntax structure provides profile, tier and level to which an OLS conforms. When the profile_tier_level( ) syntax structure is included in a vps_extension( ) syntax structure, the profile_tier_level_idx[i] syntax element of the vps_extension( ) syntax structure specifies which profile_tier_level( ) syntax structure applies to the i-th OLS. When num_add_layer_sets is greater than 0 and i is in the range of FirstAddLayerSetIdx to LastAddLayerSetIdx, inclusive, the profile_tier_level( ) syntax structure identified by profile_tier_level_idx[i] applies to the output of the non-base layer subtree extraction process of subclause F.10.2 with the input variable lsIdx set equal to OlsIdxToLsIdx[i]. When the profile_tier_level( ) syntax structure is included in a VPS, but not in a vps_extension( ) syntax structure, it applies to the 0-th OLS. When the profile_tier_level( ) syntax structure is included in an active SPS for the base layer, it applies to the 0-th OLS. When the profile_tier_level( ) syntax structure is included in an active SPS for an independent non-base layer with nuh_layer_id equal to layerId, it applies to the 0-th OLS in an output bitstream of the non-base layer subtree extraction process of subclause F.10.2 with an input parameter lsIdx such that AssignedBaseLayerId[lsIdx] is equal to layerId.

For interpretation of the following semantics, CVS refers to the CVS subset associated with the layer set to which the profile_tier_level( ) syntax structure applies.

When the syntax elements general_profile_space, general_tier_flag, general_profile_idc, general_profile_compatibility_flag[j], general_progressive_source_flag, general_interlaced_source_flag, general_non_packed_constraint_flag, general_frame_only_constraint_flag, general_reserved_zero_44bits are not present, they are inferred to be equal to the corresponding values of the (ptlIdx − 1)-th profile_tier_level( ) syntax structure in the VPS extension.

When the syntax elements sub_layer_profile_space[i], sub_layer_tier_flag[i], sub_layer_profile_idc[i], sub_layer_profile_compatibility_flag[i][j], sub_layer_progressive_source_flag[i], sub_layer_interlaced_source_flag[i], sub_layer_non_packed_constraint_flag[i], sub_layer_frame_only_constraint_flag[i], sub_layer_reserved_zero_44bits[i] are not present, they are inferred to be equal to the corresponding values of (ptlIdx − 1)-th profile_tier_level( ) syntax structure in the VPS extension.

The specifications in subclause 7.4.4 apply, with following modifications.

general_tier_flag specifies the tier context for the interpretation of general_level_idc as specified in Annex A or subclause G.11.

general_profile_idc, when general_profile_space is equal to 0, indicates a profile to which the CVS conforms as specified in Annex A or subclause G.11. Bitstreams shall not contain values of general_profile_idc other than those specified in Annex A or subclause G.11. Other values of general_profile_idc are reserved for future use by ITU-T | ISO/IEC.

general_profile_compatibility_flag[j] equal to 1, when general_profile_space is equal to 0, indicates that the CVS conforms to the profile indicated by general_profile_idc equal to i as specified in Annex A or subclause G.11. When general_profile_space is equal to 0, general_profile_compatibility_flag[general_profile_idc] shall be equal to 1. The value of general_profile_compatibility_flag[j] shall be equal to 0 for any value of j that is not specified as an allowed value of general_profile_idc in Annex A or subclause G.11.

A sequence of pictures picSeq is derived as follows:

– If the profile_tier_level( ) syntax structure is included in an SPS, picSeq consists of the pictures in the CVS for which the SPS is the active SPS.

– Otherwise, if the profile_tier_level( ) syntax structure is included in a VPS, but not in the vps_extension( ) syntax structure, picSeq consists of the pictures with nuh_layer_id equal to 0 in the CVS.

– Otherwise, if the profile_tier_level( ) syntax structure is associated with an OLS with alt_output_layer_flag[i] equal to 1, picSeq consists of the pictures of the output layer and its direct and indirect reference layers within the CVS.

– Otherwise, picSeq consists of the pictures of the output layers of the associated OLS within the CVS.

general_progressive_source_flag and **general_interlaced_source_flag** are interpreted as follows:

– If general_progressive_source_flag is equal to 1 and general interlaced_source_flag is equal to 0, the source scan type of the pictures in the picSeq should be interpreted as progressive only.

– Otherwise, if general_progressive_source_flag is equal to 0 and general_interlaced_source_flag is equal to 1, the source scan type of the pictures in the picSeq should be interpreted as interlaced only.

– Otherwise, if general_progressive_source_flag is equal to 0 and general_interlaced_source_flag is equal to 0, the source scan type of the pictures in the picSeq should be interpreted as unknown or unspecified.

– Otherwise, general_progressive_source_flag is equal to 1 and general_interlaced_source_flag is equal to 1, the source scan type of each picture in the picSeq is indicated at the picture level using the syntax element source_scan_type in a picture timing SEI message or the syntax element ffinfo_source_scan_type in a frame-field information SEI message.

NOTE 3 – Decoders may ignore the values of general_progressive_source_flag and general_interlaced_source_flag for purposes other than determining the value to be inferred for frame_field_info_present_flag when vui_parameters_present_flag is equal to 0, as there are no other decoding process requirements associated with the values of these flags. Moreover, the actual source scan type of the pictures is outside the scope of this Specification, and the method by which the encoder selects the values of general_progressive_source_flag and general_interlaced_source_flag is unspecified.

general_non_packed_constraint_flag equal to 1 specifies that there are no frame packing arrangement SEI messages present for the pictures of picSeq. general non_packed_constraint_flag equal to 0 indicates that there may or may not be one or more frame packing arrangement SEI messages present for the pictures of picSeq.

NOTE 4 – Decoders may ignore the value of general_non_packed_constraint_flag, as there are no decoding process requirements associated with the presence or interpretation of frame packing arrangement SEI messages.

general_frame_only_constraint_flag equal to 1 specifies that field_seq_flag in the active SPSs for the pictures of picSeq is equal to 0. general_frame_only_constraint_flag equal to 0 indicates that field_seq_flag in the active SPSs for the pictures of picSeq may or may not be equal to 0.

NOTE 5 – Decoders may ignore the value of general_frame_only_constraint_flag, as there are no decoding process requirements associated with the value of field_seq_flag.

NOTE 6 – When general_progressive_source_flag is equal to 1, general_frame_only_constraint_flag may or may not be equal to 1.

general_level_idc indicates a level to which the CVS conforms as specified in Annex A or subclause G.11. Bitstreams shall not contain values of general_level_idc other than those specified in Annex A or subclause G.11. Other values of general_level_idc are reserved for future use by ITU-T | ISO/IEC.

sub_layer_profile_present_flag[i] equal to 1, specifies that profile information is present in the profile_tier_level( ) syntax structure for the representation of the sub-layer with TemporalId equal to i. sub_layer_profile_present_flag[i] equal to 0 specifies that profile information is not present in the profile_tier_level( ) syntax structure for the representation of the sub-layer with TemporalId equal to i. When profilePresentFlag is equal to 0, sub_layer_profile_present_flag[i] shall be equal to 0.

F.7.4.5 Scaling list data semantics

The specifications in subclause 7.4.5 apply.

F.7.4.6 Supplemental enhancement information message semantics

The specifications in subclause 7.4.6 apply.

F.7.4.7 Slice segment header semantics

F.7.4.7.1 General slice segment header semantics

The specifications in subclause 7.4.7.1 apply with the following modifications and additions.

When present, the value of the slice segment header syntax elements slice_pic_parameter_set_id, pic_output_flag, no_output_of_prior_pics_flag, slice_pic_order_cnt_lsb, short_term_ref_pic_set_sps_flag, short_term_ref_pic_set_idx, num_long_term_sps, num_long_term_pics, slice_temporal_mvp_enabled_flag, discardable_flag, cross_layer_bla_flag, inter_layer_pred_enabled_flag, num_inter_layer_ref_pics_minus1, poc_reset_idc, poc_reset_period_id, full_poc_reset_flag, poc_lsb_val, and poc_msb_val shall be the same in all slice segment headers of a coded picture. When present, the value of the slice segment header syntax elements lt_idx_sps[i], poc_lsb_lt[i], used_by_curr_pic_lt_flag[i], delta_poc_msb_present_flag[i], delta_poc_msb_cycle_lt[i], and inter_layer_pred_layer_idc[i] shall be the same in all slice segment headers of a coded picture for each possible value of i.

When vps_poc_lsb_aligned_flag is equal to 1, slice_pic_order_cnt_lsb shall be the same in all slice segment headers of all coded pictures of the same access unit.

– "When nal_unit_type has a value in the range of 16 to 23, inclusive (IRAP picture), slice_type shall be equal to 2." is replaced by "When nal_unit_type has a value in the range of 16 to 23 and nuh_layer_id is equal to 0, inclusive (IRAP picture), slice_type shall be equal to 2."

discardable_flag equal to 1 specifies that the coded picture is not used as a reference picture for inter prediction and is not used as an inter-layer reference picture in the decoding process of subsequent pictures in decoding order. discardable_flag equal to 0 specifies that the coded picture may be used as a reference picture for inter prediction and may be used as an inter-layer reference picture in the decoding process of subsequent pictures in decoding order. When not present, the value of discardable_flag is inferred to be equal to 0.

When nal_unit_type is equal to TRAIL_R, TSA_R, STSA_R, RASL_R or RADL_R, the value of discardable_flag shall be equal to 0.

cross_layer_bla_flag equal to 1 affects the derivation of NoClrasOutputFlag as specified in subclause 8.1. cross_layer_bla_flag shall be equal to 0 for pictures with nal_unit_type not equal to IDR_W_RADL or IDR_N_LP or with nuh_layer_id not equal to 0.

num_long_term_sps specifies the number of entries in the long-term RPS of the current picture that are derived based on the candidate long-term reference pictures specified in the active SPS. The value of num_long_term_sps shall be in the range of 0 to num_long_term_ref_pics_sps, inclusive. When not present, the value of num_long_term_sps is inferred to be equal to 0.

num_long_term_pics specifies the number of entries in the long-term RPS of the current picture that are directly signalled in the slice header. When not present, the value of num_long_term_pics is inferred to be equal to 0.

The variable maxNumPics is derived as follows:

```
maxNumPics = MaxDpbSize - 1
for( olsIdx = 0; olsIdx < NumOutputLayerSets; olsIdx++) {
    lsIdx = OlsIdxToLsIdx[ olsIdx ]
    for( j = 0; j < NumLayersInIdList[ lsIdx ]; j++ )
        if( LayerSetLayerIdList[ lsIdx ][ j ] == nuh_layer_id ) {
            maxSL = MaxSubLayersInLayerSetMinus1[ lsIdx ]
            maxNumPics = Min( maxNumPics, max_vps_dec_pic_buffering_minus1[ olsIdx ][ j ][ maxSL ] )
        }
}
```

When nuh_layer_id is equal to 0, the sum of NumNegativePics[CurrRpsIdx], NumPositivePics[CurrRpsIdx], num_long_term_sps, and num_long_term_pics shall be less than or equal to sps_max_dec_pic_buffering_minus1[sps_max_sub_layers_minus1]. When vps_extension_flag is equal to 1, the sum of NumNegativePics[CurrRpsIdx], NumPositivePics[CurrRpsIdx], num_long_term_sps, and num_long_term_pics shall be less than or equal to maxNumPics.

slice_temporal_mvp_enabled_flag specifies whether temporal motion vector predictors can be used for inter prediction. If slice_temporal_mvp_enabled_flag is equal to 0, the syntax elements of the current picture shall be constrained such that no temporal motion vector predictor is used in decoding of the current picture. Otherwise (slice_temporal_mvp_enabled_flag is equal to 1), temporal motion vector predictors may be used in decoding of the current picture. When not present, the value of slice_temporal_mvp_enabled_flag is inferred to be equal to 0.

Let currLayerId be equal to nuh_layer_id of the current NAL unit. When NumDirectRefLayers[currLayerId] is equal to 0, slice_temporal_mvp_enabled_flag is equal to 0, and TemporalId is equal to 0, the syntax elements for all coded pictures with nuh_layer_id equal to currLayerId that follow the current picture in decoding order shall be constrained such that no temporal motion vector from any picture that precedes the current picture in decoding order is used in decoding of any coded picture with nuh_layer_id equal to currLayerId that follows the current picture in decoding order.

NOTE 7 – When NumDirectRefLayers[currLayerId] is equal to 0 and slice_temporal_mvp_enabled_flag is equal to 0 in an I slice, it has no impact on the normative decoding process of the picture but merely expresses a bitstream constraint.

NOTE 8 – When NumDirectRefLayers[currLayerId] is equal to 0 and slice_temporal_mvp_enabled_flag is equal to 0 in a slice with TemporalId equal to 0, decoders may empty "motion vector storage" for all reference pictures with nuh_layer_id equal to currLayerId in the decoded picture buffer.

inter_layer_pred_enabled_flag equal to 1 specifies that inter-layer prediction may be used in decoding of the current picture. inter_layer_pred_enabled_flag equal to 0 specifies that inter-layer prediction is not used in decoding of the current picture.

num_inter_layer_ref_pics_minus1 plus 1 specifies the number of pictures that may be used in decoding of the current picture for inter-layer prediction. The length of the num_inter_layer_ref_pics_minus1 syntax element is Ceil(Log2(NumDirectRefLayers[nuh_layer_id])) bits. The value of num_inter_layer_ref_pics_minus1 shall be in the range of 0 to NumDirectRefLayers[nuh_layer_id] − 1, inclusive.

The variables numRefLayerPics and refLayerPicIdc[j] are derived as follows:

```
for( i = 0, j = 0;  i < NumDirectRefLayers[ nuh_layer_id ]; i++ ) {
    refLayerIdx = LayerIdxInVps[ RefLayerId[ nuh_layer_id ][ i ] ]
    if( sub_layers_vps_max_minus1[ refLayerIdx ] >= TemporalId  && ( TemporalId == 0 ||
                max_tid_il_ref_pics_plus1[ refLayerIdx ][ LayerIdxInVps[ nuh_layer_id ] ] > TemporalId ) )
        refLayerPicIdc[ j++ ] = i
}

numRefLayerPics = j
```

The variable NumActiveRefLayerPics is derived as follows:

```
if( nuh_layer_id == 0 || numRefLayerPics == 0 )
    NumActiveRefLayerPics = 0
else if( all_ref_layers_active_flag )
    NumActiveRefLayerPics = numRefLayerPics
else if( !inter_layer_pred_enabled_flag )
    NumActiveRefLayerPics = 0
else if( max_one_active_ref_layer_flag || NumDirectRefLayers[ nuh_layer_id ] == 1 )
    NumActiveRefLayerPics = 1
else
    NumActiveRefLayerPics = num_inter_layer_ref_pics_minus1 + 1
```

All slices of a coded picture shall have the same value of NumActiveRefLayerPics.

inter_layer_pred_layer_idc[i] specifies the variable, RefPicLayerId[i], representing the nuh_layer_id of the i-th picture that may be used by the current picture for inter-layer prediction. The length of the syntax element inter_layer_pred_layer_idc[i] is Ceil(Log2(NumDirectRefLayers[nuh_layer_id])) bits. The value of inter_layer_pred_layer_idc[i] shall be in the range of 0 to NumDirectRefLayers[nuh_layer_id] − 1, inclusive. When not present, the value of inter_layer_pred_layer_idc[i] is inferred to be equal to refLayerPicIdc[i].

When i is greater than 0, inter_layer_pred_layer_idc[i] shall be greater than inter_layer_pred_layer_idc[i − 1].

The variables RefPicLayerId[i] for all values of i in the range of 0 to NumActiveRefLayerPics − 1, inclusive, are derived as follows:

```
for( i = 0, j = 0; i < NumActiveRefLayerPics; i++)
    RefPicLayerId[ i ] = RefLayerId[ nuh_layer_id ][ inter_layer_pred_layer_idc[ i ] ]
```

It is a requirement of bitstream conformance that for each value of i in the range of 0 to NumActiveRefLayerPics − 1, inclusive, either of the following two conditions shall be true:

– The value of max_tid_il_ref_pics_plus1[LayerIdxInVps[RefPicLayerId[i]]][LayerIdxInVps[nuh_layer_id]] is greater than TemporalId.

– The values of max_tid_il_ref_pics_plus1[LayerIdxInVps[RefPicLayerId[i]]][LayerIdxInVps[nuh_layer_id]] and TemporalId are both equal to 0 and the picture in the current access unit with nuh_layer_id equal to RefPicLayerId[i] is an IRAP picture.

poc_reset_idc equal to 0 specifies that neither the most significant bits nor the least significant bits of the picture order count value for the current picture are reset. poc_reset_idc equal to 1 specifies that only the most significant bits of the picture order count value for the current picture may be reset. poc_reset_idc equal to 2 specifies that both the most significant bits and the least significant bits of the picture order count value for the current picture may be reset. poc_reset_idc equal to 3 specifies that either only the most significant bits or both the most significant bits and the least significant bits of the picture order count value for the current picture may be reset and additional picture order count information is signalled. When not present, the value of poc_reset_idc is inferred to be equal to 0.

It is a requirement of bitstream conformance that the following constraints apply:

– The value of poc_reset_idc shall not be equal to 1 or 2 for a RASL picture, a RADL picture, a sub-layer non-reference picture, or a picture that has TemporalId greater than 0, or a picture that has discardable_flag equal to 1.

– The value of poc_reset_idc of all pictures in an access unit shall be the same.

– When the picture in an access unit with nuh_layer_id equal to 0 is an IRAP picture with a particular value of nal_unit_type and there is at least one other picture in the same access unit with a different value of nal_unit_type, the value of poc_reset_idc shall be equal to 1 or 2 for all pictures in the access unit.

– When there is at least one picture that has nuh_layer_id greater than 0 and that is an IDR picture with a particular value of nal_unit_type in an access unit and there is at least one other picture in the same access unit with a different value of nal_unit_type, the value of poc_reset_idc shall be equal to 1 or 2 for all pictures in the access unit.

– The value of poc_reset_idc of a CRA or BLA picture shall less than 3.

– When the picture with nuh_layer_id equal to 0 in an access unit is an IDR picture and there is at least one non-IDR picture in the same access unit, the value of poc_reset_idc shall be equal to 2 for all pictures in the access unit.

– When the picture with nuh_layer_id equal to 0 in an access unit is not an IDR picture, the value of poc_reset_idc shall not be equal to 2 for any picture in the access unit.

The value of poc_reset_idc of an access unit is the value of poc_reset_idc of the pictures in the access unit.

poc_reset_period_id identifies a POC resetting period. There shall be no two pictures consecutive in decoding order in the same layer that have the same value of poc_reset_period_id and poc_reset_idc equal to 1 or 2. When not present, the value of poc_reset_period_id is inferred as follows:

– If the previous picture picA that has poc_reset_period_id present in the slice segment header in present in the same layer of the bitstream as the current picture, the value of poc_reset_period_id is inferred to be equal to the value of the poc_reset_period_id of picA.

– Otherwise, the value of poc_reset_period_id is inferred to be equal to 0.

NOTE – It is not prohibited for multiple pictures in a layer to have the same value of poc_reset_period_id and to have poc_reset_idc equal to 1 or 2 unless such pictures occur in two consecutive access units in decoding order. To minimize the likelihood of such two pictures appearing in the bitstream due to picture losses, bitstream extraction, seeking, or splicing

operations, encoders should set the value of poc_reset_period_id to be a random value for each POC resetting period (subject to the constraints specified above).

It is a requirement of bitstream conformance that the following constraints apply:

– One POC resetting period shall not include more than one access unit with poc_reset_idc equal to 1 or 2.

– An access unit with poc_reset_idc equal to 1 or 2 shall be the first access unit in a POC resetting period.

– A picture that follows, in decoding order, the first POC resetting picture among all layers of a POC resetting period in decoding order shall not precede, in output order, another picture in any layer that precedes the first POC resetting picture in decoding order.

full_poc_reset_flag equal to 1 specifies that both the most significant bits and the least significant bits of the picture order count value for the current picture are reset when the previous picture in decoding order in the same layer does not belong to the same POC resetting period. full_poc_reset_flag equal to 0 specifies that only the most significant bits of the picture order count value for the current picture are reset when the previous picture in decoding order in the same layer does not belong to the same POC resetting period.

poc_lsb_val specifies a value that may be used to derive the picture order count of the current picture. The length of the poc_lsb_val syntax element is log2_max_pic_order_cnt_lsb_minus4 + 4 bits.

It is a requirement of bitstream conformance that, when poc_reset_idc is equal to 3, and the previous picture picA in decoding order that is in the same layer as the current picture, that has poc_reset_idc equal to 1 or 2, and that belongs to the same POC resetting period is present in the bitstream, picA shall be the same picture as the previous picture in decoding order that is in the same layer as the current picture, that is not a RASL picture, a RADL picture or a sub-layer non-reference picture, and that has TemporalId equal to 0 and discardable_flag equal to 0, and the value of poc_lsb_val of the current picture shall be equal to the value of slice_pic_order_cnt_lsb of picA.

The variable PocMsbValRequiredFlag is derived as follows:

```
PocMsbValRequiredFlag = CraOrBlaPicFlag  && ( !vps_poc_lsb_aligned_flag  ||                (F-27)
                        ( vps_poc_lsb_aligned_flag  &&  NumDirectRefLayers[ nuh_layer_id ]  = =  0 ) )
```

poc_msb_val_present_flag equal to 1 specifies that poc_msb_val is present. When poc_msb_val_present_flag is equal to 0, poc_msb_val is not present. When not present, the value of poc_msb_val_present_flag is inferred as follows:

– If slice_segment_header_extension_length is equal to 0, the value of poc_msb_val_present_flag is inferred to be equal to 0.

– Otherwise, if PocMsbValRequiredFlag is equal to 1, the value of poc_msb_val_present_flag is inferred to be equal to 1.

– Otherwise, the value of poc_msb_val_present_flag is inferred to be equal to 0.

poc_msb_val specifies the value of the most significant bits of the picture order count value of the current picture. The value of poc_msb_val may also be used to derive the value used to decrement the picture order count values of previously decoded pictures in the same layer as the current picture. The value of poc_msb_val shall be in the range of 0 to $2^{32 - \log2\_max\_pic\_order\_cnt\_lsb\_minus4 - 4}$, inclusive. The value of poc_msb_val shall be equal to the difference between the values of the most significant bits of the picture order counts of the current picture and the previous POC resetting picture in the same layer or the previous IDR picture in the same layer, whichever is closer, in decoding order, to the current picture. If neither picture is present, the value of poc_msb_val can be any value in the allowed range.

slice_segment_header_extension_data_bit may have any value. Decoders shall ignore the value of slice_segment_header_extension_data_bit. Its value does not affect decoder conformance to profiles specified in this version of this Specification.

F.7.4.7.2 Reference picture list modification semantics

The specifications in subclause 7.4.7.2 apply with following modifications.

– Equation 7-43 specifying the derivation of NumPicTotalCurr is replaced by:

```
NumPicTotalCurr = 0
for( i = 0; i < NumNegativePics[ CurrRpsIdx ]; i++)
  if(UsedByCurrPicS0[ CurrRpsIdx ][ i ] )
      NumPicTotalCurr++
for( i = 0; i < NumPositivePics[ CurrRpsIdx ]; i++)                                    (F-28)
  if(UsedByCurrPicS1[ CurrRpsIdx ][ i ] )
      NumPicTotalCurr++
```

```
for( i = 0; i < num_long_term_sps + num_long_term_pics; i++ )
  if( UsedByCurrPicLt[ i ] )
      NumPicTotalCurr++
NumPicTotalCurr  +=  NumActiveRefLayerPics
```

F.7.4.7.3 Weighted prediction parameters semantics

The specifications in subclause 7.4.7.3 apply.

F.7.4.8 Short-term reference picture set semantics

The specifications in subclause 7.4.8 apply, with the following modifications:

The variable maxNumPics is derived as follows:

```
maxNumPics = MaxDpbSize - 1
for( olsIdx = 0; olsIdx < NumOutputLayerSets; olsIdx++) {
      lsIdx = OlsIdxToLsIdx[ olsIdx ]
      for( j = 0; j < NumLayersInIdList[ lsIdx ]; j++ )
            if( LayerSetLayerIdList[ lsIdx ][ j ]  = =  nuh_layer_id ) {
                  maxSL = MaxSubLayersInLayerSetMinus1[ lsIdx ]
                  maxNumPics = Min( maxNumPics, max_vps_dec_pic_buffering_minus1[ olsIdx ][ j ][ maxSL ] )
            }
}
```

num_negative_pics specifies the number of entries in the stRpsIdx-th candidate short-term RPS that have picture order count values less than the picture order count value of the current picture. When nuh_layer_id is equal to 0, the value of num_negative_pics shall be in the range of 0 to sps_max_dec_pic_buffering_minus1[sps_max_sub_layers_minus1], inclusive. When vps_extension_flag is equal to 1, the value of num_negative_pics shall be in the range of 0 to maxNumPics, inclusive.

num_positive_pics specifies the number of entries in the stRpsIdx-th candidate short-term RPS that have picture order count values greater than the picture order count value of the current picture. When nuh_layer_id is equal to 0, the value of num_positive_pics shall be in the range of 0 to sps_max_dec_pic_buffering_minus1[sps_max_sub_layers_minus1] − num_negative_pics, inclusive. When vps_extension_flag is equal to 1, the value of num_positive_pics shall be in the range of 0 to maxNumPics − num_negative_pics, inclusive.

[Ed. (AR): Currently derivation of maxNumPics repeated here and in slice segment header semantics.]

F.7.4.9 Slice segment data semantics

F.7.4.9.1 General slice segment data semantics

The specifications in subclause 7.4.9.1 apply.

F.7.4.9.2 Coding tree unit semantics

The specifications in subclause 7.4.9.2 apply.

F.7.4.9.3 Sample adaptive offset semantics

The specifications in subclause 7.4.9.3 apply.

F.7.4.9.4 Coding quadtree semantics

The specifications in subclause 7.4.9.4 apply.

F.7.4.9.5 Coding unit semantics

The specifications in subclause 7.4.9.5 apply.

F.7.4.9.6 Prediction unit semantics

The specifications in subclause 7.4.9.6 apply.

F.7.4.9.7 PCM sample semantics

The specifications in subclause 7.4.9.7 apply.

F.7.4.9.8 Transform tree semantics

The specifications in subclause 7.4.9.8 apply.

F.7.4.9.9 Motion vector difference semantics

The specifications in subclause 7.4.9.9 apply.

F.7.4.9.10 Transform unit semantics

The specifications in subclause 7.4.9.10 apply.

F.7.4.9.11 Residual coding semantics

The specifications in subclause 7.4.9.11 apply.

F.8 Decoding process

F.8.1 General decoding process

The specifications in subclause 8.1 apply with following changes:

– *Replace the references to clause 7, and subclause 8.1.1 with subclauses F.7, and F.8.1.1, respectively.*

– *At the end of the subclause, add the following in this subclause:*

When the current picture has nuh_layer_id greater than 0, the decoding process for a coded picture with nuh_layer_id greater than 0 as specified in subclause F.8.1.1 is invoked.

– When vps_base_layer_internal_flag is equal to 0, the following applies: [Ed. (YK): Check other places to ensure correct handling of the base layer when this flag is equal to 0.] [Ed. (MH): It might be better to move this to subclause 8.1 to specify clearly that it applies before processing the first (internal) picture of an access unit.]

  – There is no coded picture with nuh_layer_id equal to 0 in the bitstream.

  – The size of the sub-DPB for the layer with nuh_layer_id equal to 0 is set equal to 1.

  – The values of pic_width_in_luma_samples, pic_height_in_luma_samples, chroma_format_idc, separate_colour_plane_flag, bit_depth_luma_minus8, and bit_depth_chroma_minus8 for decoded pictures with nuh_layer_id equal to 0 are set equal to the values of pic_width_vps_in_luma_samples, pic_height_vps_in_luma_samples, chroma_format_vps_idc, separate_colour_plane_vps_flag, bit_depth_vps_luma_minus8, and bit_depth_vps_chroma_minus8, respectively, of the vps_rep_format_idx[0]-th rep_format( ) syntax structure in the active VPS.

  – In addition to a list of decoded pictures, this process also outputs a flag BaseLayerOutputFlag, and, when BaseLayerOutputFlag is equal to 0 and AltOptLayerFlag[TargetOptLayerSetIdx] is equal to 1, a flag BaseLayerPicOutputFlag for each access unit.

    NOTE – The BaseLayerOutputFlag and, when present, BaseLayerPicOutputFlag for each access unit, are to be sent by an external means to the base layer decoder for controlling the output of base layer decoded pictures.

    The variables BaseLayerOutputFlag and BaseLayerPicOutputFlag are derived as specified in the following :

    – The variable BaseLayerOutputFlag is set equal to (TargetOptLayerIdList[0] = = 0).

      BaseLayerOutputFlag equal to 1 specifies that the base layer is an output layer. BaseLayerOutputFlag equal to 0 specifies that the base layer is not an output layer.

    – When BaseLayerOutputFlag is equal to 0 and AltOptLayerFlag[TargetOptLayerSetIdx] is equal to 1, for each access unit, BaseLayerPicOutputFlag is derived as follows:

      – If the base layer is a direct or indirect reference layer of the output layer, the access unit does not contain a picture at the output layer or contains a picture at the output layer that has PicOutputFlag equal to 0, and does not contain a picture at any other direct or indirect reference layer of the output layer, BaseLayerPicOutputFlag is set equal to 1.

      – Otherwise, BaseLayerPicOutputFlag is set equal to 0.

      BaseLayerPicOutputFlag equal to 1 for an access unit specifies that the base layer picture of the access unit is output. BaseLayerPicOutputFlag equal to 0 for an access unit specifies that the base layer picture of the access unit is not output.

- The variable LayerInitializedFlag[0] is set equal to 1 and the variable FirstPicInLayerDecodedFlag[0] is set equal to 1.
- For each access unit with TemporalId less than or equal to sub_layers_vps_max_minus1[0], a decoded picture with nuh_layer_id equal to 0 may be provided by external means. When not provided, no picture with nuh_layer_id equal to 0 is used for inter-layer prediction for the current access unit. When provided, the following applies:
  - The following information of the picture with nuh_layer_id equal to 0 for the access unit is provided by external means:
    - The decoded sample values (1 sample array S_L if chroma_format_idc is equal to 0 or 3 sample arrays S_L, S_{Cb}, and S_{Cr} otherwise)
    - The value of the variable BlIrapPicFlag, and when BlIrapPicFlag is equal to 1, the value of nal_unit_type of the decoded picture
      - BlIrapPicFlag equal to 1 specifies that the decoded picture is an IRAP picture. BlIrapPicFlag equal to 0 specifies that the decoded picture is a non-IRAP picture.
      - The provided value of nal_unit_type of the decoded picture shall be equal to IDR_W_RADL, CRA_NUT, or BLA_W_LP.
        - nal_unit_type equal to IDR_W_RADL specifies that the decoded picture is an IDR picture.
        - nal_unit_type equal to CRA_NUT specifies that the decoded picture is a CRA picture.
        - nal_unit_type equal to BLA_W_LP specifies that the decoded picture is a BLA picture.
  - When BlIrapPicFlag of the picture with nuh_layer_id equal to 0 is equal to 1, the following applies for the decoded picture with nuh_layer_id equal to 0 for the access unit:
    - The variable NoRaslOutputFlag is specified as follows:
      - If nal_unit_type is IDR_W_RADL or BLA_W_LP, the variable NoRaslOutputFlag is set equal to 1.
      - Otherwise, if the current access unit is the first access unit in the bitstream in decoding order, the variable NoRaslOutputFlag is set equal to 1.
      - Otherwise, the variable NoRaslOutputFlag is set equal to 0.
    - The variable NoClrasOutputFlag is specified as follows:
      - If the current access unit is the first access unit in the bitstream, NoClrasOutputFlag is set equal to 1.
      - Otherwise, if nal_unit_type is equal to CRA_NUT and NoRaslOutputFlag is equal to 1, NoClrasOutputFlag is set equal to 1.
      - Otherwise, if nal_unit_type is equal to BLA_W_LP, NoClrasOutputFlag is set equal to1.
      - Otherwise, if some external means, not specified in this Specification, is available to set NoClrasOutputFlag, NoClrasOutputFlag is set by the external means.
      - Otherwise, NoClrasOutputFlag is set equal to 0.
    - When NoClrasOutputFlag is equal to 1, the variable LayerInitializedFlag[i] is set equal to 0 for all values of i from 1 to vps_max_layer_id, inclusive, and the variable FirstPicInLayerDecodedFlag[i] is set equal to 0 for all values of i from 1 to vps_max_layer_id, inclusive.
  - The following applies for the decoded picture with nuh_layer_id equal to 0 for the access unit:
    - If the access unit has at least one picture with nuh_layer_id greater than 0, the TemporalId and PicOrderCntVal of the decoded picture with nuh_layer_id equal to 0 are set equal to the TemporalId and PicOrderCntVal, respectively, of any picture with nuh_layer_id greater than 0 in the access unit.
    - Otherwise, the decoded picture with nuh_layer_id equal to 0 is discarded and the sub-DPB for the layer with nuh_layer_id equal to 0 is set to be empty. [Ed. (YK): Make sure that there is a restriction, indirect or direct, that requires the TemporalId to be equal to 0 when BlIrapPicFlag is equal to 1.]
    - The decoded picture with nuh_layer_id equal to 0 is stored in the sub-DPB for the layer with nuh_layer_id equal to 0 and is marked as "used for long-term reference".

– When the access unit has at least one picture with nuh_layer_id greater than 0, after all pictures in the access unit are decoded, the sub-DPB for the layer with nuh_layer_id equal to 0 is set to be empty.

F.8.1.1 Decoding process for a coded picture with nuh_layer_id equal to 0

The specifications in subclause 8.1.1 apply with the following changes:

– Replace the references to subclauses 8.2, 8.3, 8.3.1, 8.3.2, 8.3.3, 8.3.4, 8.4, 8.5, 8.6, and 8.7 with subclauses F.8.2, F.8.3, F.8.3.1, F.8.3.2, F.8.3.3, F.8.3.4, F.8.4, F.8.5, F.8.6, and F.8.7, respectively.

– At the end of the subclause, add item 5 as follows:

5. When FirstPicInLayerDecodedFlag[0] is equal to 0, FirstPicInLayerDecodedFlag[0] is set equal to 1.

F.8.1.2 Decoding process for a coded picture with nuh_layer_id greater than 0

The decoding process operates as follows for the current picture CurrPic.

– For the decoding of the slice segment header of the first slice, in decoding order, of the current picture, the decoding process for starting the decoding of a coded picture with nuh_layer_id greater than 0 specified in subclause F.8.1.3 is invoked.

– When ViewScalExtLayerFlag[nuh_layer_id] is equal to 1, the decoding process for a coded picture with nuh_layer_id greater than 0 specified in subclause G.8.1.1 is invoked. [Ed. (YK): It looks a bit odd to refer to Annex G here. Is this avoidable?] [Ed. (MH): The condition on ViewScalExtLayerFlag[nuh_layer_id] being equal to 1 has the consequence that no decoding process is invoked for an auxiliary picture layer with ViewOrderIdx equal to 0. In general, it should be clarified which decoding process is invoked for coded pictures of any layers, including coded pictures that have nuh_layer_id greater than 0 but ViewScalExtLayerFlag[nuh_layer_id] equal to 0.]

– After all slices of the current picture have been decoded, the decoding process for ending the decoding of a coded picture with nuh_layer_id greater than 0 specified in subclause F.8.1.4 is invoked.

F.8.1.3 Decoding process for starting the decoding of a coded picture with nuh_layer_id greater than 0

Each picture referred to in this subclause is a complete coded picture.

The decoding process operates as follows for the current picture CurrPic:

1. The decoding of NAL units is specified in subclause F.8.2.
2. The processes in subclause F.8.3 specify the following decoding processes using syntax elements in the slice segment layer and above:
   – Variables and functions relating to picture order count are derived in subclause F.8.3.1. This needs to be invoked only for the first slice segment of a picture. It is a requirement of bitstream conformance that PicOrderCntVal shall remain unchanged within an access unit.
   – The decoding process for RPS in subclause F.8.3.2 is invoked, wherein only reference pictures with nuh_layer_id equal to that of CurrPic may be marked as "unused for reference" or "used for long-term reference" and any picture with a different value of nuh_layer_id is not marked. This needs to be invoked only for the first slice segment of a picture.
   – When FirstPicInLayerDecodedFlag[nuh_layer_id] is equal to 0, the decoding process for generating unavailable reference pictures specified in subclause F.8.1.5 is invoked, which needs to be invoked only for the first slice segment of a picture.
   – When FirstPicInLayerDecodedFlag[nuh_layer_id] is not equal to 0 and the current picture is an IRAP picture with NoRaslOutputFlag equal to 1, the decoding process for generating unavailable reference pictures specified in subclause F.8.3.3 is invoked, which needs to be invoked only for the first slice segment of a picture.

F.8.1.4 Decoding process for ending the decoding of a coded picture with nuh_layer_id greater than 0

PicOutputFlag is set as follows:

– If LayerInitializedFlag[nuh_layer_id] is equal to 0, PicOutputFlag is set equal to 0.

– Otherwise, if the current picture is a RASL picture and NoRaslOutputFlag of the associated IRAP picture is equal to 1, PicOutputFlag is set equal to 0.

– Otherwise, PicOutputFlag is set equal to pic_output_flag.

The decoded picture is marked as "used for short-term reference".

When FirstPicInLayerDecodedFlag[nuh_layer_id] is equal to 0, FirstPicInLayerDecodedFlag[nuh_layer_id] is set equal to 1.

F.8.1.5 Generation of unavailable reference pictures for pictures first in decoding order within a layer

This process is invoked for a picture with nuh_layer_id equal to layerId, when FirstPicInLayerDecodedFlag[layerId] is equal to 0.

NOTE – A cross-layer random access skipped (CL-RAS) picture is a picture with nuh_layer_id equal to layerId such that LayerInitializedFlag[layerId] is equal to 0 when the decoding process for starting the decoding of a coded picture with nuh_layer_id greater than 0 is invoked. The entire specification of the decoding process for CL-RAS pictures is included only for purposes of specifying constraints on the allowed syntax content of such CL-RAS pictures. During the decoding process, any CL-RAS pictures may be ignored, as these pictures are not specified for output and have no effect on the decoding process of any other pictures that are specified for output. However, in HRD operations as specified in Annex C, CL-RAS pictures may need to be taken into consideration in derivation of CPB arrival and removal times.

When this process is invoked, the following applies:

– For each RefPicSetStCurrBefore[i], with i in the range of 0 to NumPocStCurrBefore − 1, inclusive, that is equal to "no reference picture", a picture is generated as specified in subclause 8.3.3.2, and the following applies:
  – The value of PicOrderCntVal for the generated picture is set equal to PocStCurrBefore[i].
  – The value of PicOutputFlag for the generated picture is set equal to 0.
  – The generated picture is marked as "used for short-term reference".
  – RefPicSetStCurrBefore[i] is set to be the generated reference picture.
  – The value of nuh_layer_id for the generated picture is set equal to nuh_layer_id.
– For each RefPicSetStCurrAfter[i], with i in the range of 0 to NumPocStCurrAfter − 1, inclusive, that is equal to "no reference picture", a picture is generated as specified in subclause 8.3.3.2, and the following applies:
  – The value of PicOrderCntVal for the generated picture is set equal to PocStCurrAfter[i].
  – The value of PicOutputFlag for the generated picture is set equal to 0.
  – The generated picture is marked as "used for short-term reference".
  – RefPicSetStCurrAfter[i] is set to be the generated reference picture.
  – The value of nuh_layer_id for the generated picture is set equal to nuh_layer_id.
– For each RefPicSetStFoll[i], with i in the range of 0 to NumPocStFoll − 1, inclusive, that is equal to "no reference picture", a picture is generated as specified in subclause 8.3.3.2, and the following applies:
  – The value of PicOrderCntVal for the generated picture is set equal to PocStFoll[i].
  – The value of PicOutputFlag for the generated picture is set equal to 0.
  – The generated picture is marked as "used for short-term reference".
  – RefPicSetStFoll[i] is set to be the generated reference picture.
  – The value of nuh_layer_id for the generated picture is set equal to nuh_layer_id.
– For each RefPicSetLtCurr[i], with i in the range of 0 to NumPocLtCurr − 1, inclusive, that is equal to "no reference picture", a picture is generated as specified in subclause 8.3.3.2, and the following applies:
  – The value of PicOrderCntVal for the generated picture is set equal to PocLtCurr[i].
  – The value of slice_pic_order_cnt_lsb for the generated picture is inferred to be equal to (PocLtCurr[i] & (MaxPicOrderCntLsb − 1)).
  – The value of PicOutputFlag for the generated picture is set equal to 0.
  – The generated picture is marked as "used for long-term reference".
  – RefPicSetLtCurr[i] is set to be the generated reference picture.
  – The value of nuh_layer_id for the generated picture is set equal to nuh_layer_id.
– For each RefPicSetLtFoll[i], with i in the range of 0 to NumPocLtFoll − 1, inclusive, that is equal to "no reference picture", a picture is generated as specified in subclause 8.3.3.2, and the following applies:
  – The value of PicOrderCntVal for the generated picture is set equal to PocLtFoll[i].

- The value of slice_pic_order_cnt_lsb for the generated picture is inferred to be equal to (PocLtFoll[i] & (MaxPicOrderCntLsb − 1)).
- The value of PicOutputFlag for the generated picture is set equal to 0.
- The generated picture is marked as "used for long-term reference".
- RefPicSetLtFoll[i] is set to be the generated reference picture.
- The value of nuh_layer_id for the generated picture is set equal to nuh_layer_id.

F.8.2 NAL unit decoding process

The specifications in subclause 8.2 apply.

F.8.3 Slice decoding processes

F.8.3.1 Decoding process for picture order count

Output of this process is PicOrderCntVal, the picture order count of the current picture.

Picture order counts are used to identify pictures, for deriving motion parameters in merge mode and motion vector prediction, and for decoder conformance checking (see subclause C.5).

Each coded picture is associated with a picture order count variable, denoted as PicOrderCntVal.

When the current picture is the first picture among all layers of a POC resetting period, the variable PocDecrementedInDPBFlag[i] is set equal to 0 for each value of i in the range of 0 to 62, inclusive.

The variable pocResettingFlag is derived as follows:

- If the current picture is a POC resetting picture, the following applies:
  - If vps_poc_lsb_aligned_flag is equal to 0, pocResettingFlag is set equal to 1.
  - Otherwise, if PocDecrementedInDPBFlag[nuh_layer_id] is equal to 1, pocResettingFlag is set equal to 0.
  - Otherwise, pocResettingFlag is set equal to 1.
- Otherwise, pocResettingFlag is set equal to 0.

The list affectedLayerList is derived as follows:

- If vps_poc_lsb_aligned_flag is equal to 0, affectedLayerList consists of the nuh_layer_id of the current picture.
- Otherwise, affectedLayerList consists of the nuh_layer_id of the current picture and the nuh_layer_id values equal to PredictedLayerId[currNuhLayerId][j] for all values of j in the range of 0 to NumPredictedLayers[currNuhLayerId] − 1, inclusive, where currNuhLayerId is the nuh_layer_id value of the current picture.

If pocResettingFlag is equal to 1, the following applies:

- When FirstPicInLayerDecodedFlag[nuh_layer_id] is equal to 1, the following applies:
  - The variables pocMsbDelta, pocLsbDelta and DeltaPocVal are derived as follows:

```
if( poc_reset_idc  = =  3 )
    pocLsbVal = poc_lsb_val
else
    pocLsbVal = slice_pic_order_cnt_lsb
if(  poc_msb_val_present_flag  )
    pocMsbDelta = poc_msb_val * MaxPicOrderCntLsb
else {
    prevPicOrderCntLsb = PrevPicOrderCnt[ nuh_layer_id ] & ( MaxPicOrderCntLsb − 1 )
    prevPicOrderCntMsb = PrevPicOrderCnt[ nuh_layer_id ] − prevPicOrderCntLsb
    pocMsbDelta = getCurrMsb( pocLsbVal, prevPicOrderCntLsb, prevPicOrderCntMsb,
                                        MaxPicOrderCntLsb )
}
if( poc_reset_idc  = =  2  | |  ( poc_reset_idc  = =  3  &&  full_poc_reset_flag ) )
    pocLsbDelta = pocLsbVal
else
```

```
        pocLsbDelta = 0
    DeltaPocVal  =  pocMsbDelta + pocLsbDelta
```

- The PicOrderCntVal of each picture that is in the DPB and has nuh_layer_id value nuhLayerId for which PocDecrementedInDPBFlag[nuhLayerId] is equal to 0 and that is equal to any value in affectedLayerList is decremented by DeltaPocVal.
- PocDecrementedInDPBFlag[nuhLayerId] is set equal to 1 for each value of nuhLayerId included in affectedLayerList.

– The PicOrderCntVal of the current picture is derived as follows:

```
if( poc_reset_idc  = =  1 )
    PicOrderCntVal = slice_pic_order_cnt_lsb
else if( poc_reset_idc  = =  2 )
    PicOrderCntVal = 0
else { // poc_reset_idc  = =  3
    PicOrderCntMsb = getCurrMsb( slice_pic_order_cnt_lsb, full_poc_reset_flag ? 0 : poc_lsb_val,
                                                    0, MaxPicOrderCntLsb )
    PicOrderCntVal = PicOrderCntMsb + slice_pic_order_cnt_lsb
}
```

Otherwise, the following applies:

– The PicOrderCntVal of the current picture is derived as follows:

```
if( poc_msb_val_present_flag )
    PicOrderCntMsb = poc_msb_val * MaxPicOrderCntLsb
else if(!FirstPicInLayerDecodedFlag[ nuh_layer_id ] ||
            nal_unit_type  = =  IDR_N_LP  ||  nal_unit_type  = =  IDR_W_RADL )
    PicOrderCntMsb = 0
else {
    prevPicOrderCntLsb = PrevPicOrderCnt[ nuh_layer_id ] & ( MaxPicOrderCntLsb − 1 ).
    prevPicOrderCntMsb = PrevPicOrderCnt[ nuh_layer_id ] − prevPicOrderCntLsb
    PicOrderCntMsb =  getCurrMsb( slice_pic_order_cnt_lsb, prevPicOrderCntLsb, prevPicOrderCntMsb,
                                            MaxPicOrderCntLsb )
}
PicOrderCntVal = PicOrderCntMsb + slice_pic_order_cnt_lsb
```

The value of PrevPicOrderCnt[lId] for each of the lId values included in affectedLayerList is derived as follows:

– If the current picture is not a RASL picture, a RADL picture or a sub-layer non-reference picture, and the current picture has TemporalId equal to 0 and discardable_flag equal to 0, PrevPicOrderCnt[lId] is set equal to PicOrderCntVal.

– Otherwise, when poc_reset_idc is equal to 3 and one of the following conditions is true, PrevPicOrderCnt[lId] is set equal to (full_poc_reset_flag ? 0 : poc_lsb_val):

- FirstPicInLayerDecodedFlag[nuh_layer_id] is equal to 0.
- FirstPicInLayerDecodedFlag[nuh_layer_id] is equal to 1 and the current picture is a POC resetting picture.

The value of PicOrderCntVal shall be in the range of -2^{31} to $2^{31} - 1$, inclusive. In one CVS, the PicOrderCntVal values for any two coded pictures in the same layer shall not be the same.

The function PicOrderCnt(picX) is specified as follows:

PicOrderCnt(picX) = PicOrderCntVal of the picture picX (F-29)

The function DiffPicOrderCnt(picA, picB) is specified as follows:

DiffPicOrderCnt(picA, picB) = PicOrderCnt(picA) − PicOrderCnt(picB) (F-30)

The bitstream shall not contain data that result in values of DiffPicOrderCnt(picA, picB) used in the decoding process that are not in the range of -2^{15} to $2^{15} - 1$, inclusive.

NOTE – Let X be the current picture and Y and Z be two other pictures in the same sequence, Y and Z are considered to be in the same output order direction from X when both DiffPicOrderCnt(X, Y) and DiffPicOrderCnt(X, Z) are positive or both are negative.

F.8.3.2 Decoding process for reference picture set

The specifications in subclause 8.3.2 apply with the following changes:

– Replace the references to subclauses 7.4.7.2, 8.3.1, 8.3.3, and 8.3.4 to subclauses F.7.4.7.2, F.8.3.1, F.8.3.3, and F.8.3.4, respectively.

F.8.3.3 Decoding process for generating unavailable reference pictures

The specifications in subclause 8.3.3 apply.

F.8.3.4 Decoding process for reference picture lists construction

This process is invoked at the beginning of the decoding process for each P or B slice.

Reference pictures are addressed through reference indices as specified in subclause 8.5.3.3.2. A reference index is an index into a reference picture list. When decoding a P slice, there is a single reference picture list RefPicList0. When decoding a B slice, there is a second independent reference picture list RefPicList1 in addition to RefPicList0.

At the beginning of the decoding process for each slice, the reference picture lists RefPicList0 and, for B slices, RefPicList1 are derived as follows:

The variable NumRpsCurrTempList0 is set equal to Max(num_ref_idx_l0_active_minus1 + 1, NumPicTotalCurr) and the list RefPicListTemp0 is constructed as follows:

```
rIdx = 0
while( rIdx < NumRpsCurrTempList0 ) {
    for( i = 0; i < NumPocStCurrBefore  &&  rIdx < NumRpsCurrTempList0; rIdx++, i++ )
        RefPicListTemp0[ rIdx ] = RefPicSetStCurrBefore[ i ]
    for( i = 0; i < NumActiveRefLayerPics0; rIdx++, i++ )
        RefPicListTemp0[ rIdx ] = RefPicSetInterLayer0[ i ]
    for( i = 0;  i < NumPocStCurrAfter  &&  rIdx < NumRpsCurrTempList0; rIdx++, i++ )          (F-1)
        RefPicListTemp0[ rIdx ] = RefPicSetStCurrAfter[ i ]
    for( i = 0; i < NumPocLtCurr  &&  rIdx < NumRpsCurrTempList0; rIdx++, i++ )
        RefPicListTemp0[ rIdx ] = RefPicSetLtCurr[ i ]
    for( i = 0; i < NumActiveRefLayerPics1; rIdx++, i++ )
        RefPicListTemp0[ rIdx ] = RefPicSetInterLayer1[ i ]
}
```

The list RefPicList0 is constructed as follows:

```
for( rIdx = 0; rIdx  <=  num_ref_idx_l0_active_minus1; rIdx++)                              (F-2)
    RefPicList0[ rIdx ] = ref_pic_list_modification_flag_l0 ? RefPicListTemp0[ list_entry_l0[ rIdx ] ] :
                                                              RefPicListTemp0[ rIdx ]
```

When the slice is a B slice, the variable NumRpsCurrTempList1 is set equal to Max(num_ref_idx_l1_active_minus1 + 1, NumPicTotalCurr) and the list RefPicListTemp1 is constructed as follows:

```
rIdx = 0
while( rIdx < NumRpsCurrTempList1 ) {
    for( i = 0; i < NumPocStCurrAfter  &&  rIdx < NumRpsCurrTempList1; rIdx++, i++ )
        RefPicListTemp1[ rIdx ] = RefPicSetStCurrAfter[ i ]
    for( i = 0; i< NumActiveRefLayerPics1; rIdx++, i++ )
        RefPicListTemp1[ rIdx ] = RefPicSetInterLayer1[ i ]
    for( i = 0;  i < NumPocStCurrBefore  &&  rIdx < NumRpsCurrTempList1; rIdx++, i++ )          (F-3)
        RefPicListTemp1[ rIdx ] = RefPicSetStCurrBefore[ i ]
    for( i = 0; i < NumPocLtCurr  &&  rIdx < NumRpsCurrTempList1; rIdx++, i++ )
        RefPicListTemp1[ rIdx ] = RefPicSetLtCurr[ i ]
    for( i = 0; i< NumActiveRefLayerPics0; rIdx++, i++ )
        RefPicListTemp1[ rIdx ] = RefPicSetInterLayer0[ i ]
}
```

When the slice is a B slice, the list RefPicList1 is constructed as follows:

```
for( rIdx = 0; rIdx <= num_ref_idx_l1_active_minus1; rIdx++)                                (F-4)
    RefPicList1[ rIdx ] = ref_pic_list_modification_flag_l1 ? RefPicListTemp1[ list_entry_l1[ rIdx ] ] :
                                                              RefPicListTemp1[ rIdx ]
```

F.8.4 Decoding process for coding units coded in intra prediction mode

The specifications in subclause 8.4 apply.

F.8.5 Decoding process for coding units coded in inter prediction mode

The specifications in subclause 8.5 apply.

F.8.6 Scaling, transformation and array construction process prior to deblocking filter process

The specifications in subclause 8.6 apply.

F.8.7 In-loop filter process

The specifications in subclause 8.7 apply.

F.9 Parsing process

The specifications in clause 9 apply.

F.10 Specification of bitstream subsets

F.10.1 Sub-bitstream extraction process

Inputs to this process are a bitstream, a target highest TemporalId value tIdTarget, and a target layer identifier list layerIdListTarget.

Output of this process is a sub-bitstream.

If vps_base_layer_internal_flag is equal to 1, it is a requirement of bitstream conformance for the input bitstream that any output sub-bitstream of the process specified in this clause with tIdTarget equal to any value in the range of 0 to 6, inclusive, and layerIdListTarget equal to the layer identifier list associated with a layer set specified in the active VPS shall be a conforming bitstream.

NOTE 1 – When vps_base_layer_internal_flag is equal to 1, a conforming bitstream contains one or more coded slice segment NAL units with nuh_layer_id equal to 0 and TemporalId equal to 0.

Otherwise (vps_base_layer_internal_flag is equal to 0), it is a requirement of bitstream conformance for the input bitstream that any output sub-bitstream of the process specified in this clause with tIdTarget equal to any value in the range of 0 to 6, inclusive, and layerIdListTarget equal to the layer identifier list associated with a layer set specified in the active VPS shall be a conforming bitstream according to at least one profile in which vps_base_layer_internal_flag may be equal to 0.

The output sub-bitstream is derived as follows:

– When one or more of the following two conditions are true, remove all SEI NAL units that have nuh_layer_id equal to 0 and that contain a non-nested buffering period SEI message, a non-nested picture timing SEI message, or a non-nested decoding unit information SEI message:

  – layerIdListTarget does not include all the values of nuh_layer_id in all NAL units in the bitstream.

  – tIdTarget is less than the greatest TemporalId in all NAL units in the bitstream.

    NOTE 2 – A "smart" bitstream extractor may include appropriate non-nested buffering picture SEI messages, non-nested picture timing SEI messages, and non-nested decoding unit information SEI messages in the extracted sub-bitstream, provided that the SEI messages applicable to the sub-bitstream were present as nested SEI messages in the original bitstream.

– Remove all NAL units with TemporalId greater than tIdTarget or nuh_layer_id not among the values included in layerIdListTarget.

F.10.2 Non-base layer subtree extraction process

This process may be applied when num_add_layer_sets is greater than 0 in the active VPSs of the input bitstream.

Inputs to this process are a bitstream inBitstream and for each CVS of the input bitstream a layer set index lsIdx in the range of FirstAddLayerSetIdx to LastAddLayerSetIdx, inclusive.

Output of this process is a bitstream outBitstream.

It is a requirement of bitstream conformance for the input bitstream that any output bitstream of the process specified in this clause with lsIdx in the range of FirstAddLayerSetIdx to LastAddLayerSetIdx, inclusive, shall otherwise be a

conforming bitstream except that the output bitstream is not required to contain any VPS NAL units, when all the VCL NAL units of the output bitstream have nuh_layer_id equal to 0.

NOTE 1 – When an additional layer set contains only one layer, a VPS rewriting SEI message for that additional layer set is not required to be present.

The bitstream outBitstream is derived from the bitstream inBitstream by applying the following ordered steps:

- The bitstream outBitstream is set to be identical to the bitstream inBitstream.
- NAL units with nal_unit_type not equal to SPS_NUT, PPS_NUT, EOS_NUT, and EOB_NUT and with nuh_layer_id not among the nuh_layer_id values of the layer set with index lsIdx are removed from outBitstream.
- NAL units with nal_unit_type equal to SPS_NUT, PPS_NUT, EOS_NUT, or EOB_NUT and with nuh_layer_id not equal to 0 and not among the nuh_layer_id values of the layer set with index lsIdx are removed from outBitstream.
- SEI NAL units including a scalable nesting SEI message for which at least one of the following conditions is true are removed from outBitstream:
  - bitstream_subset_flag is equal to 1.
  - nesting_op_flag is equal to 1.
  - nesting_op_flag is equal to 0 and all_layers_flag is equal to 1.
  - nesting_op_flag is equal to 0, all_layers_flag is equal to 0, and nesting_layer_id[i] for any value of i in the range of 0 to nesting_num_layers_minus1, inclusive, is not among the layer set with index lsIdx.
- For each NAL unit, the following applies:
  - When nuh_layer_id is equal to AssignedBaseLayerId[lsIdx], nuh_layer_id is set equal to 0.
- For each SEI NAL unit containing an OLS nesting SEI message for which all the following conditions are true:
  - The OLS nesting SEI message contains a VPS rewriting SEI message.
  - ols_idx[i] is equal to lsIdx for a value of i in the range of 0 to num_ols_indices_minus1, inclusive.

  the following applies:
  - If an access unit delimiter NAL unit is present in the same access unit that contains the SEI NAL unit, the nal_unit( ) in the payload of the VPS rewriting SEI message is inserted into outBitstream as the first NAL unit following the access unit delimiter NAL unit in decoding order.
  - Otherwise, the nal_unit( ) in the payload of the VPS rewriting SEI message is inserted into outBitstream as the first NAL unit, in decoding order, of the access unit.
  - The SEI NAL unit is removed.
- For each SEI NAL unit oldSeiNalUnit containing an OLS nesting SEI message for which all the following conditions are true:
  - The OLS nesting SEI message contains a scalable nesting SEI message that contains one or more of the following: buffering period SEI message, picture timing SEI message, decoding unit information SEI message.
  - ols_idx[i] is equal to lsIdx for a value of i in the range of 0 to num_ols_indices_minus1, inclusive.

  the following applies:
  - A new prefix SEI NAL unit is added in the same access unit that contains the SEI NAL unit oldSeiNalUnit before the first VCL NAL unit of the access unit, where the NAL unit payload of the new prefix SEI NAL unit consists of the scalable nesting SEI message. nuh_layer_id of the new prefix SEI NAL unit is equal to 0 and nuh_temporal_id_plus1 of the new prefix SEI NAL unit is equal to 1.
  - The SEI NAL unit oldSeiNalUnit is removed.
- All SEI NAL units containing an OLS nesting SEI message or a bitstream partition nesting SEI message are removed.
- For each SEI NAL unit containing a scalable nesting SEI message, the following applies:
  - For each value of i in the range of 0 to nesting_num_layers_minus1, inclusive, the following applies:
    - When nesting_layer_id[i] in a scalable nesting SEI message is equal to AssignedBaseLayerId[lsIdx], nesting_layer_id[i] is set equal to 0.

F.11 (Void)

F.12 Byte stream format

The specifications in Annex B apply.

F.13 Hypothetical reference decoder

The specifications in Annex C and its subclauses apply.

F.14 SEI messages

The specifications in Annex D together with the extensions and modifications specified in this subclause apply.

[Ed. (JO): Could be better to put all about the SEI messages directly to annex D, and VUI related stuff directly to annex E. This can however still be done when the new edition is produced.]

The semantics of the structure of pictures information SEI message specified in subclause D.3.18 are replaced with the following (changed parts are highlighted in turquois):

The structure of pictures information SEI message provides information for a list of entries, some of which correspond to the target picture set consists of a series of pictures starting from the current picture until the last picture in decoding order in the CVS or the last picture in decoding order in the current POC resetting period, whichever is earlier.

The first entry in the structure of pictures information SEI message corresponds to the current picture. When there is a picture in the target picture set that has PicOrderCntVal equal to the variable entryPicOrderCnt[i] as specified below, the entry i corresponds to a picture in the target picture set. The decoding order of the pictures in the target picture set that correspond to entries in the structure of pictures information SEI message corresponds to increasing values of i in the list of entries.

Any picture picB in the target picture set that has PicOrderCntVal equal to entryPicOrderCnt[i] for any i in the range of 0 to num_entries_in_sop_minus1, inclusive, where PicOrderCntVal is the value of PicOrderCntVal of picB immediately after the invocation of the decoding process for picture order count for picB, shall correspond to an entry in the list of entries.

The structure of pictures information SEI message shall not be present in a CVS for which the active SPS has long_term_ref_pics_present_flag equal to 1 or num_short_term_ref_pic_sets equal to 0.

The structure of pictures information SEI message shall not be present in any access unit that has TemporalId greater than 0 or contains a RASL, RADL or sub-layer non-reference picture. Any picture in the target picture set that corresponds to an entry other than the first entry described in the structure of pictures information SEI message shall not be an IRAP picture.

sop_seq_parameter_set_id indicates and shall be equal to the sps_seq_parameter_set_id value of the active SPS. The value of sop_seq_parameter_set_id shall be in the range of 0 to 15, inclusive.

num_entries_in_sop_minus1 plus 1 specifies the number of entries in the structure of pictures information SEI message. num_entries_in_sop_minus1 shall be in the range of 0 to 1023, inclusive.

sop_vcl_nut[i], when the i-th entry corresponds to a picture in the target picture set, indicates and shall be equal to the nal_unit_type value of the picture corresponding to the i-th entry.

sop_temporal_id[i], when the i-th entry corresponds to a picture in the target picture set, indicates and shall be equal to the TemporalId value of the picture corresponding to the i-th entry. The value of 7 for sop_temporal_id[i] is reserved for future use by ITU-T | ISO/IEC and shall not be present in bitstreams conforming to this version of this Specification. Decoders shall ignore structure of pictures information SEI messages that contain the value 7 for sop_temporal_id[i].

sop_short_term_rps_idx[i], when the i-th entry corresponds to a picture in the target picture set, indicates and shall be equal to the index, into the list of candidate short-term RPSs included in the active SPS, of the candidate short-term RPS used by the picture corresponding to the i-th entry for derivation of the short-term reference picture set. sop_short_term_rps_idx[i] shall be in the range of 0 to num_short_term_ref_pic_sets − 1, inclusive.

sop_poc_delta[i] is used to specify the value of the variable entryPicOrderCnt[i] for the i-th entry described in the structure of pictures information SEI message. sop_poc_delta[i] shall be in the range of (−MaxPicOrderCntLsb) / 2 + 1 to MaxPicOrderCntLsb / 2 − 1, inclusive.

The variable entryPicOrderCnt[i] is derived as follows:

```
entryPicOrderCnt[ 0 ] = PicOrderCnt( currPic )
for( i = 1; i  <=  num_entries_in_sop_minus1; i++ )
    entryPicOrderCnt[ i ] = entryPicOrderCnt[ i − 1 ] + sop_poc_delta[ i ]          (F-31)
```

where currPic is the current picture.

[Ed. (CY): to check the semantics in D.3 and that in F.14.2 to make them align with the AU definition.]

F.14.1 SEI message syntax

F.14.1.1 Layers not present SEI message syntax

layers_not_present(payloadSize) {	**Descriptor**
lnp_sei_active_vps_id	u(4)
for(i = 0; i <= MaxLayersMinus1; i++)	
layer_not_present_flag[i]	u(1)
}	

F.14.1.2 Inter-layer constrained tile sets SEI message syntax

inter_layer_constrained_tile_sets(payloadSize) {	**Descriptor**
il_all_tiles_exact_sample_value_match_flag	u(1)
il_one_tile_per_tile_set_flag	u(1)
if(!il_one_tile_per_tile_set_flag) {	
il_num_sets_in_message_minus1	ue(v)
if(il_num_sets_in_message_minus1)	
skipped_tile_set_present_flag	u(1)
numSignificantSets = il_num_sets_in_message_minus1 − skipped_tile_set_present_flag + 1	
for(i = 0; i < numSignificantSets; i++) {	
ilcts_id[i]	ue(v)
il_num_tile_rects_in_set_minus1[i]	ue(v)
for(j = 0; j <= il_num_tile_rects_in_set_minus1[i]; j++) {	
il_top_left_tile_index[i **][** j **]**	ue(v)
il_bottom_right_tile_index[i]**[** j **]**	ue(v)
}	
ilc_idc[i]	u(2)
if (!il_all_tiles_exact_sample_value_match_flag)	
il_exact_sample_value_match_flag[i]	u(1)
}	
} else	
all_tiles_ilc_idc	u(2)
}	

F.14.1.3 Bitstream partition nesting SEI message syntax

bsp_nesting(payloadSize) {	**Descriptor**
bsp_idx	ue(v)
while(!byte_aligned( ))	
bsp_nesting_zero_bit /* equal to 0 */	u(1)
do	
sei_message( )	
while(more_rbsp_data( ))	
}	

F.14.1.4 Bitstream partition initial arrival time SEI message syntax

bsp_initial_arrival_time(payloadSize) {	**Descriptor**
if(NalHrdBpPresentFlag)	
for(i = 0; i < SchedCombCnt[nesting_op_idx[0]]; i++)	
nal_initial_arrival_delay[i]	u(v)
else	
for(i = 0; i < SchedCombCnt[nesting_op_idx[0]]; i++)	
vcl_initial_arrival_delay[i]	u(v)
}	

F.14.1.5 Bitstream partition HRD parameters SEI message syntax

bsp_hrd(payloadSize) {	**Descriptor**
sei_num_bsp_hrd_parameters_minus1	ue(v)
for(i = 0; i <= sei_num_bsp_hrd_parameters_minus1; i++) {	
if(i > 0)	
sei_bsp_cprms_present_flag[i]	u(1)
hrd_parameters(sei_bsp_cprms_present_flag[i], nesting_max_temporal_id_plus1[0] − 1)	
}	
for(h = 0; h <= nesting_num_ops_minus1; h++) {	
lsIdx = nesting_op_idx[h]	
num_sei_bitstream_partitions_minus1[lsIdx]	ue(v)
for(i = 0; i <= num_sei_bitstream_partitions_minus1[lsIdx]; i++)	
for(j = 0; j < NumLayersInIdList[lsIdx]; j++)	
sei_layer_in_bsp_flag[lsIdx][i][j]	u(1)
sei_num_bsp_sched_combinations_minus1[lsIdx]	ue(v)
for(i = 0; i <= sei_num_bsp_sched_combinations_minus1[lsIdx]; i++)	
for(j = 0; j <= num_sei_bitstream_partitions_minus1[lsIdx]; j++) {	
sei_bsp_comb_hrd_idx[lsIdx][i][j]	u(v)
sei_bsp_comb_sched_idx[lsIdx][i][j]	ue(v)
}	
}	
}	

F.14.1.6 Sub-bitstream property SEI message syntax

sub_bitstream_property(payloadSize) {	**Descriptor**
sb_property_active_vps_id	u(4)
num_additional_sub_streams_minus1	ue(v)
for(i = 0; i <= num_additional_sub_streams_minus1; i++) {	
sub_bitstream_mode[i **]**	u(2)
ols_idx_to_vps[i]	ue(v)
highest_sublayer_id[i]	u(3)
avg_sb_property_bit_rate[i]	u(16)
max_ sb_property_bit_rate[i]	u(16)
}	
}	

F.14.1.7 Alpha channel information SEI message syntax

alpha_channel_info(payloadSize) {	**Descriptor**
alpha_channel_cancel_flag	u(1)
if(!alpha_channel_cancel_flag) {	
alpha_channel_use_idc	u(3)
alpha_channel_bit_depth_minus8	u(3)
alpha_transparent_value	u(v)
alpha_opaque_value	u(v)
alpha_channel_incr_flag	u(1)
alpha_channel_clip_flag	u(1)
if(alpha_channel_clip_flag)	
alpha_channel_clip_type_flag	u(1)
}	
}	

F.14.1.8 Overlay information SEI message syntax

[Ed. (GT): All this "information" and "info" in SEI message names is redundant. However, this is already in base spec.]

overlay_info(payloadSize) {	**Descriptor**
overlay_info_cancel_flag	u(1)
if(!overlay_info_cancel_flag) {	
overlay_content_aux_id_minus128	ue(v)
overlay_label_aux_id_minus128	ue(v)
overlay_alpha_aux_id_minus128	ue(v)
num_overlays_minus1	ue(v)
for(i = 0; i <= num_overlays_minus1; i++) {	
overlay_idx[i]	ue(v)
overlay_name[i]	st(v)
overlay_content_layer_id[i]	u(6)
overlay_label_present_flag[i]	u(1)
if(overlay_label_present_flag[i])	
overlay_label_layer_id[i]	u(6)
overlay_alpha_present_flag[i]	u(1)
if(overlay_alpha_present_flag[i])	
overlay_alpha_layer_id[i]	u(6)
if(overlay_label_present_flag[i]) {	
num_overlay_elements_minus1[i]	ue(v)
for(j = 0; j <= num_overlay_elements_minus1[i]; j++) {	
overlay_element_name[i][j]	st(v)
overlay_element_label_min[i][j]	u(v)
overlay_element_label_max[i][j]	u(v)
}	
}	
}	
overlay_info_persistence_flag	u(1)
}	
}	

F.14.1.9 Temporal motion vector prediction constraints SEI message syntax

temporal_motion_vector_prediction_constraints(payloadSize) {	**Descriptor**
prev_pics_not_used_flag	u(1)
no_intra_layer_col_pic_flag	u(1)
}	

F.14.1.10 Frame-field information SEI message syntax

frame_field_info(payloadSize) {	**Descriptor**
ffinfo_pic_struct	u(4)
ffinfo_source_scan_type	u(2)
ffinfo_duplicate_flag	u(1)
}	

F.14.1.11 OLS nesting SEI message syntax

ols_nesting(payloadSize) {	**Descriptor**
ols_flag	u(1)
num_ols_indices_minus1	ue(v)
for(i = 0; i <= num_ols_indices_minus1; i++)	
ols_idx[i]	ue(v)
while(!byte_aligned( ))	
ols_nesting_zero_bit /* equal to 0 */	u(1)
do	
sei_message( )	
while(more_data_in_payload( ))	
}	

F.14.1.12 VPS rewriting SEI message syntax

vps_rewriting(payloadSize) {	**Descriptor**
nal_unit(payloadSize)	
}	

F.14.2 SEI message semantics

Table F-3 – Persistence scope of SEI messages (informative)

SEI message	Persistence scope
Layers not present	The access unit containing the SEI message and up to but not including the next access unit, in decoding order, that contains a layers not present SEI message or the end of the CVS, whichever is earlier in decoding order [Ed. (AR): Would be better to move this to semantics of SEI, as done for other SEI messages.]
Inter-layer constrained tile sets	The CVS containing the SEI message
Bitstream partition nesting	Depending on the nested SEI messages. Each nested SEI message has the same persistence scope as if the SEI message was not nested
Bitstream partition initial arrival time	The remainder of the bitstream partition (specified by the containing bitstream partition nesting SEI message)
Bitstream partition HRD parameters	The CVS containing the SEI message
Sub-bitstream property	The CVS containing the SEI message
Alpha channel information	Specified by the syntax of the SEI message
Overlay information	Specified by the syntax of the SEI message
Temporal motion vector prediction constraints	Specified by the semantics of the SEI message in subclause F.14.2.9
Frame-field information	One or more pictures of the access unit containing the SEI message [Ed. (YK): To be aligned with version 1, this should be "The access unit containing the SEI message", same as picture timing SEI message. This table column should be interpreted as the persistence scope in the temporal direction or on AU level. We should clarify this a bit, and check this for all the new SEI messages, as well as all the old ones taking into account the multi-layer context. (MH): Agreed.]
OLS nesting	Depending on the nested SEI messages. Each nested SEI message has the same persistence scope as if the SEI message was not nested
VPS rewriting	Specified in subclause F.10.2

The constraints of bitstream conformance specified in clause D.3.1 apply with the following additions.

Let prevVclNalUnitInAu of an SEI NAL unit or an SEI message be the preceding VCL NAL unit in decoding order, if any, in the same access unit, and nextVclNalUnitInAu of an SEI NAL unit or an SEI message be the next VCL NAL unit in decoding order, if any, in the same access unit. It is a requirement of bitstream conformance that the following restrictions apply:

– When a bitstream partition HRD parameters SEI message contained in a scalable nesting SEI message is present in an access unit, the scalable nesting SEI message shall not follow any other SEI message that follows the prevVclNalUnitInAu of the scalable nesting SEI message and precedes the nextVclNalUnitInAu of the scalable nesting SEI message, other than an active parameter sets SEI message, a non-nested buffering period SEI message, a non-nested picture timing SEI message, a non-nested decoding unit information SEI message, a scalable nesting SEI message including a buffering period SEI message, a picture timing SEI message or a decoding unit information SEI message, or another scalable nesting SEI message that contains a bitstream partition HRD parameters SEI message.

– When a buffering period SEI message, a picture timing SEI message, a decoding unit information SEI message or a bitstream partition initial arrival time SEI message is present in a bitstream partition nesting SEI message contained in a scalable nesting SEI message, the scalable nesting SEI message shall not follow any other SEI message that follows the prevVclNalUnitInAu of the scalable nesting SEI message and precedes the nextVclNalUnitInAu of the scalable nesting SEI message, other than an active parameter sets SEI message, a non-nested buffering period SEI message, a non-nested picture timing SEI message, a non-nested decoding unit information SEI message, a scalable nesting SEI message including a buffering period SEI message, a picture timing SEI message or a decoding unit

information SEI message, a scalable nesting SEI message including a bitstream partition HRD parameters SEI message, or another scalable nesting SEI message that contains a bitstream partition nesting SEI message including a buffering period SEI message, a picture timing SEI message, a decoding unit information SEI message or a bitstream partition initial arrival time SEI message.

F.14.2.1 Layers not present SEI message semantics

The layers not present SEI message provides a mechanism for signalling that VCL NAL units of particular layers indicated by the VPS are not present in a particular set of access units.

The target access units are defined as the set of access units starting from the access unit containing the layers not present SEI message up to but not including the next access unit, in decoding order, that contains a layers not present change SEI message or the end of the CVS, whichever is earlier in decoding order.

When present, the layers not present SEI message applies to the target access units.

A layers not present SEI message shall not be included in a scalable nesting SEI message.

A layers not present SEI message shall not be included in an SEI NAL unit with TemporalId greater than 0.

lnp_sei_active_vps_id identifies the active VPS of the CVS containing the layers not present SEI message. The value of lnp_sei_active_vps_id shall be equal to the value of vps_video_parameter_set_id of the active VPS for the VCL NAL units of the access unit containing the SEI message.

layer_not_present_flag[i] equal to 1 indicates that there are no VCL NAL units with nuh_layer_id equal to layer_id_in_nuh[i] present in the target access units. layer_not_present_flag[i] equal to 0 indicates that there may or may not be VCL NAL units with nuh_layer_id equal to layer_id_in_nuh[i] present in the target access units.

When layer_not_present_flag[i] is equal to 1 and i is less than MaxLayersMinus1, layer_not_present_flag[LayerIdxInVps[PredictedLayerId[layer_id_in_nuh[i]][j]]] shall be equal to 1 for all values of j in the range of 0 to NumPredictedLayers[layer_id_in_nuh[i]] − 1, inclusive.

F.14.2.2 Inter-layer constrained tile sets SEI message semantics

The scope of the inter-layer constrained tile sets SEI message is the complete CVS. When an inter-layer tile sets SEI message is present in any access unit of a CVS, it shall be present for the first access unit of the CVS in decoding order and may also be present for other access units of the CVS.

The inter-layer constrained tile sets SEI message shall not be present for a layer when tiles_enabled_flag is equal to 0 for any PPS that is active for the layer.

The inter-layer constrained tile sets SEI message shall not be present for a layer unless every PPS that is active for the layer has tile_boundaries_aligned_flag equal to 1 or fulfills the conditions that would be indicated by tile_boundaries_aligned_flag being equal to 1.

The presence of the inter-layer tile sets SEI message indicates that the inter-layer prediction process is constrained such that no sample value outside each identified tile set, and no sample value at a fractional sample position that is derived using one or more sample values outside the identified tile set, is used for inter-layer prediction of any sample within the identified tile set. [Ed. (AR). Should tile set be defined here?]

NOTE 1 – When loop filtering and resampling filter is applied across tile boundaries, inter-layer prediction of any samples within an inter-layer constrained tile set that refers to samples within 8 samples from an inter-layer constrained tile set boundary that is not also a picture boundary may result in propagation of mismatch error. An encoder can avoid such potential error propagation by avoiding the use of motion vectors that cause such references.

When more than one inter-layer constrained tile sets SEI message is present within the access units of a CVS, they shall contain identical content.

The number of inter-layer constrained tile sets SEI messages in each access unit shall not exceed 5.

il_all_tiles_exact_sample_value_match_flag equal to equal to 1 indicates that, within the CVS, when the coding tree blocks that are outside of any identified tile are not decoded and the boundaries of the identified tile is treated as picture boundaries for purposes of the decoding process, the value of each sample in the identified tile would be exactly the same as the value of the sample that would be obtained when all the coding tree blocks of all pictures in the CVS are decoded. il_all_tiles_exact_sample_value_match_flag equal to 0 indicates that, within the CVS, when the coding tree blocks that are outside of any identified tile are not decoded and the boundaries of the identified tile is treated as picture boundaries for purposes of the decoding process, the value of each sample in the identified tile may or may not be exactly the same as the value of the same sample when all the coding tree blocks of all pictures in the CVS are decoded.

il_one_tile_per_tile_set_flag equal to 1 indicates that each inter-layer constrained tile set contains one tile, and il_num_sets_in_message_minus1 is not present. When il_one_tile_per_tile_set_flag is equal to zero, tile sets are signalled explicitly.

il_num_sets_in_message_minus1 plus 1 specifies the number of inter-layer tile sets identified in the SEI message. The value of il_num_sets_in_message_minus1 shall be in the range of 0 to 255, inclusive.

skipped_tile_set_present_flag equal to 1 indicates that, within the CVS, the tile set consists of those remaining tiles that are not included in any earlier tile sets in the same message and all the prediction blocks that are inside the identified tile set having nuh_layer_id equal to ictsNuhLayerId are inter-layer predicted from inter-layer reference pictures with nuh_layer_id equal to RefLayerId[ictsNuhLayerId][NumDirectRefLayers[ictsNuhLayerId] − 1] and no residual_coding( ) syntax structure is present in any transform unit of the identified tile set, where ictsNuhLayerId is the value of nuh_layer_id of this SEI message. skipped_tile_set_present_flag equal to 0 does not indicate a bitstream constraint within the CVS. When not present, the value of skipped_tile_set_present_flag is inferred to be equal to 0. [Ed. (AR). All occurrences of "tile set having nuh_layer_id equal to ictsNuhLayerId" may have to be modified based on the definition of tile set.]

ilcts_id[i] contains an identifying number that may be used to identify the purpose of the i-th identified tile set (for example, to identify an area to be extracted from the coded video sequence for a particular purpose). The value of ilcts_id[i] shall be in the range of 0 to $2^{32} - 2$, inclusive.

Values of ilcts_id[i] from 0 to 255 and from 512 to $2^{31} - 1$ may be used as determined by the application. Values of ilcts_id[i] from 256 to 511 and from 2^{31} to $2^{32} - 2$ are reserved for future use by ITU-T | ISO/IEC. Decoders encountering a value of ilcts_id[i] in the range of 256 to 511 or in the range of 2^{31} to $2^{32} - 2$ shall ignore (remove from the bitstream and discard) it.

il_num_tile_rects_in_set_minus1[i] plus 1 specifies the number of rectangular regions of tiles in the i-th identified inter-layer constrained tile set. The value of il_num_tile_rects_in_set_minus1[i] shall be in the range of 0 to (num_tile_columns_minus1 + 1) * (num_tile_rows_minus1 + 1) − 1, inclusive.

il_top_left_tile_index[i][j] and **il_bottom_right_tile_index**[i][j] identify the tile position of the top-left tile and the tile position of the bottom-right tile in a rectangular region of the i-th identified inter-layer constrained tile set, respectively, in tile raster scan order.

ilc_idc[i] equal to 1 indicates that, within the CVS, no samples outside of the i-th identified tile set and no samples at a fractional sample position that is derived using one or more samples outside of the i-th identified tile set are used for inter-layer prediction of any sample within the i-th identified tile set with nuh_layer_id equal to ictsNuhLayerId, where ictsNuhLayerId is the value of nuh_layer_id of this message. ilc_idc[i] equal to 2 indicates that, within the CVS, no prediction block in the i-th identified tile set with nuh_layer_id equal to ictsNuhLayerId is predicted from an inter-layer reference picture. ilc_idc[i] equal to 0 indicates that, within the CVS, the inter-layer prediction process may or may not be constrained for the prediction block in the i-th identified tile set having nuh_layer_id equal to ictsNuhLayerId. The value of ilc_idc[i] equal to 3 is reserved.

il_exact_sample_value_match_flag[i] equal to 1 indicates that, within the CVS, when the coding tree blocks that do not belong to the inter-layer constrained tile set are not decoded and the boundaries of the i-th inter-layer constrained tile set are treated as picture boundaries for purposes of the decoding process, the value of each sample in the inter-layer constrained tile set would be exactly the same as the value of the sample that would be obtained when all the coding tree blocks of all pictures in the coded video sequence are decoded. il_exact_sample_value_match_flag[i] equal to 0 indicates that, within the CVS, when the coding tree blocks that are outside of the i-th identified inter-layer constrained tile set are not decoded and the boundaries of the i-th inter-layer constrained tile set are treated as picture boundaries for purposes of the decoding process, the value of each sample in the identified tile set may or may not be exactly the same as the value of the same sample when all the coding tree blocks of the picture are decoded.

NOTE 2 – It should be feasible to use il_exact_sample_value_match_flag equal to 1 when using certain combinations of loop_filter_across_tiles_enabled_flag, pps_loop_filter_across_slices_enabled_flag, pps_deblocking_filter_disabled_flag, slice_loop_filter_across_slices_enabled_flag, slice_deblocking_filter_disabled_flag, sample_adaptive_offset_enabled_flag, slice_sao_luma_flag, and slice_sao_chroma_flag.

all_tiles_ilc_idc equal to 1 indicates that, within the CVS, no sample value outside of each identified tile and no sample value at a fractional sample position that is derived using one or more samples outside of the identified tile is used for inter-layer prediction of any sample within the identified tile with nuh_layer_id equal to ictsNuhLayerId, where ictsNuhLayerId is the value of nuh_layer_id of this SEI message. all_tiles_ilc_idc equal to 2 indicates that, within the CVS, no prediction block in each identified tile with nuh_layer_id equal to ictsNuhLayerId is predicted from an inter-layer reference picture. all_tiles_ilc_idc equal to 0 indicates that, within the CVS, the inter-layer prediction process may or may not be constrained for the tile having nuh_layer_id equal to ictsNuhLayerId. The value of all_tiles_ilc_idc equal to 3 is reserved. [Ed (AR). Default value of all_tiles_ilc_idc should be zero?]

F.14.2.3 Bitstream partition nesting SEI message semantics

The bitstream partition nesting SEI message provides a mechanism to associate SEI messages with a bitstream partition of a layer set.

When present, this SEI message shall be contained within a scalable nesting SEI message. When this SEI message is contained in a scalable nesting SEI message, it shall be the only nested SEI message. In the scalable nesting SEI message containing this SEI message, bitstream_subset_flag shall be equal to 1, nesting_op_flag shall be equal to 1, default_op_flag shall be equal to 0, nesting_num_ops_minus1 shall be equal to 0, and nesting_op_idx[0] shall not be equal to 0. The nuh_layer_id of the SEI NAL unit shall be equal to the highest value within the list nestingLayerIdList[0].

A bitstream partition nesting SEI message contains one or more SEI messages.

bsp_idx is used to specify the bitstream partition to which the contained SEI message applies as follows:

– If vps_vui_bsp_hrd_present_flag is equal to 1, bsp_idx is an index among the bitstream partitions specified for the layer set with index nesting_op_idx[0] in the vps_vui_bsp_hrd_parameters( ) syntax structure.

– Otherwise, an associated bitstream partition HRD parameters SEI message shall be present. The associated bitstream partition HRD parameter SEI message for the bitstream partition nesting SEI message is the preceding bitstream partition HRD parameters SEI message, in decoding order, that is nested in a scalable nesting SEI message with nesting_op_idx[i] that, with any value of i in the range of 0 to nesting_num_ops_minus1, inclusive, of the scalable nesting SEI message containing the bitstream partition HRD parameters SEI message, is equal to nesting_op_idx[0] of the scalable nesting SEI message containing the bitstream partition nesting SEI message. It is a requirement of bitstream conformance that when a bitstream partition nesting SEI message is present, it shall have an associated bitstream partition HRD parameters SEI message within the same coded video sequence. bsp_idx is an index among the bitstream partitions specified in the associated bitstream partition HRD parameters SEI message.

bsp_nesting_zero_bit shall be equal to 0.

F.14.2.4 Bitstream partition initial arrival time SEI message semantics

The bitstream partition initial arrival time SEI message specifies the initial arrival times to be used in the bitstream-partition-specific CPB operation.

When present, this SEI message shall be contained within a bitstream partition nesting SEI message that is contained in a scalable nesting SEI message. The same bitstream partition nesting SEI message shall also contain a buffering period SEI message.

Let hrdParamIdx be equal to the index of the hrd_parameters( ) syntax structure in the active VPS for which hrd_layer_set_idx[hrdParamIdx] is equal to nesting_op_idx[0] of the scalable nesting SEI message that contains the bitstream partition SEI message containing this bitstream partition initial arrival time SEI message. Let initialCpbRemovalDelayLength be equal to initial_cpb_removal_delay_length_minus1 + 1, where initial_cpb_removal_delay_length_minus1 is found in the hrdParamIdx-th hrd_parameters( ) syntax structure in the active VPS.

nal_initial_arrival_delay[i] specifies the initial arrival time for the i-th schedule combination of the bitstream partition to which this SEI message applies, when NAL HRD parameters are in use. The length, in bits, of the nal_initial_arrival_delay[i] syntax element is equal to initialCpbRemovalDelayLength.

vcl_initial_arrival_delay[i] specifies the initial arrival time for the i-th schedule combination of the bitstream partition to which this SEI message applies, when VCL HRD parameters are in use. The length, in bits, of the vcl_initial_arrival_delay[i] syntax element is equal to initialCpbRemovalDelayLength.

F.14.2.5 Bitstream partition HRD parameters SEI message semantics

The bitstream partition HRD parameters SEI message specifies HRD parameters for bitstream-partition-specific CPB operation.

When present, this SEI message shall be contained within a scalable nesting SEI message in an initial IRAP access unit. When this SEI message is contained in a scalable nesting SEI message, it shall be the only nested SEI message. In the scalable nesting SEI message containing this SEI message, bitstream_subset_flag shall be equal to 1, nesting_op_flag shall be equal to 1 and default_op_flag shall be equal to 0. The nuh_layer_id of the SEI NAL unit shall be equal to the highest value within the lists nestingLayerIdList[h] with h in the range of 0 to nesting_num_ops_minus1, inclusive.

When both this SEI message and the vps_vui_bsp_hrd_parameters( ) syntax structure in the active VPS are present, the contents of this SEI message shall be semantically identical to the contents of the vps_vui_bsp_hrd_parameters( ) syntax structure of the active VPS.

sei_num_bsp_hrd_parameters_minus1 plus 1 specifies the number of hrd_parameters( ) syntax structures present within this SEI message.

sei_bsp_cprms_present_flag[i] equal to 1 specifies that the HRD parameters that are common for all sub-layers are present in the i-th hrd_parameters( ) syntax structure in this SEI message. sei_bsp_cprms_present_flag[i] equal to 0 specifies that the HRD parameters that are common for all sub-layers are not present in the i-th hrd_parameters( ) syntax structure in this SEI message and are derived to be the same as the (i − 1)-th hrd_parameters( ) syntax structure in this SEI message. sei_bsp_cprms_present_flag[0] is inferred to be equal to 1.

For the subsequent syntax elements of this SEI message, the variable lsIdx is set equal to nesting_op_idx[h]. It is a requirement of bitstream conformance that when a scalable nesting SEI message includes a bitstream partition HRD parameters SEI message, nesting_op_idx[h] shall not be equal to 0 for any value of h in the range of 0 to nesting_num_ops_minus1, inclusive.

num_sei_bitstream_partitions_minus1[lsIdx] plus 1 specifies the number of bitstream partitions for which HRD parameters are specified for the layer set with index lsIdx.

sei_layer_in_bsp_flag[lsIdx][i][j] specifies that the layer with index LayerSetLayerIdList[lsIdx][j] is a part of bitstream partition with index i within the layer set with index lsIdx.

It is a requirement of bitstream conformance that the following constraints apply:

– The bitstream partition with index j shall not include direct or indirect reference layers of any layers in the bitstream partition with index i for any values of i and j in the range of 0 to num_sei_bitstream_partitions_minus1[lsIdx], inclusive, such that i is less than j.

– When vps_base_layer_internal_flag is equal to 0 and sei_layer_in_bsp_flag[lsIdx][i][0] is equal to 1 for any value of h in the range of 0 to nesting_num_ops_minus1, inclusive, and any value of i in the range of 0 to num_sei_bitstream_partitions_minus1[lsIdx], inclusive, the value of sei_layer_in_bsp_flag[lsIdx][i][j] for at least one value of j in the range of 1 to NumLayersInIdList[lsIdx] − 1, inclusive, shall be equal to 1.

[Ed. (GT): The following item corresponds to items 5/6 in Q0101 and might, according to meeting notes, require further alignment for the case that the base layer is externally specified.]

– When num_sei_bitstream_partitions_minus1[lsIdx] is equal to 0 for any value of h in the range 0 to nesting_num_ops_minus1, inclusive, the value of sei_layer_in_bsp_flag[lsIdx][0][j] should be equal to 0 for at least one value of j in the range 0 to NumLayersInIdList[lsIdx] − 1, inclusive.

– For any value of h in the range 1 to nesting_num_ops_minus1, inclusive, the value of sei_layer_in_bsp_flag[h][i][j] shall be equal to 1 for at most one value of i in the range 0 to num_sei_bitstream_partitions_minus1, inclusive.

sei_num_bsp_sched_combinations_minus1[lsIdx] plus 1 specifies the number of combinations of delivery schedules and hrd_parameters( ) specified for bitstream partitions for the layer set with index lsIdx.

The variable SchedCombCnt[lsIdx] is set equal to sei_num_bsp_sched_combinations_minus1[lsIdx] + 1.

sei_bsp_comb_hrd_idx[lsIdx][i][j] specifies the index of hrd_parameters( ) within this SEI message used in the i-th combination of a delivery schedule and hrd_parameters( ) specified for the bitstream partition with index j and for the layer set with index lsIdx. The value of sei_bsp_comb_hrd_idx[lsIdx][i][j] shall be in the range of 0 to sei_num_bsp_hrd_parameters_minus1, inclusive. The length of the sei_bsp_comb_hrd_idx[lsIdx][i][j] syntax element is Ceil(Log2(sei_num_bsp_hrd_parameters_minus1 + 1)) bits.

sei_bsp_comb_sched_idx[lsIdx][i][j] specifies the index of a delivery schedule within the hrd_parameters( ) syntax structure with the index sei_bsp_comb_hrd_idx[lsIdx][i][j] that is used in the i-th combination of a delivery schedule and hrd_parameters( ) specified for the bitstream partition with index j and for the layer set with index lsIdx. The value of sei_bsp_comb_sched_idx[lsIdx][i][j] shall be in the range of 0 to cpb_cnt_minus1[HighestTid], inclusive, where cpb_cnt_minus1[HighestTid] is found in the sub_layer_hrd_parameters(HighestTid) syntax structure from the hrd_parameters( ) syntax structure corresponding to the index sei_bsp_comb_hrd_idx[lsIdx][i][j].

F.14.2.6 Sub-bitstream property SEI message semantics

The sub-bitstream property SEI message, when present, provides the bit rate information for a sub-bitstream created by discarding those pictures in the layers that do not belong to the output layers of the OLSs specified by the active VPS and that do not affect the decoding of the output layers.

When present, the sub-bitstream property SEI message shall be associated with an initial IRAP access unit, and the information provided by the SEI messages applies to the bitstream corresponding to the CVS containing the associated initial IRAP access unit.

sb_property_active_vps_id identifies the active VPS. The value of sb_property_active_vps_id shall be equal to the value of vps_video_parameter_set_id of the active VPS referred to by the VCL NAL units of the associated access unit.

num_additional_sub_streams_minus1 plus 1 specifies the number of the sub-bitstreams for which the bit rate information may be provided by this SEI message. The value of num_additional_sub_streams_minus1 shall be in the range of 0 to $2^{10}-1$, inclusive.

sub_bitstream_mode[i **]** specifies how the i-th sub-bitstream is generated. The value of sub_bitstream_mode[i] shall be equal to 0 or 1, inclusive. The values 2 and 3 are reserved for future use by ITU-T and ISO/IEC. When sub_bitstream_mode[i] is the greater than 1, decoders shall ignore the syntax elements ols_idx_to_vps[i], highest_sublayer_id[i], avg_sb_property_bit_rate[i], and max_sb_property_bit_rate[i].

When sub_bitstream_mode[i] is equal to 0, the i-th sub-bitstream is generated as specified by the following steps:

– The sub-bitstream extraction process as specified in clause 10 is invoked with the bitstream corresponding to the CVS containing the sub-bitstream property SEI message, highest_sublayer_id[i], and LayerSetLayerIdList[OlsIdxToLsIdx[ols_idx_to_vps[i]]] as inputs.

– Remove all NAL units for which the nuh_layer_id is not included in TargetOptLayerIdList and either of the following conditions is true:

  – The value of nal_unit_type is not in the range of BLA_W_LP to RSV_IRAP_VCL23, inclusive, and max_tid_il_ref_pics_plus1[LayerIdxInVps[nuh_layer_id]][LayerIdxInVps[layerId]] is equal to 0 for layerId values included in TargetOptLayerIdList.

  – TemporalId is greater than the maximum value of max_tid_il_ref_pics_plus1[LayerIdxInVps[nuh_layer_id]][LayerIdxInVps[layerId]] − 1 for all layerId values included in TargetOptLayerIdList.

When sub_bitstream_mode[i] is equal to 1, the i-th sub-bitstream is generated as specified by the above steps followed by:

– Remove all NAL units with nuh_layer_id not among the values included in TargetOptLayerIdList and with discardable_flag equal to 1.

ols_idx_to_vps[i **]** specifies the index of the OLS corresponding to the i-th sub-bitstream.

highest_sublayer_id[i] specifies the highest TemporalId of access units in the i-th sub-bitstream.

avg_sb_property_bit_rate[i] indicates the average bit rate of the i-th sub-bitstream, in bits per second. The value is given by BitRateBPS(avg_sb_property_bit_rate[i]) with the function BitRateBPS( ) being specified as follows:

$$BitRateBPS(x) = (x \,\&\, (2^{14} - 1)) * 10^{(2 + (x >> 14))} \quad \text{(F-32)}$$

The average bit rate is derived according to the access unit removal time specified in clause F.13. In the following, bTotal is the number of bits in all NAL units of the i-th sub-bitstream, t_1 is the removal time (in seconds) of the first access unit to which the VPS applies, and t_2 is the removal time (in seconds) of the last access unit (in decoding order) to which the VPS applies. With x specifying the value of avg_sb_property_bit_rate[i], the following applies:

– If t_1 is not equal to t_2, the following condition shall be true:

$$(x \,\&\, (2^{14} - 1)) == Round(bTotal \div ((t_2 - t_1) * 10^{(2 + (x >> 14))})) \quad \text{(F-33)}$$

– Otherwise (t_1 is equal to t_2), the following condition shall be true:

$$(x \,\&\, (2^{14} - 1)) == 0 \quad \text{(F-34)}$$

max_sb_property_bit_rate[i] indicates an upper bound for the bit rate of the i-th sub-bitstream in any one-second time window of access unit removal time as specified in clause F.13. The upper bound for the bit rate in bits per second is given by BitRateBPS(max_sb_property_bit_rate[i]). The bit rate values are derived according to the access unit removal time specified in clause F.13. In the following, t_1 is any point in time (in seconds), t_2 is set equal to $t_1 + 1 \div 100$, and bTotal is the number of bits in all NAL units of access units with a removal time greater than or equal to t_1 and less than t_2. With x specifying the value of max_sb_property_bit_rate[i], the following condition shall be obeyed for all values of t_1:

$$(x \,\&\, (2^{14} - 1)) >= bTotal \div ((t_2 - t_1) * 10^{(2 + (x >> 14))}) \quad \text{(F-35)}$$

F.14.2.7 Alpha channel information SEI message semantics

The alpha channel information SEI message provides information about alpha channel sample values and post-

processing applied to the decoded alpha planes coded in auxiliary pictures of type AUX_ALPHA, and one or more associated primary pictures.

For an auxiliary picture with nuh_layer_id equal to nuhLayerIdA and AuxId[nuhLayerIdA] equal to AUX_ALPHA, an associated primary picture, if any, is a picture in the same access unit having AuxId[nuhLayerIdB] equal to 0 such that ScalabilityId[LayerIdxInVps[nuhLayerIdA]][j] is equal to ScalabilityId[LayerIdxInVps[nuhLayerIdB]][j] for all values of j in the range of 0 to 2, inclusive, and 4 to 15, inclusive.

alpha_channel_cancel_flag equal to 1 indicates that the alpha channel information SEI message cancels the persistence of any previous alpha channel information SEI message in output order. alpha_channel_cancel_flag equal to 0 indicates that alpha channel information follows. [Ed. (YK): The following persistency scope of this SEI message needs to be adjusted to make it clear for multi-layer context, probably similarly as did for other SEI messages with similar syntax-specified scope.]

When an access unit contains an auxiliary picture picA with nuh_layer_id equal to nuhLayerIdA and AuxId[nuhLayerIdA] equal to AUX_ALPHA, the alpha channel sample values of picA persist in output order until one or more of the following conditions are true:

– A new CVS begins.

– The bitstream ends.

– A picture picB in an access unit containing an alpha channel information SEI message is output having PicOrderCnt(picB) greater than PicOrderCnt(picA) and alpha_channel_cancel_flag in the alpha channel information SEI message is equal to 1, where PicOrderCnt(picB) and PicOrderCnt(picA) are the PicOrderCntVal values of picB and picA, respectively, immediately after the invocation of the decoding process for picture order count for picB.

alpha_channel_use_idc equal to 0 indicates that for alpha blending purposes the decoded samples of the associated primary picture should be multiplied by the interpretation sample values of the auxiliary coded picture in the display process after output from the decoding process. alpha_channel_use_idc equal to 1 indicates that for alpha blending purposes the decoded samples of the associated primary picture should not be multiplied by the interpretation sample values of the auxiliary coded picture in the display process after output from the decoding process. alpha_channel_use_idc equal to 2 indicates that the usage of the auxiliary picture is unspecified. Values greater than 2 for alpha_channel_use_idc are reserved for future use by ITU-T | ISO/IEC. When not present, the value of alpha_channel_use_idc is inferred to be equal to 2.

alpha_channel_bit_depth_minus8 plus 8 specifies the bit depth of the samples of the sample array of the auxiliary picture. alpha_channel_bit_depth_minus8 shall be in the range 0 to 7 inclusive. alpha_channel_bit_depth_minus8 shall be equal to bit_depth_luma_minus8 of the associated primary picture.

alpha_transparent_value specifies the interpretation sample value of an auxiliary coded picture sample for which the associated luma and chroma samples of the primary coded picture are considered transparent for purposes of alpha blending. The number of bits used for the representation of the alpha_transparent_value syntax element is alpha_channel_bit_depth_minus8 + 9.

alpha_opaque_value specifies the interpretation sample value of an auxiliary coded picture sample for which the associated luma and chroma samples of the primary coded picture are considered opaque for purposes of alpha blending. The number of bits used for the representation of the alpha_opaque_value syntax element is alpha_channel_bit_depth_minus8 + 9.

alpha_channel_incr_flag equal to 0 indicates that the interpretation sample value for each decoded auxiliary picture sample value is equal to the decoded auxiliary picture sample value for purposes of alpha blending. alpha_channel_incr_flag equal to 1 indicates that, for purposes of alpha blending, after decoding the auxiliary picture samples, any auxiliary picture sample value that is greater than Min(alpha_opaque_value, alpha_transparent_value) should be increased by one to obtain the interpretation sample value for the auxiliary picture sample, and any auxiliary picture sample value that is less than or equal to Min(alpha_opaque_value, alpha_transparent_value) should be used without alteration as the interpretation sample value for the decoded auxiliary picture sample value. When not present, the value of alpha_channel_incr_flag is inferred to be equal to 0.

alpha_channel_clip_flag equal to 0 indicates that no clipping operation is applied to obtain the interpretation sample values of the decoded auxiliary picture. alpha_channel_clip_flag equal to 1 indicates that the interpretation sample values of the decoded auxiliary picture are altered according to the clipping process described by the alpha_channel_clip_type_flag syntax element. When not present, the value of alpha_channel_clip_flag is inferred to be equal to 0.

alpha_channel_clip_type_flag equal to 0 indicates that, for purposes of alpha blending, after decoding the auxiliary picture samples, any auxiliary picture sample that is greater than (alpha_opaque_value − alpha_transparent_value) / 2 is set equal to alpha_opaque_value to obtain the interpretation sample value for the auxiliary picture sample, and any

auxiliary picture sample that is less or equal than (alpha_opaque_value − alpha_transparent_value) / 2 is set equal to alpha_transparent_value to obtain the interpretation sample value for the auxiliary picture sample. alpha_channel_clip_type_flag equal to 1 indicates that, for purposes of alpha blending, after decoding the auxiliary picture samples, any auxiliary picture sample that is greater than alpha_opaque_value is set equal to alpha_opaque_value to obtain the interpretation sample value for the auxiliary picture sample, and any auxiliary picture sample that is less than or equal to alpha_transparent_value is set equal to alpha_transparent_value to obtain the interpretation sample value for the auxiliary picture sample.

NOTE – When both alpha_channel_incr_flag and alpha_channel_clip_flag are equal to one, the clipping operation specified by alpha_channel_clip_type_flag should be applied first followed by the alteration specified by alpha_channel_incr_flag to obtain the interpretation sample value for the auxiliary picture sample.

F.14.2.8 Overlay information SEI message semantics

The overlay information SEI message provides information about overlay pictures coded as auxiliary pictures. Overlay auxiliary pictures have nuh_layer_id equal to nuhLayerIdA and AuxId[nuhLayerIdA] in the range of 128 to 143, inclusive. Each overlay auxiliary picture layer is associated with one or more primary picture layers as specified below.

overlay_info_cancel_flag equal to 1 indicates that the SEI message cancels the persistence of any previous overlay information SEI message in output order. overlay_info_cancel_flag equal to 0 indicates that overlay information follows.

overlay_content_aux_id_minus128 plus 128 indicates the value of AuxId of auxiliary pictures containing overlay content. overlay_content_aux_id_minus128 shall be in the range of 0 to 15, inclusive.

overlay_label_aux_id_minus128 plus 128 indicates the value of AuxId of auxiliary pictures containing overlay label. overlay_label_aux_id_minus128 shall be in the range of 0 to 15, inclusive.

overlay_alpha_aux_id_minus128 plus 128 indicates the value of AuxId of auxiliary pictures containing overlay alpha. overlay_alpha_aux_id_minus128 shall be in the range of 0 to 15, inclusive.

num_overlays_minus1 plus 1 specifies the number of overlays described by the overlay information SEI message. num_overlays_minus1 shall be in the range of 0 to 15, inclusive.

overlay_idx[i] indicates the index of the i-th overlay. overlay_idx[i] shall be in the range of 0 to 255, inclusive.

overlay_name[i] indicates the name of the i-th overlay. The length of the syntax element overlay_name[i] shall be less than or equal to 256 bytes.

overlay_content_layer_id[i] indicates the nuh_layer_id value of the NAL units of the overlay content of the i-th overlay. AuxId[overlay_content_layer_id[i]] shall be equal to overlay_content_aux_id_minus128 + 128 for all values of i in the range of 0 to num_overlays_minus1, inclusive.

The value of the variable pLid, which identifies the nuh_layer_id value of the primary picture which the i-th overlay is associated with, is derived as follows:

```
pLid = −1
for( j = 0; j < 63; j++ )
    if( ViewOrderIdx[ j ]  = =  ViewOrderIdx[ overlay_content_layer_id[ i ] ]  &&
        ScalabilityId[ j ][ 2 ]  = =  ScalabilityId[ overlay_content_layer_id[ i ] ][ 2 ]  &&
        AuxId[ j ]  = =  0 )
      pLid = j [Ed. (YK): The style of the pseudo code should be aligned with other pseudo codes.]
```

The value of pLid shall be in the range of 0 to 62, inclusive.

overlay_label_present_flag[i] equal to 1 specifies that overlay_label_layer_id[i] is present. overlay_label_present_flag[i] equal to 0 specifies that overlay_label_layer_id[i] is not present.

overlay_label_layer_id[i] indicates the nuh_layer_id value of NAL units in the overlay label of the i-th overlay. AuxId[overlay_label_layer_id[i]] shall be equal to overlay_label_aux_id_minus128 + 128 for all values of i in the range of 0 to num_overlays_minus1, inclusive.

overlay_alpha_layer_id[i] indicates the nuh_layer_id value of NAL units in the overlay alpha of the i-th overlay. AuxId[overlay_alpha_layer_id[i]] shall be equal to overlay_alpha_aux_id_minus128 + 128 for all values of i in the range of 0 to num_overlays_minus1, inclusive.

overlay_alpha_present_flag[i] equal to 1 specifies that overlay_alpha_layer_id[i] is present. overlay_alpha_present_flag[i] equal to 0 specifies that overlay_alpha_layer_id[i] is not present.

num_overlay_elements_minus1[i] indicates the number of overlay elements in the i-th overlay. When not present, the value of num_over_elements_minus1[i] is inferred to be equal to 0.

overlay_element_name[i][j] indicates the name of the j-th overlay element of the i-th overlay. The length of the syntax element overlay_element_name[i][j] shall be less than or equal to 256 bytes.

overlay_element_label_min[i][j] and **overlay_element_label_max**[i][j] indicate the minimum and maximum values, respectively, of the range of sample values corresponding to the j-th overlay element of the i-th overlay. The length of the overlay_element_label_min[i][j] and overlay_element_label_max[i][j] is $BitDepth_Y$ bits.

The variable overlayElementId[i][x][y], the overlay element identifier of the (x, y) sample position of the i-th overlay, is derived as follows, where $sample_{Label}$[x][y] refers to the (x, y) sample position of the decoded label auxiliary picture of the i-th overlay:

```
for( y = 0; y < pic_height_in_luma_samples; y++ )
    for( x = 0; x < pic_width_in_luma_samples; x++ )
        for( i = 0; i <= number_overlays_minus1[ i ] ) {
            overlayElementId[ i ][ x ][ y ] = 0
            for( j = 0; j <= num_overlay_elements_minus1[ i ]; j++ )
                if( sample_Label[ x ][ y ] >= overlay_element_label_min[ i ][ j ] &&
                        sample_Label[ x ][ y ] <= overlay_element_label_max[ i ][ j ] )
                    overlayElementId [ i ][ x ][ y ] = j
        }
```

overlay_info_persistence_flag specifies the persistence of the overlay information SEI message. overlay_info_persistence_flag equal to 0 specifies that the overlay information SEI message applies to the current decoded picture only.

Let picA be the current picture. overlay_info_persistence_flag equal to 1 specifies that the overlay information SEI message persists in output order until one or more of the following conditions are true:

– A new CVS begins.

– The bitstream ends.

– A picture picB in an access unit containing an overlay information SEI message is output for which PicOrderCnt(picB) is greater than PicOrderCnt(picA), where PicOrderCnt(picB) and PicOrderCnt(picA) are the PicOrderCntVal values of picB and picA, respectively, immediately after the invocation of the decoding process for picture order count for picB.

F.14.2.9 Temporal motion vector prediction constraints SEI message semantics

The temporal motion vector prediction constraints SEI message indicates constraints on collocated pictures for temporal motion vector prediction. The SEI message may be used to determine whether the motion vectors of earlier pictures in decoding order no longer need to be stored and whether the motion vectors of the current picture and subsequent pictures need to be stored.

When the SEI message is not included in a scalable nesting SEI message, it applies to pictures with nuh_layer_id equal to that of the SEI NAL unit containing the SEI message. When the SEI message is included in a scalable nesting SEI message, it applies to the pictures with nuh_layer_id equal to all values of nestingLayerIdList[i] derived through the semantics of the containing scalable nesting SEI message. Let associatedLayerIdList be the list of nuh_layer_id values to which the temporal motion vector prediction constraints SEI message applies. [Ed. (AR): Check paragraph after integration of Q0183.][Ed. (YK): These should be included in the generic SEI message semantics – should be done during/after integration of Q0183.]

The temporal motion vector prediction constraints SEI message is a prefix SEI message. The temporal motion vector prediction constraints SEI message may be present in an access unit with TemporalId equal to 0 and shall not be present in an access unit with TemporalId greater than 0. [Ed. (AR): Check if sentence to be re-written based on SEI NAL unit and TemporalId of the AU. (MH): I changed references to a picture with references to an access unit, but I did not really understand the first part of AR's comment on writing the sentence based on SEI NAL unit.]

For the semantics below, currLayerId is a single nuh_layer_id value in associatedLayerIdList, and the semantics apply separately for each nuh_layer_id value in associatedLayerIdList. [Ed. (AR): Check paragraph after integration of Q0183.]

Let a set of pictures associatedPicSet be the pictures with nuh_layer_id equal to currLayerId from the access unit containing the SEI message, inclusive, up to but not including the first of any of the following in decoding order:

– The next access unit, in decoding order, that contains a temporal motion vector prediction constraints SEI message with an associatedLayerIdList that contains currLayerId.

– The next IDR or BLA picture, in decoding order, with nuh_layer_id equal to currLayerId.

– The next IRAP access unit, in decoding order, with NoClrasOutputFlag equal to 1.

prev_pics_not_used_flag equal to 1 indicates that the syntax elements for all coded pictures that follow the access unit containing the current picture in decoding order are constrained such that no temporal motion vector from any picture that has nuh_layer_id equal to any value in associatedLayerIdList and precedes the access unit containing the current picture in decoding order is used in decoding of any coded picture that follows the access unit containing the current picture in decoding order. prev_pics_not_used_flag equal to 0 indicates that the bitstream may or may not fulfill the constraints indicated by prev_pics_not_used_flag equal to 1.

NOTE 1 – When prev_pics_not_used_flag is equal to 1, decoders may empty the "motion vector storage" for all reference pictures with nuh_layer_id equal to currLayerId in the decoded picture buffer.

prev_pics_not_used_flag shall be equal to 1 when all of the following conditions are true:

– no_intra_layer_col_pic_flag is equal to 1 in the previous temporal motion vector prediction constraints SEI message applying to nuh_layer_id equal to currLayerId.

– There is no IDR or BLA picture with nuh_layer_id equal to currLayerId following, in decoding order, the previous temporal motion vector prediction constraints SEI message applying to nuh_layer_id equal to curLayerId, and preceding, in decoding order, the current temporal motion vector prediction constraints SEI message.

– There is no IRAP access unit that contains an IRAP picture with nuh_layer_id equal to 0 and NoClrasOutputFlag equal to 1 following, in decoding order, the previous temporal motion vector prediction constraints SEI message applying to nuh_layer_id equal to currLayerId, and preceding, in decoding order, the current temporal motion vector prediction constraints SEI message.

no_intra_layer_col_pic_flag equal to 1 indicates the following:

– If NumDirectRefLayers[currLayerId] is equal to 0, slice_temporal_mvp_enabled_flag is not present or is equal to 0 in each picture in associatedPicSet.

– Otherwise, all the pictures in associatedPicSet do not use temporal motion vector prediction or use collocated pictures with nuh_layer_id different from currLayerId.

When no_intra_layer_col_pic_flag is equal to 0, no constraint for the collocated picture of the pictures in associatedPicSet is indicated.

Let NoIntraLayerColPicFlag[currLayerId] be equal to no_intra_layer_col_pic_flag.

NOTE 2 – The motion vectors of the current picture with nuh_layer_id equal to layerId have to be stored when they may be used for temporal motion vector prediction of other pictures in the same layer or when they may be used for inter-layer motion prediction. In other words, the motion vectors of the current picture have to be stored when at least one of the following is true:

- sps_temporal_mvp_enabled_flag in the active SPS for the current picture is equal to 1 and NoIntraLayerColPicFlag[layerId] is equal 0.
- NoIntraLayerColPicFlag[layerId] is equal to 1 and there is a nuh_layer_id value nuhLayerIdA such that VpsInterLayerMotionPredictionEnabled[LayerIdxInVps[nuhLayerIdA]][LayerIdxInVps[layerId]] is equal to 1.

NOTE 3 – The motion vectors of a picture with nuh_layer_id equal to layerId need no longer be stored when the picture is marked as "unused for reference", or the picture is not used for temporal motion vector prediction of other pictures in the same layer and all pictures in the same access unit that may use the picture as a reference for inter-layer motion prediction have been decoded, or the access unit containing the picture precedes the current access unit in decoding order, where this SEI message is present with associatedLayerIdList including the nuh_layer_id of the picture and prev_pics_not_used_flag equal to 1. In other words, the motion vectors of a picture need no longer be stored when at least one of the following is true: [Ed. (AR): This note repeats the conditions. Is it not sufficient to say it once?]

- The picture is marked as "unused for reference".
- NoIntraLayerColPicFlag[layerId] is equal to 1 for the picture and the access unit containing the picture has been decoded.
- The access unit containing the picture precedes the current access unit, in decoding order, and the current access unit contains this SEI message with associatedLayerIdList including the nuh_layer_id value of the picture and with prev_pics_not_used_flag equal to 1.

F.14.2.10 Frame-field information SEI message semantics

The frame-field information SEI message may be used to indicate how the associated picture should be displayed, the source scan type of the associated picture, and whether the associated picture is a duplicate of a previous picture, in output order, of the same layer.

When a non-nested frame-field information SEI message is included in an SEI NAL unit with nuh_layer_id assocLayerId, it is associated to the picture within nuh_layer_id equal to assocLayerId within the same access unit as the SEI NAL unit. When a frame-field information SEI message is included in a scalable nesting SEI message, it is associated to each picture with nuh_layer_id assocLayerId equal to nestingLayerIdList[i] for all values of i in the range of 0 to nesting_num_layers_minus1, inclusive. [Ed. (YK): These should be included in the generic SEI message semantics – should be done during/after integration of Q0183.]

When a picture with nuh_layer_id equal to assocLayerId is present in an access unit, frame_field_info_present_flag is equal to 1 in the active SPS for the layer with nuh_layer_id assocLayerId, and a non-nested picture timing SEI message is not present in an SEI NAL unit with nuh_layer_id equal to assocLayerId, a frame-field information SEI message associated with nuh_layer_id equal to assocLayerId shall be present in the access unit.

The semantics of ffinfo_pic_struct, ffinfo_source_scan_type and ffinfo_duplicate_flag apply layer-wise to each value of assocLayerId.

ffinfo_pic_struct has the same semantics as the pic_struct syntax element in the picture timing SEI message.

ffinfo_source_scan_type has the same semantics as the source_scan_type syntax element in the picture timing SEI message.

ffinfo_duplicate_flag has the same semantics as the duplicate_flag syntax element in the picture timing SEI message.

F.14.2.11 OLS nesting SEI message semantics

The OLS nesting SEI message provides a mechanism to associate SEI messages with one or more additional layer sets or one or more OLSs.

An OLS nesting SEI message contains one or more SEI messages.

ols_flag equal to 0 specifies that the nested SEI messages are associated with additional layer sets identified through ols_idx[i]. ols_flag equal to 1 specifies that the nested SEI messages are associated with OLSs identified through ols_idx[i]. When num_add_layer_sets is equal to 0, ols_flag shall be equal to 1.

num_ols_indices_minus1 plus 1 specifies the number of indices of additional layer sets or OLSs the nested SEI messages are associated with. num_ols_indices_minus1 shall be in the range of 0 to 2047, inclusive.

ols_idx[i] specifies an index of the additional layer set or the OLS specified in the active VPS to which the nested SEI messages are associated with. If ols_flag is equal to 0, ols_idx[i] shall be in the range of vps_num_layer_sets_minus1 + 1 to vps_num_layer_sets_minus1 + num_add_layer_sets, inclusive. Otherwise (ols_flag is equal to 1), ols_idx[i] shall be in the range of 0 to NumOutputLayerSets – 1, inclusive.

ols_nesting_zero_bit shall be equal to 0.

F.14.2.12 VPS rewriting SEI message semantics

The VPS rewriting SEI message contains a nal_unit( ) syntax structure in which nal_unit_type shall be equal to VPS_NUT. The VPS rewriting SEI message contains a VPS NAL unit that is added to the output bitstream of the non-base layer subtree extraction process as specified in subclause F.10.2.

When an OLS has an index olsIdx in the range of FirstAddLayerSetIdx to LastAddLayerSetIdx, inclusive, and the OLS includes more than one layer, a VPS rewriting SEI message shall be present within an OLS nesting SEI message with ols_idx[i] equal to olsIdx.

The VPS rewriting SEI message, when present, shall be included in an OLS nesting SEI message in which ols_flag shall be equal to 0 and ols_idx[i] shall be in the range of FirstAddLayerSetIdx to LastAddLayerSetIdx, inclusive, for each value of i in the range of 0 to num_ols_indices_minus1, inclusive.

F.15 Video usability information

F.15.1 General

The specifications in clause E.1 apply.

F.15.2 VUI syntax

The specifications in clause E.2 apply.

F.15.3 VUI semantics

F.15.3.1 VUI parameters semantics

The specifications in clause E.3.1 apply with the following modifications and additions.

field_seq_flag equal to 1 indicates that the layers for which the SPS is an active SPS within the CVS convey pictures that represent fields, and specifies that a picture timing SEI message or a frame-field information SEI message shall be present for those layers in every access unit of the current CVS. [Ed. (MH): The previous sentence could more explicitly refer to nested and/or non-nested picture timing SEI message, and any requirements of the syntax elements of the scalable nesting SEI message.] field_seq_flag equal to 0 indicates that the layers for which the SPS is an active SPS

within the CVS convey pictures that represent frames and that a picture timing SEI message or a frame-field information SEI message may or may not be present for the layers for which the SPS is an active SPS in any access unit of the current CVS. When field_seq_flag is not present, it is inferred to be equal to 0. When general_frame_only_constraint_flag is present in the SPS and is equal to 1, the value of field_seq_flag shall be equal to 0. When general_frame_only_constraint_flag is present in the active VPS, applies for a layer for which the SPS is an active SPS, and is equal to 1, the value of field_seq_flag shall be equal to 0.

NOTE 4 – The specified decoding process does not treat access units conveying pictures that represent fields or frames differently. A sequence of pictures that represent fields would therefore be coded with the picture dimensions of an individual field. For example, access units containing pictures that represent 1080i fields would commonly have cropped output dimensions of 1920x540, while the sequence picture rate would commonly express the rate of the source fields (typically between 50 and 60 Hz), instead of the source frame rate (typically between 25 and 30 Hz).

frame_field_info_present_flag equal to 1 specifies that picture timing SEI messages or frame-field information SEI messages are present for every picture for which this SPS is the active SPS and the picture timing SEI messages, when present, include the pic_struct, source_scan_type, and duplicate_flag syntax elements. frame_field_info_present_flag equal to 0 specifies that the pic_struct syntax element is not present in picture timing SEI messages associated with pictures for which the SPS is the active SPS.

When frame_field_info_present_flag is present and either or both of the following conditions are true, frame_field_info_present_flag shall be equal to 1:

– field_seq_flag is equal to 1.

– general_progressive_source_flag and general_interlaced_source_flag are present in this SPS, general_progressive_source_flag is equal to 1, and general_interlaced_source_flag is equal to 1.

When frame_field_info_present_flag is not present, its value is inferred as follows:

– If general_progressive_source_flag and general_interlaced_source_flag are present in this SPS, general_progressive_source_flag is equal to 1, and general_interlaced_source_flag is equal to 1, frame_field_info_present_flag is inferred to be equal to 1.

– Otherwise, frame_field_info_present_flag is inferred to be equal to 0.

vui_timing_info_present_flag equal to 1 specifies that vui_num_units_in_tick, vui_time_scale, vui_poc_proportional_to_timing_flag, and vui_hrd_parameters_present_flag are present in the vui_parameters( ) syntax structure. vui_timing_info_present_flag equal to 0 specifies that vui_num_units_in_tick, vui_time_scale, vui_poc_proportional_to_timing_flag, and vui_hrd_parameters_present_flag are not present in the vui_parameters( ) syntax structure. It is a requirement of bitstream conformance that, when nuh_layer_id is greater than 0, vui_timing_info_present_flag shall be equal to 0.

F.15.3.2 HRD parameters semantics

The specifications in clause E.3.2 apply.

F.15.3.3 Sub-layer HRD parameters semantics

The specifications in clause E.3.3 apply.

Annex G

Multiview high efficiency video coding

(This annex forms an integral part of this Recommendation | International Standard)

This annex specifies syntax, semantics and decoding processes for multiview high efficiency video coding that use the syntax, semantics, and decoding processes specified in clauses 2-9 and Annexes A-F.

G.1 Scope

Decoding processes and bitstreams conforming to this annex are completely specified in this annex with reference made to clauses 2-9 and Annexes A-F.

G.2 Normative references

The specifications in clause 2 apply.

G.3 Definitions

The specifications in clause F.3 apply.

G.4 Abbreviations

The specifications in clause 4 apply.

G.5 Conventions

The specifications in clause 5 apply.

G.6 Source, coded, decoded and output data formats, scanning processes, and neighbouring relationships

The specifications in clause 6 apply.

G.7 Syntax and semantics

The specifications in clause F.7 apply.

G.8 Decoding processes

G.8.1 General decoding process

The specifications in subclause F.8.1 applies.

G.8.1.1 Decoding process for a coded picture with nuh_layer_id greater than 0

The decoding process operates as follows for the current picture CurrPic:

1. The decoding of NAL units is specified in subclause G.8.2.
2. The processes in subclause G.8.1.2 and G.8.3.4 specify the following decoding processes using syntax elements in the slice segment layer and above:
   - Prior to decoding the first slice of the current picture, subclause G.8.1.2 is invoked.
   - At the beginning of the decoding process for each P or B slice, the decoding process for reference picture lists construction specified in subclause G.8.3.4 is invoked for derivation of reference picture list 0 (RefPicList0), and when decoding a B slice, reference picture list 1 (RefPicList1).
3. The processes in subclauses F.8.5, G.8.5, G.8.6, and G.8.7 specify decoding processes using syntax elements in all syntax structure layers. It is a requirement of bitstream conformance that the coded slices of the picture shall contain slice segment data for every coding tree unit of the picture, such that the division of the picture into

slices, the division of the slices into slice segments, and the division of the slice segments into coding tree units each form a partitioning of the picture.

4. After all slices of the current picture have been decoded, the marking process for ending the decoding of a coded picture with nuh_layer_id greater than 0 specified in subclause G.8.1.3 is invoked.

G.8.1.2 Decoding process for inter-layer reference picture set

Outputs of this process are updated lists of inter-layer pictures RefPicSetInterLayer0 and RefPicSetInterLayer1 and the variables NumActiveRefLayerPics0 and NumActiveRefLayerPics1.

The lists RefPicSetInterLayer0 and RefPicSetInterLayer1 are first emptied, NumActiveRefLayerPics0 and NumActiveRefLayerPics1 are set equal to 0 and the following applies:

```
for( i = 0; i < NumActiveRefLayerPics; i++ ) {
    refPicSet0Flag = ( ViewId[ nuh_layer_id ] <= ViewId[ 0 ] &&
                                    ViewId[ nuh_layer_id ] <= ViewId[ RefPicLayerId[ i ] ] ) ||
                     ( ViewId[ nuh_layer_id ] >= ViewId[ 0 ] &&
                                    ViewId[ nuh_layer_id ] >= ViewId[ RefPicLayerId[ i ] ] ) )
    if( there is a picture picX in the DPB that is in the same access unit as the current picture and has
                                                nuh_layer_id equal to RefPicLayerId[ i ] ) {
        if( refPicSet0Flag ) {
            RefPicSetInterLayer0[ NumActiveRefLayerPics0 ] = picX
            RefPicSetInterLayer0[ NumActiveRefLayerPics0++ ] is marked as "used for long-term reference"
        } else {
            RefPicSetInterLayer1[ NumActiveRefLayerPics1 ] = picX
            RefPicSetInterLayer1[ NumActiveRefLayerPics1++ ] is marked as "used for long-term reference"
        }
    } else {
        if( refPicSet0Flag )
            RefPicSetInterLayer0[ NumActiveRefLayerPics0++ ] = "no reference picture"
        else
            RefPicSetInterLayer1[ NumActiveRefLayerPics1++ ] = "no reference picture"
    }
}
```

There shall be no entry equal to "no reference picture" in RefPicSetInterLayer0 or RefPicSetInterLayer1.

There shall be no picture that has discardable_flag equal to 1 in RefPicSetInterLayer0 or RefPicSetInterLayer1.

If the current picture is a RADL picture, there shall be no entry in RefPicSetInterLayer0 or RefPicSetInterLayer1 that is a RASL picture.

NOTE – An access unit may contain both RASL and RADL pictures.

G.8.1.3 Marking process for ending the decoding of a coded picture with nuh_layer_id greater than 0

Output of this process is:

– a potentially updated marking as "used for short-term reference" for some decoded pictures.

The following applies:

```
for( i = 0; i < NumActiveRefLayerPics0; i++ )
    RefPicSetInterLayer0[ i ] is marked as "used for short-term reference"

for( i = 0; i < NumActiveRefLayerPics1; i++ )
    RefPicSetInterLayer1[ i ] is marked as "used for short-term reference"
```

G.8.2 NAL unit decoding process

The specifications in subclause 8.2 apply.

G.8.3 Slice decoding processes

G.8.3.1 Decoding process for picture order count

The specifications in subclause F.8.3.1 apply.

G.8.3.2 Decoding process for reference picture set

The specifications in subclause F.8.3.2 apply.

G.8.3.3 Decoding process for generating unavailable reference pictures

The specifications in subclause F.8.3.3 apply.

G.8.3.4 Decoding process for reference picture lists construction

The specifications in subclause F.8.3.4 apply.

G.8.4 Decoding process for coding units coded in intra prediction mode

The specifications in subclause F.8.4 apply.

G.8.5 Decoding process for coding units coded in inter prediction mode

The specifications in subclause F.8.5 apply.

G.8.6 Scaling, transformation and array construction process prior to deblocking filter process

The specifications in subclause F.8.6 apply.

G.8.7 In-loop filter process

The specifications in subclause F.8.7 apply.

G.9 Parsing process

The specifications in subclause F.9 apply.

G.10 Specification of bitstream subsets

The specifications in subclause F.10 apply.

G.11 Profiles, tiers, and levels

G.11.1 Profiles

G.11.1.1 General

TBD. [Ed. (JO): These definitions should better be moved to annex A, with reference that the specifications of annexes F and G apply for the case of stereo main. Can be done in course of the new edition.]

G.11.1.2 Stereo Main profile

Bitstreams conforming to the Stereo Main profile shall obey the following constraints:

– VPSs shall have vps_base_layer_internal_flag equal to 1 only.

– VPSs shall have vps_num_rep_formats_minus1 in the range of 0 to 15, inclusive.

Bitstreams containing OLSs conforming to the Stereo Main profile shall obey the following constraints on the derived sub-bitstream for each of the OLSs, with OLS index olsIdx and layerSetIdx being the layer set for the OLS, and the sub-bitstream being derived by invoking the sub-bitstream extraction process as specified in subclause F.10 with the following inputs: the bitstream, tIdTarget equal to 6, and layerIdListTarget containing the nuh_layer_id values of the layers that are included in the layer set with the index layerSetIdx and are primary picture layers.

Bitstreams containing OLSs conforming to the Stereo Main profile shall also obey the following constraints on the base layer bitstream derived by invoking the sub-bitstream extraction process as specified in subclause F.10 with the bitstream, tIdTarget equal to 6, and with layerIdListTarget containing only one nuh_layer_id value that is equal to 0 as inputs.

The base layer bitstream derived from bitstreams conforming to the Stereo Main profile shall obey the following constraints:

– The base layer bitstream shall obey all constraints of the Main profile specified in subclause A.3.2.

– SPSs of the base layer bitstream shall have general_profile_idc equal to 1 or general_profile_compatibility_flag[1] equal to 1.

The derived sub-bitstream for an OLS conforming to the Stereo Main profile shall obey the following constraints: [Ed. (YK): Check whether all the SPS syntax elements referred to be below exist or have been derived, and if not, either derive them or use the corresponding VPS syntax elements instead.]

– All active SPSs for the sub-bitstream shall have chroma_format_idc equal to 1 only.

– CtbLog2SizeY derived from any active SPS of the sub-bitstream shall be in the range of 4 to 6, inclusive.

– ScalabilityId[j][smIdx] shall be equal to 0 for any smIdx value not equal to 1 and for any value of j for the sub-bitstream.

– The number of the layers in the sub-bitstream shall be equal to 2.

– output_layer_flag[olsIdx][j] shall be equal to 1 for all values of j in the range of 0 to 1.

NOTE – This restriction implies that alt_output_layer_flag[olsIdx] is equal to 0.

– When ViewScalExtLayerFlag[i] is equal to 1 for the layer with nuh_layer_id equal to i in the sub-bitstream, inter_view_mv_vert_constraint_flag shall be equal to 1 in the sps_multilayer_extension( ) syntax structure in each active SPS RBSP for that layer.

– When ViewScalExtLayerFlag[i] is equal to 1 for the layer with nuh_layer_id equal to i in the sub-bitstream, num_scaled_ref_layer_offsets shall be equal to 0 in each active SPS for that layer.

– When ViewScalExtLayerFlag[i] is equal to 1 for the layer with nuh_layer_id equal to i in the sub-bitstream, the values of pic_width_in_luma_samples and pic_height_in_luma_samples in each active SPS for that layer shall be equal to the values of pic_width_in_luma_samples and pic_height_in_luma_samples, respectively, in each active SPS for all direct reference layers of that layer.

– All active SPSs for the sub-bitstream shall have sps_range_extensions_flag equal to 0 only and sps_extension_6bits equal to 0 only.

– All active PPSs for the sub-bitstream shall have pps_range_extensions_flag equal to 0 only and pps_extension_6bits equal to 0 only.

– All active SPSs for the sub-bitstream shall have bit_depth_luma_minus8 equal to 0 only.

– All active SPSs for the sub-bitstream shall have bit_depth_chroma_minus8 equal to 0 only.

– When AuxId[i] and AuxId[j] are both equal to 0 and i is not equal to j, ViewOrderIndex[i] shall not be equal to ViewOrderIndex[j]. [Ed. (YK): There is a weird symbol at the beginning of this sentence and I don't know how to get rid of it.]

[Ed. (JB): profile_idc value for stereo main profile missing,]

G.11.2 Tiers and levels

G.11.2.1 General tier and level limits

The specifications in A.4.1 apply with the following modifications.

[Ed: PicSizeInSamplesY corresponds to the spatial resolution of a picture; it is assumed that the picture size in each view is the same.]

[Ed: The current design assumes only two views are present.]

Replace item d) by the following:

d) The value of sps_max_dec_pic_buffering_minus1[HighestTid] + 1 shall be less than or equal to MaxDpbSize, which is derived as follows:

```
if( PicSizeInSamplesY <= ( MaxLumaPs >> 2 ) )
    MaxDpbSize = Min( 4 * maxDpbPicBuf, 16 )
else if( PicSizeInSamplesY <= ( MaxLumaPs >> 1 ) )
    MaxDpbSize = Min( 2 * maxDpbPicBuf, 16 )                    (G-5)
else if( PicSizeInSamplesY <= ( ( 3 * MaxLumaPs ) >> 2 ) )
    MaxDpbSize = Min( ( 4 * maxDpbPicBuf ) / 3, 16 )
else
    MaxDpbSize = maxDpbPicBuf
```

where MaxLumaPs is specified in Table A-1 and maxDpbPicBuf is equal to 6.

[Ed: The above needs to be considered depending on the outcome of the DPB spec. If DPB is specified per layer, then no change is needed, it just needs to be clarified that these constraints apply per layer. But if the DPB is for all views, then certain parameters (e.g., MaxLumaPs and maxDpbBuf) should be doubled.]

G.11.2.2 Profile-specific level limits for the Main, Main 10, Monochrome 8, and Stereo Main profiles

[Ed (CY/JB): Currently the same level value may be intended to be used for a given resolution for both Stereo Main profile and Main profile, even though the stereo bitstream requires twice of the decoding capability as the single-view bitstream. Further study is needed to consider if this is an appropriate intention, and how to express the intention with appropriate constraints.]

The specifications in A.4.1 apply with the following modifications.

Replace item b) by the following:

b) The difference between consecutive output times of pictures of the same layer from the DPB, as specified in subclause C.3.3, shall satisfy the constraint that DpbOutputInterval[n] is greater than or equal to Max(PicSizeInSamplesY ÷ MaxLumaSr, fR) for the value of PicSizeInSamplesY of picture n, where MaxLumaSr is the value specified in Table A-2 for picture n, provided that picture n is a picture that is output and is not the last picture of the bitstream that is output.

G.12 Byte stream format

The specifications in subclause F.12 apply.

G.13 Hypothetical reference decoder

The specifications in subclause F.13 and its subclauses apply.

G.14 SEI messages

The specifications in Annex D and subclause F.14 together with the extensions and modifications specified in this subclause apply.

G.14.1 SEI message syntax

G.14.1.1 3D reference displays information SEI message syntax

three_dimensional_reference_displays_info(payloadSize) {	**Descriptor**
prec_ref_display_width	ue(v)
ref_viewing_distance_flag	u(1)
if(ref_viewing_distance_flag)	
prec_ref_viewing_dist	ue(v)
num_ref_displays_minus1	ue(v)
for(i = 0; i <= num_ref_displays_minus1; i++) {	
left_view_id[i]	ue(v)
right_view_id[i]	ue(v)
exponent_ref_display_width[i]	u(6)
mantissa_ref_display_width[i]	u(v)
if(ref_viewing_distance_flag) {	
exponent_ref_viewing_distance[i]	u(6)
mantissa_ref_viewing_distance[i]	u(v)
}	
additional_shift_present_flag[i]	u(1)
if(additional_shift_present_flag[i])	
num_sample_shift_plus512[i]	u(10)
}	
three_dimensional_reference_displays_extension_flag	u(1)
}	

G.14.1.2 Depth representation information SEI message syntax

depth_representation_info_sei(payloadSize) {	**Descriptor**
z_near_flag	u(1)
z_far_flag	u(1)
d_min_flag	u(1)
d_max_flag	u(1)
depth_representation_type	ue(v)
if(d_min_flag || d_max_flag)	
disparity_ref_view_id	ue(v)
if(z_near_flag)	
depth_rep_sei_element(ZNearSign, ZNearExp, ZNearMantissa, ZNearManLen)	
if(z_far_flag)	
depth_rep_sei_element(ZFarSign, ZFarExp, ZFarMantissa, ZFarManLen)	
if(d_min_flag)	
depth_rep_sei_element(DMinSign, DMinExp, DMinMantissa, DMinManLen)	
if(d_max_flag)	
depth_rep_sei_element(DMaxSign, DMaxExp, DMaxMantissa, DMaxManLen)	
if(depth_representation_type == 3) {	
depth_nonlinear_representation_num_minus1	ue(v)
for(i = 1; i <= depth_nonlinear_representation_num_minus1 + 1; i++)	
depth_nonlinear_representation_model[i]	

}	
}	

G.14.1.2.1 Depth representation SEI element syntax

depth_rep_sei_element(OutSign, OutExp, OutMantissa, OutManLen) {	**Descriptor**
da_sign_flag	u(1)
da_exponent	u(7)
da_mantissa_len_minus1	u(5)
da_mantissa	u(v)
}	

G.14.1.2.2 Multiview scene information SEI message syntax

multiview_scene_info(payloadSize) {	**Descriptor**
max_disparity	ue(v)
}	

G.14.1.2.3 Multiview acquisition information SEI message syntax

multiview_scene_info(payloadSize) {	**Descriptor**
num_views_minus1	ue(v)
intrinsic_param_flag	u(1)
extrinsic_param_flag	u(1)
if(instrinsic_param_flag) {	
intrinsic_params_equal_flag	u(1)
prec_focal_length	ue(v)
prec_principal_point	ue(v)
prec_skew_factor	ue(v)
for(i = 0; i <= intrinsic_params_equal_flag ? 0 : num_views_minus1; i++) {	
sign_focal_length_x[i]	u(1)
exponent_focal_length_x[i]	u(6)
mantissa_focal_length_x[i]	u(v)
sign_focal_length_y[i]	u(1)
exponent_focal_length_y[i]	u(6)
mantissa_focal_length_y[i]	u(v)
sign_principal_point_x[i]	u(1)
exponent_principal_point_x[i]	u(6)
mantissa_principal_point_x[i]	u(v)
sign_principal_point_y[i]	u(1)
exponent_principal_point_y[i]	u(6)
mantissa_principal_point_y[i]	u(v)
sign_skew_factor[i]	u(1)
exponent_skew_factor[i]	u(6)
mantissa_skew_factor[i]	u(v)
}	

}	
if(extrinsic_param_flag) {	
prec_rotation_param	ue(v)
prec_translation_param	ue(v)
for(i = 0; i <= num_views_minus1; i++)	
for(j = 1; j <= 3; j++) { /* row */	
for(k = 1; k <= 3; k++) { /* column */	
sign_r[i][j][k]	u(1)
exponent_r[i][j][k]	u(6)
mantissa_r[i][j][k]	u(v)
}	
sign_t[i][j]	u(1)
exponent_t[i][j]	u(6)
mantissa_t[i][j]	u(v)
}	
}	
}	

G.14.1.2.4 Multiview view position SEI message syntax

multiview_view_position(payloadSize) {	**Descriptor**
num_views_minus1	ue(v)
for(i = 0; i <= num_views_minus1; i++)	
view_position[i]	ue(v)
multiview_view_position_extension_flag	u(1)
}	

G.14.2 SEI message semantics

Table G-1 – Persistence scope of SEI messages (informative)

SEI message	Persistence scope
3D reference displays information	The access unit containing the SEI message and up to but not including the next access unit, in both decoding and displaying order, that contains the SEI message
Depth representation information	Specified by the semantics of the SEI message.
Multiview scene information	The CVS containing the SEI message
Multiview acquisition information	The CVS containing the SEI message
Multiview view position SEI message	The CVS containing the SEI message

G.14.2.1 3D reference displays information SEI message semantics

A 3D reference displays information SEI message contains information about the reference display width(s) and reference viewing distance(s) as well as information about the corresponding reference stereo pair(s), i.e. the pair(s) of views to be displayed for the viewer's left and right eyes on the reference display at the reference viewing distance. This information enables a view renderer to generate a proper stereo pair for the target screen width and the viewing distance. The reference display width and viewing distance values are signalled in units of centimetres. The reference pair of view specified in this SEI message can be used to extract or infer parameters related to the distance between the camera centers in the reference stereo pair, which can be used for generation of views for the target display. For multi-view displays, the reference stereo pair corresponds to a pair of views that can be simultaneously observed by the viewer's left

and right eyes.

When present, this SEI message shall be associated an IRAP access unit or with a non-IRAP access unit, when all access units that follow this access unit in the decoding order, also follow it in the display order. The 3D reference display information SEI message should be applied for the access unit, it is associated with and the access units which follow this access unit in both the output and decoding order until the next IRAP access unit or the next access unit containing a 3D reference displays information SEI message.

NOTE 1 – The 3D reference displays information SEI message specifies display parameters for which the 3D sequence was optimized and the corresponding reference parameters. Each reference display (i.e. a reference display width and possibly a corresponding viewing distance) is associated with one reference pair of views by signalling their ViewId. The difference between the values of ViewId is referred to as the baseline distance (i.e. the distance between the centers of the cameras used to obtain the video sequence).

The following equations can be used for determining the baseline distance and horizontal shift for the receiver's display when the ratio between the receiver's viewing distance and the reference viewing distance is the same as the ratio between the receiver screen width and the reference screen width:

baseline[i] = refBaseline[i] * (refDisplayWidth[i] ÷ displayWidth)

shift[i] = refShift[i] * (refDisplayWidth[i] ÷ displayWidth)

where refBaseline[i] is equal to right_view_id[i] − left_view_id[i] signalled in this SEI message. Other parameters related to the view generation may be obtained determined by using a similar equation.

parameter[i] = refParameter[i] * (refDisplayWidth[i] ÷ displayWidth)

where refParameter[i] is a parameter related to view generation that corresponds to the reference pair of views signalled by left_view_id[i] and right_view_id[i]. In the above equations, the width of the visible part of the display used for showing the video sequence should be understood under "display width". The same equations can also be used for determining the pair of views and horizontal shift and/or other view synthesis parameters when the viewing distance is not scaled proportionally to the screen width compared to the reference display parameters. In this case, the effect of applying the above equations would be to keep the perceived depth in the same proportion to the viewing distance as in the reference setup.

When the view synthesis related parameters that correspond to the reference stereo pair change from one access unit to another, they should be scaled with the same scaling factor as the parameters in the access unit that the SEI message is associated with. Therefore, the above equation should also be applied to obtain the parameters for a following access unit, where the refParameter is the parameter related to the reference stereo pair associated the following access unit.

The horizontal shift for the receiver's display should also be modified by scaling it with the same factor as that used to scale the baseline distance (or other view synthesis parameters).

prec_ref_display_width specifies the exponent of the maximum allowable truncation error for refDisplayWidth[i] as given by $2^{-\text{prec\_ref\_display\_width}}$. The value of prec_ref_display_width shall be in the range of 0 to 31, inclusive.

ref_viewing_distance_flag equal to 1 indicates the presence of reference viewing distance. ref_viewing_distance_flag equal to 0 indicates that the reference viewing distance is not present in the bitstream.

prec_ref_viewing_dist specifies the exponent of the maximum allowable truncation error for refViewingDist[i] as given by $2^{-\text{prec\_ref\_viewing\_dist}}$. The value of prec_ref_viewing_dist shall be in the range of 0 to 31, inclusive.

num_ref_displays_minus1 plus 1 specifies the number of reference displays that are signalled in the bitstream. The value of num_ref_displays_minus1 shall be in the range of 0 to 31, inclusive.

left_view_id[i] indicates the ViewId of the left view of a stereo pair corresponding to the i-th reference display.

right_view_id[i] indicates the ViewId of the right view of a stereo-pair corresponding to the i-th reference display.

exponent_ref_display_width[i] specifies the exponent part of the reference display width of the i-th reference display. The value of exponent_ref_display_width[i] shall be in the range of 0 to 62, inclusive. The value 63 is reserved for future use by ITU-T | ISO/IEC. Decoders shall treat the value 63 as indicating an unspecified reference display width.

mantissa_ref_display_width[i] specifies the mantissa part of the reference display width of the i-th reference display. The variable refDispWidthBits specifying the number of bits of the mantissa_ref_display_width[i] syntax element is derived as follows:

– If exponent_ref_display_width[i] is equal to 0, refDispWidthBits is set equal to Max(0, prec_ref_display_width − 30).

– Otherwise (0 < exponent_ref_display_width[i] < 63), refDispWidthBits is set equal to Max(0, exponent_ref_display_width[i] + prec_ref_display_width − 31).

exponent_ref_viewing_distance[i] specifies the exponent part of the reference viewing distance of the i-th reference display. The value of exponent_ref_viewing_distance[i] shall be in the range of 0 to 62, inclusive. The value 63 is reserved for future use by ITU-T | ISO/IEC. Decoders shall treat the value 63 as indicating an unspecified reference display width.

mantissa_ref_viewing_distance[i] specifies the mantissa part of the reference viewing distance of the i-th reference

display. The variable refViewDistBits specifying the number of bits of the mantissa_ref_viewing_distance[i] syntax element is derived as follows:

– If exponent_ref_viewing_distance[i] is equal to 0, the refViewDistBits is set equal to Max(0, prec_ref_viewing_distance − 30).

– Otherwise (0 < exponent_ref_viewing_distance[i] < 63), refViewDistBits is set equal to Max(0, exponent_ref_viewing_distance[i] + prec_ref_viewing_distance − 31).

The variables in the x row of Table G-2 are derived as follows from the respective variables or values in the e, n, and v rows of Table G-2 as follows:

– If e is not equal to 0, the following applies:

$$x = 2^{(e-31)} * (1 + n \div 2^{v}) \quad \text{(G-6)}$$

– Otherwise (e is equal to 0), the following applies:

$$x = 2^{-(30+v)} * n \quad \text{(G-7)}$$

NOTE 2 – The above specification is similar to that found in IEC 60559:1989, *Binary floating-point arithmetic for microprocessor systems*.

Table G-2 – Association between camera parameter variables and syntax elements

x	refDisplayWidth[i]	refViewingDistance[i **]**
e	exponent_ref_display_width[i]	exponent_ref_viewing_distance[i]
n	mantissa_ref_display_width[i]	mantissa_ref_viewing_distance[i]
v	refDispWidthBits	refViewDistBits

additional_shift_present_flag[i] equal to 1 indicates that the information about additional horizontal shift of the left and right views for the i-th reference display is present in the bitstream. additional_shift_present_flag[i] equal to 0 indicates that the information about additional horizontal shift of the left and right views for the i-th reference display is not present in the bitstream.

num_sample_shift_plus512[i] indicates the recommended additional horizontal shift for a stereo pair corresponding to the i-th reference baseline and the i-th reference display.

– If (num_sample_shift_plus512[i] − 512) is less than 0, it is recommended that the left view of the stereo pair corresponding to the i-th reference baseline and the i-th reference display is shifted in the left direction by (512 − num_sample_shift_plus512[i]) samples with respect to the right view of the stereo pair.

– Otherwise, if num_sample_shift_plus512[i] is equal to 512, it is recommended that shifting is not applied.

– Otherwise, ((num_sample_shift_plus512[i] − 512) is greater than 0), it is recommended that the left view in the stereo pair corresponding to the i-th reference baseline and the i-th reference display should be shifted in the right direction by (512 − num_sample_shift_plus512[i]) samples with respect to the right view of the stereo pair.

The value of num_sample_shift_plus512[i] shall be in the range of 0 to 1023, inclusive.

three_dimensional_reference_displays_extension_flag equal to 0 indicates that no additional data follows within the reference displays SEI message. The value of three_dimensional_reference_displays_extension_flag shall be equal to 0 in bitstreams conforming to this version of this Specification. The value of 1 for three_dimensional_reference_displays_extension_flag is reserved for future use by ITU-T | ISO/IEC. Decoders shall ignore all data that follows the value of 1 for three_dimensional_reference_displays_extension_flag in a reference displays SEI message.

NOTE 3 – Shifting the left view in the left (or right) direction by x samples with respect to the right view can be performed by the following two-step processing:

1) Shift the left view by x/2 samples in the left (or right) direction, and shift the right view by x/2 samples in the right (or left) direction.

2) Fill the left and right image margins of x/2 samples in width in both the left and right views in background colour.

The following pseudo code explains the recommended shifting processing in the case of shifting the left view in the left direction by x samples with respect to the right view.

```
for( i = x/2; i < width − x/2; i++ )
    for( j=0;  j < height; j++ ) {
        leftView[ j ][ i ] = leftView[ j ][ i + x/2 ]
        rightView[ j ][ width − 1 − i ] = rightView[ j ][ width − 1 − i − x/2 ]
       }
for( i = 0; i < x/2; i++)
    for( j = 0; j < height; j++ ) {
        leftView[ j ][ width − 1 − i ] = leftView[ j ][ i ] = backgroundColour
        rightView[ j ][ width − 1 − i ] = rightView[ j ][ i ] = backgroundColour
  }
```

The following pseudo code explains the recommended shifting processing in the case of shifting the left view in the right direction by x samples with respect to the right view.

```
for( i = x/2; i < width − x/2; i++ )
    for( j = 0; j < height; j++ ){
        leftView[ j ][ width − 1 − i ] = leftView[ j ][ width − 1 − i − x/2 ]
        rightView[ j ][ i ] = rightView[ j ][ i + x/2 ]
  }
for( i=0; i < x/2; i++ )
    for( j = 0; j < height; j++ ) {
        leftView[ j ][ width − 1 − i ] = leftView[ j ][ i ] = backgroundColour
        rightView[ j ][ width − 1 − i ] = rightView[ j ][ i ] = backgroundColour
  }
```

The variable backgroundColour may take different values in different systems, for example black or gray.

G.14.2.2 Depth representation information SEI message semantics

The syntax elements in the depth representation information SEI message specify various parameters for auxiliary pictures of type AUX_DEPTH for the purpose of processing decoded primary and auxiliary pictures prior to rendering on a 3D display, such as view synthesis. Specifically, depth or disparity ranges for depth pictures are specified.

When present, the depth representation information SEI message shall be associated with one or more layers with AuxId value equal to AUX_DEPTH. When the depth representation SEI message is not nested in the scalable nesting SEI message, it is associated with the layer having nuh_layer_id value equal to that of the SEI NAL unit containing the SEI message. When the depth representation SEI message is nested in the scalable nesting SEI message, it is associated with the layers having nuh_layer_id value equal to each value in the list nestingLayerIdList[i] for each value of i specified in the scalable nesting SEI message.

When present, the depth representation information SEI message may be included in any access unit. It is recommended that, when present, the SEI message is included in an IRAP access unit for the purpose of random access. The information indicated in the SEI message applies to all the pictures of each associated layer from the access unit containing the SEI message to the next access unit, in decoding order, containing an SEI message of the same type and associated with the same layer, exclusive, or to the end of the coded video sequence, whichever is earlier in decoding order.

z_near_flag equal to 0 specifies that the syntax elements specifying the nearest depth value are not present in the syntax structure. z_near_flag equal to 1 specifies that the syntax elements specifying the nearest depth value are present in the syntax structure.

z_far_flag equal to 0 specifies that the syntax elements specifying the farthest depth value are not present in the syntax structure. z_far_flag equal to 1 specifies that the syntax elements specifying the farthest depth value are present in the syntax structure.

d_min_flag equal to 0 specifies that the syntax elements specifying the minimum disparity value are not present in the syntax structure. d_min_flag equal to 1 specifies that the syntax elements specifying the minimum disparity value are present in the syntax structure.

d_max_flag equal to 0 specifies that the syntax elements specifying the maximum disparity value are not present in the syntax structure. d_max_flag equal to 1 specifies that the syntax elements specifying the maximum disparity value are present in the syntax structure.

depth_representation_type specifies the representation definition of decoded luma samples of auxiliary pictures as specified in Table G-3. In Table G-3, disparity specifies the horizontal displacement between two texture views and Z value specifies the distance from a camera.

[Ed. (MH): the semantics should be generalized to apply for other bit-depths than 8 or a constraint should be added that the luma bit-depth for the depth auxiliary pictures shall be equal to 8.]

Table G-3 – Definition of depth_representation_type

depth_representation_type	Interpretation
0	Each decoded luma sample value of an auxiliary picture represents an inverse of Z value that is uniformly quantized into the range of 0 to 255, inclusive. [Ed. (JO): Is this meant to be the range between zfar and znear?]
1	Each decoded luma sample value of an auxiliary picture represents disparity that is uniformly quantized into the range of 0 to 255, inclusive. [Ed. (JO): Is this meant to be the range between dmin and dmax?]
2	Each decoded luma sample value of an auxiliary picture represents a Z value uniformly quantized into the range of 0 to 255, inclusive. [Ed. (JO): Is this meant to be the range between zfar and znear?]
3	Each decoded luma sample value of an auxiliary picture represents a nonlinearly mapped disparity, normalized in range from 0 to 255, as specified by depth_nonlinear_representation_num_minus1 and depth_nonlinear_representation_model[i].
Other values	Reserved for future use

disparity_ref_view_id specifies the ViewId value against which the disparity values are derived. [Ed. (JO): Is this only be useful in representation types 1 and 3? If yes, should a note be added?].

The variables in the x column of Table G-4 are derived as follows from the respective variables in the s, e, n, and v columns of Table G-4 as follows.

– If $0 < e < 127$, $x = (-1)^{s} * 2^{e-31} * (1 + n \div 2^{v})$.

– Otherwise (e is equal to 0), $x = (-1)^{s} * 2^{-(30+v)} * n$.

NOTE 1 – The above specification is similar to that found in IEC 60559:1989, *Binary floating-point arithmetic for microprocessor systems*.

Table G-4 – Association between depth parameter variables and syntax elements

x	s	e	n	v
ZNear	ZNearSign	ZNearExp	ZNearMantissa	ZNearManLen
ZFar	ZFarSign	ZFarExp	ZFarMantissa	ZFarManLen
DMax	DMaxSign	DMaxExp	DMaxMantissa	DMaxManLen
DMin	DMinSign	DMinExp	DMinMantissa	DMinManLen

The DMin and DMax values, when present, are specified in units of a luma sample width of the coded picture with ViewId equal to ViewId of the auxiliary picture.

The units for the ZNear and ZFar values, when present, are identical but unspecified.

[Ed. (JO): It should better be expressed how the values Znear, Zfar, Dmax, Dmin are used to interpret the values in the auxiliary pictures in each of the four depth representation types.]

depth_nonlinear_representation_num_minus1 plus 2 specifies the number of piecewise linear segments for mapping of depth values to a scale that is uniformly quantized in terms of disparity.

depth_nonlinear_representation_model[i] specifies the piecewise linear segments for mapping of decoded luma sample values of an auxiliary picture to a scale that is uniformly quantized in terms of disparity.

NOTE 2 – When depth_representation_type is equal to 3, an auxiliary picture contains nonlinearly transformed depth samples. Variable DepthLUT[i], as specified below, is used to transform coded depth sample values from nonlinear representation to the linear representation – disparity normalized in range from 0 to 255. [Ed. (JO): Not fully clear whether the aux map carries the "coded depth samples" or the "normalized in range from 0 to 255" values. The latter can be assumed, but then the term "coded depth values" might be misleading.] The shape of this transform is defined by means of line-segment approximation in two-dimensional linear-disparity-to-nonlinear-disparity space. The first (0, 0) and the last (255, 255) nodes of the curve are predefined. Positions of additional nodes are transmitted in form of deviations (depth_nonlinear_representation_model[i]) from the straight-

line curve. These deviations are uniformly distributed along the whole range of 0 to 255, inclusive, with spacing depending on the value of nonlinear_depth_representation_num_minus1.

Variable DepthLUT[i] for i in the range of 0 to 255, inclusive, is specified as follows.

```
depth_nonlinear_representation_model[ 0 ] = 0
depth_nonlinear_representation_model[depth_nonlinear_representation_num_minus1 + 2 ] = 0
for( k = 0; k  <=  depth_nonlinear_representation_num_minus1 + 1; k++ ) {
    pos1 = ( 255 * k ) / (depth_nonlinear_representation_num_minus1 + 2 )
    dev1 = depth_nonlinear_representation_model[ k ]
    pos2 = ( 255 * ( k+1 ) ) / (depth_nonlinear_representation_num_minus1 + 2 )
    dev2 = depth_nonlinear_representation_model[ k+1 ]

    x1 = pos1 − dev1
    y1 = pos1 + dev1
    x2 = pos2 − dev2
    y2 = pos2 + dev2

    for( x = Max( x1, 0 ); x  <=  Min( x2, 255 ); x++ )
            DepthLUT[ x ] = Clip3( 0, 255, Round( ( ( x − x1 ) * ( y2 − y1 ) ) ÷ ( x2 − x1 ) + y1 ) )
}
```

When depth_representation_type is equal to 3, DepthLUT[dS] for all decoded luma sample values dS of an auxiliary picture in the range of 0 to 255, inclusive, represents disparity that is uniformly quantized into the range of 0 to 255, inclusive.

G.14.2.2.1 Depth representation SEI element semantics

The syntax structure specifies the value of an element in the depth representation information SEI message.

The syntax structure sets the values of the OutSign, OutExp, OutMantissa, and OutManLen variables that represent a floating-point value. When the syntax structure is included in another syntax structure, the variable names OutSign, OutExp, OutMantissa, and OutManLen are to be interpreted as being replaced by the variable names used when the syntax structure is included. [Ed. (GT): The concept of syntax structures having output variables seems to be new. We might consider allowing alternative concepts. E.g. allowing syntax structures to have an index and dot operations would help also in other parts of the spec. E.g. ZFarExp = depth_rep_sei_element( )[1].da_exponent.]

da_sign_flag equal to 0 indicates that the sign of the floating-point value is positive. da_sign_flag equal to 1 indicates that the sign is negative. The variable OutSign is set equal to da_sign_flag.

da_exponent specifies the exponent of the floating-point value. The value of da_exponent shall be in the range of 0 to $2^7 − 2$, inclusive. The value $2^7 − 1$ is reserved for future use by ITU-T | ISO/IEC. Decoders shall treat the value $2^7 − 1$ as indicating an unspecified value. The variable OutExp is set equal to da_exponent.

da_mantissa_len_minus1 plus 1 specifies the number of bits in the da_mantissa syntax element. The value of da_mantissa_len_minus1 shall be in the range of 0 to 31, inclusive. The variable OutManLen is set equal to da_mantissa_len_minus1 + 1.

da_mantissa specifies the mantissa of the floating-point value. The variable OutMantissa is set equal to da_mantissa.

G.14.2.2.2 Multiview scene information SEI message semantics

[Ed. (MH): It is suggested that the following remarks are considered when revising this SEI message:

1) It is suggested to include both maximum positive disparity (as specified below, for objects perceived behind the screen level) and minimum negative disparity (for objects perceived in front of the screen level).

2) MV-HEVC allows different spatial resolution between views provided that inter-view/inter-layer prediction is not used. In such a case, it should be specified which view/layer is used as reference for the units of luma samples.

3) It should be considered whether it would be desirable to modify this SEI message to concern explicitly specified pairs of layers/views and enable nesting of this SEI message, where the scalable nesting SEI message would imply which layers or views the multiview scene information concerns.

]

[Ed. (GT): Copied from AVC text with following changes: Replaced "view component" by "view".]

The multiview scene information SEI message indicates the maximum disparity among multiple views in an access unit.

The maximum disparity could be used for processing the decoded views prior to rendering on a 3D display. When present, the multiview scene information SEI message shall be associated with an IRAP access unit. The information signalled in the SEI message applies to the coded video sequence.

The actual maximum disparity value may be less than the one signalled in the multiview scene information SEI message, due to that some views in the coded video sequence may have been removed from the original bitstream to produce an extracted sub-bitstream according to the process specified in clause 10.

max_disparity specifies the maximum disparity, in units of luma samples, between spatially adjacent view components among the total set of views in an access unit. The value of max_disparity shall be in the range of 0 to 1023, inclusive.

NOTE – The maximum disparity depends on the baseline distance between spatially adjacent views and the spatial resolution of each view. Therefore, if either the number of views or spatial resolution is changed, the maximum disparity should also be changed accordingly.

G.14.2.2.3 Multiview acquisition information SEI message semantics

[Ed. (MH): It is suggested that the following remarks are considered when revising this SEI message:

1) The multiview acquisition information SEI message of MVC is capable of indicating the camera parameters of both texture views and depth views (when nested in an MVCD scalable nesting SEI message). Similar capability is suggested to be enabled in MV-HEVC.

2) It should be considered whether it would be desirable to modify this SEI message to concern only one view and enable nesting of this SEI message, where the scalable nesting SEI message would imply which layers or views the multiview acquisition information concerns.

3) It should be considered whether it would be desirable to separate intrinsic and extrinsic camera parameters to separate SEI messages. The intrinsic camera parameters SEI message could apply to one view only. If all the cameras share the same intrinsic parameters, a scalable nesting SEI message could be used to indicate that the intrinsic camera parameters apply to all layers/views specified in the scalable nesting SEI message.

4) It should be considered whether the extrinsic camera parameters of a texture view and a depth view with the same ViewId shall be identical. The constraint on num_view_minus1 depends on the answer to this question.

5) The mapping from index i (in the syntax of this SEI message) to either ViewOrderIdx or ViewId shall be specified.

6) To enable more straightforward view synthesis for parallel camera setups, another SEI message should be considered, where the SEI message would include weights and offsets (e.g. similar to what is included in the Depth parameter set of 3D-AVC) for indicating disparity relation between views.

]

The multiview acquisition information SEI message specifies various parameters of the acquisition environment. Specifically, intrinsic and extrinsic camera parameters are specified. These parameters could be used for processing the decoded views prior to rendering on a 3D display. When present, the multiview acquisition information SEI message shall be associated with an IRAP access unit. The information signalled in the SEI message applies to the coded video sequence.

Some of the views for which the multiview acquisition information is included in a multiview acquisition information SEI message may not be present in the coded video sequence.

The extrinsic camera parameters are specified according to a right-handed coordinate system, where the upper left corner of the image is the origin, i.e., the (0, 0) coordinate, with the other corners of the image having non-negative coordinates. With these specifications, a 3-dimensional world point, wP = [x y z] is mapped to a 2-dimensional camera point, cP[i] = [u v 1], for the i-th camera according to:

$$s * cP[i] = A[i] * R^{-1}[i] * (wP - T[i]) \quad \text{(G-8)}$$

where A[i] denotes the intrinsic camera parameter matrix, $R^{-1}[i]$ denotes the inverse of the rotation matrix R[i], T[i] denotes the translation vector, and s (a scalar value) is an arbitrary scale factor chosen to make the third coordinate of cP[i] equal to 1. The elements of A[i], R[i], T[i] are determined according to the syntax elements signalled in this SEI message and as specified below.

num_views_minus1 plus 1 shall be equal to the value of NumViews in the active VPS. The value of num_views_minus1 shall be in the range of 0 to 62, inclusive.

intrinsic_param_flag equal to 1 indicates the presence of intrinsic camera parameters. intrinsic_param_flag equal to 0 indicates the absence of intrinsic camera parameters.

extrinsic_param_flag equal to 1 indicates the presence of extrinsic camera parameters. extrinsic_param_flag equal to 0 indicates the absence of extrinsic camera parameters.

intrinsic_params_equal_flag equal to 1 indicates that the intrinsic camera parameters are equal for all cameras and only one set of intrinsic camera parameters are present. intrinsic_params_equal_flag equal to 0 indicates that the intrinsic camera parameters are different for each camera and that a set of intrinsic camera parameters are present for each camera.

prec_focal_length specifies the exponent of the maximum allowable truncation error for focal_length_x[i] and focal_length_y[i] as given by $2^{-\text{prec\_focal\_length}}$. The value of prec_focal_length shall be in the range of 0 to 31, inclusive.

prec_principal_point specifies the exponent of the maximum allowable truncation error for principal_point_x[i] and principal_point_y[i] as given by $2^{-\text{prec\_principal\_point}}$. The value of prec_principal_point shall be in the range of 0 to 31, inclusive.

prec_skew_factor specifies the exponent of the maximum allowable truncation error for skew factor as given by $2^{-\text{prec\_skew\_factor}}$. The value of prec_skew_factor shall be in the range of 0 to 31, inclusive.

sign_focal_length_x[i] equal to 0 indicates that the sign of the focal length of the i-th camera in the horizontal direction is positive. sign_focal_length_x[i] equal to 1 indicates that the sign is negative.

exponent_focal_length_x[i] specifies the exponent part of the focal length of the i-th camera in the horizontal direction. The value of exponent_focal_length_x[i] shall be in the range of 0 to 62, inclusive. The value 63 is reserved for future use by ITU-T | ISO/IEC. Decoders shall treat the value 63 as indicating an unspecified focal length.

mantissa_focal_length_x[i] specifies the mantissa part of the focal length of the i-th camera in the horizontal direction. The length of the mantissa_focal_length_x[i] syntax element is variable and determined as follows:

– If exponent_focal_length_x[i] is equal to 0, the length is Max(0, prec_focal_length − 30).

– Otherwise (0 < exponent_focal_length_x[i] < 63), the length is Max(0, exponent_focal_length_x[i] + prec_focal_length − 31).

sign_focal_length_y[i] equal to 0 indicates that the sign of the focal length of the i-th camera in the vertical direction is positive. sign_focal_length_y[i] equal to 1 indicates that the sign is negative.

exponent_focal_length_y[i] specifies the exponent part of the focal length of the i-th camera in the vertical direction. The value of exponent_focal_length_y[i] shall be in the range of 0 to 62, inclusive. The value 63 is reserved for future use by ITU-T | ISO/IEC. Decoders shall treat the value 63 as indicating an unspecified focal length.

mantissa_focal_length_y[i] specifies the mantissa part of the focal length of the i-th camera in the vertical direction.

The length of the mantissa_focal_length_y[i] syntax element is variable and determined as follows:

– If exponent_focal_length_y[i] is equal to 0, the length is Max(0, prec_focal_length − 30).

– Otherwise (0 < exponent_focal_length_y[i] < 63), the length is Max(0, exponent_focal_length_y[i] + prec_focal_length − 31).

sign_principal_point_x[i] equal to 0 indicates that the sign of the principal point of the i-th camera in the horizontal direction is positive. sign_principal_point_x[i] equal to 1 indicates that the sign is negative.

exponent_principal_point_x[i] specifies the exponent part of the principal point of the i-th camera in the horizontal direction. The value of exponent_principal_point_x[i] shall be in the range of 0 to 62, inclusive. The value 63 is reserved for future use by ITU-T | ISO/IEC. Decoders shall treat the value 63 as indicating an unspecified principal point.

mantissa_principal_point_x[i] specifies the mantissa part of the principal point of the i-th camera in the horizontal direction. The length of the mantissa_principal_point_x[i] syntax element in units of bits is variable and is determined as follows:

– If exponent_principal_point_x[i] is equal to 0, the length is Max(0, prec_principal_point − 30).

– Otherwise (0 < exponent_principal_point_x[i] < 63), the length is Max(0, exponent_principal_point_x[i] + prec_principal_point − 31).

sign_principal_point_y[i] equal to 0 indicates that the sign of the principal point of the i-th camera in the vertical direction is positive. sign_principal_point_y[i] equal to 1 indicates that the sign is negative.

exponent_principal_point_y[i] specifies the exponent part of the principal point of the i-th camera in the vertical direction. The value of exponent_principal_point_y[i] shall be in the range of 0 to 62, inclusive. The value 63 is reserved for future use by ITU-T | ISO/IEC. Decoders shall treat the value 63 as indicating an unspecified principal

point.

mantissa_principal_point_y[i] specifies the mantissa part of the principal point of the i-th camera in the vertical direction. The length of the mantissa_principal_point_y[i] syntax element in units of bits is variable and is determined as follows:

– If exponent_principal_point_y[i] is equal to 0, the length is Max(0, prec_principal_point − 30).

– Otherwise (0 < exponent_principal_point_y[i] < 63), the length is Max(0, exponent_principal_point_y[i] + prec_principal_point − 31).

sign_skew_factor[i] equal to 0 indicates that the sign of the skew factor of the i-th camera is positive.

sign_skew_factor[i] equal to 1 indicates that the sign is negative.

exponent_skew_factor[i] specifies the exponent part of the skew factor of the i-th camera. The value of exponent_skew_factor[i] shall be in the range of 0 to 62, inclusive. The value 63 is reserved for future use by ITU-T | ISO/IEC. Decoders shall treat the value 63 as indicating an unspecified skew factor.

mantissa_skew_factor[i] specifies the mantissa part of the skew factor of the i-th camera. The length of the mantissa_skew_factor[i] syntax element is variable and determined as follows:

– If exponent_skew_factor[i] is equal to 0, the length is Max(0, prec_skew_factor − 30).

– Otherwise (0 < exponent_skew_factor[i] < 63), the length is Max(0, exponent_skew_factor[i] + prec_skew_factor − 31).

The intrinsic matrix A[i] for i-th camera is represented by

$$\begin{bmatrix} focalLengthX[i] & skewFactor[i] & principalPointX[i] \\ 0 & focalLengthY[i] & principalPointY[i] \\ 0 & 0 & 1 \end{bmatrix} \tag{G-9}$$

prec_rotation_param specifies the exponent of the maximum allowable truncation error for r[i][j][k] as given by $2^{-prec\_rotation\_param}$. The value of prec_rotation_param shall be in the range of 0 to 31, inclusive.

prec_translation_param specifies the exponent of the maximum allowable truncation error for t[i][j] as given by $2^{-prec\_translation\_param}$. The value of prec_translation_param shall be in the range of 0 to 31, inclusive.

sign_r[i][j][k] equal to 0 indicates that the sign of (j, k) component of the rotation matrix for the i-th camera is positive. sign_r[i][j][k] equal to 1 indicates that the sign is negative.

exponent_r[i][j][k] specifies the exponent part of (j, k) component of the rotation matrix for the i-th camera. The value of exponent_r[i][j][k] shall be in the range of 0 to 62, inclusive. The value 63 is reserved for future use by ITU-T | ISO/IEC. Decoders shall treat the value 63 as indicating an unspecified rotation matrix.

mantissa_r[i][j][k] specifies the mantissa part of (j, k) component of the rotation matrix for the i-th camera. The length of the mantissa_r[i][j][k] syntax element in units of bits is variable and determined as follows:

– If exponent_r[i] is equal to 0, the length is Max(0, prec_rotation_param − 30).

– Otherwise (0 < exponent_r[i] < 63), the length is Max(0, exponent_r[i] + prec_rotation_param − 31).

The rotation matrix R[i] for i-th camera is represented as follows:

$$\begin{bmatrix} rE[i][0][0] & rE[i][0][1] & rE[i][0][2] \\ rE[i][1][0] & rE[i][1][1] & rE[i][1][2] \\ rE[i][2][0] & rE[i][2][1] & rE[i][2][2] \end{bmatrix} \tag{G-10}$$

sign_t[i][j] equal to 0 indicates that the sign of the j-th component of the translation vector for the i-th camera is positive. sign_t[i][j] equal to 1 indicates that the sign is negative.

exponent_t[i][j] specifies the exponent part of the j-th component of the translation vector for the i-th camera. The value of exponent_t[i][j] shall be in the range of 0 to 62, inclusive. The value 63 is reserved for future use by ITU-T | ISO/IEC. Decoders shall treat the value 63 as indicating an unspecified translation vector.

mantissa_t[i][j] specifies the mantissa part of the j-th component of the translation vector for the i-th camera. The length v of the mantissa_t[i][j] syntax element in units of bits is variable and is determined as follows:

– If exponent_t[i] is equal to 0, the length v is set equal to Max(0, prec_translation_param − 30).

– Otherwise (0 < exponent_t[i] < 63), the length v is set equal to Max(0, exponent_t[i] + prec_translation_param − 31).

The translation vector T[i] for the i-th camera is represented by:

$$\begin{bmatrix} tE[\,i\,][\,0\,] \\ tE[\,i\,][\,1\,] \\ tE[\,i\,][\,2\,] \end{bmatrix} \tag{G-11}$$

The association between the camera parameter variables and corresponding syntax elements is specified by Table G-5. Each component of the intrinsic and rotation matrices and the translation vector is obtained from the variables specified in Table G-5 as the variable x computed as follows:

– If $0 < e < 63$, $x = (-1)^{s} * 2^{e-31} * (1 + n \div 2^{v})$.

– Otherwise (e is equal to 0), $x = (-1)^{s} * 2^{-(30+v)} * n$.

NOTE – The above specification is similar to that found in IEC 60559:1989, *Binary floating-point arithmetic for microprocessor systems.*

[Ed. (GT): As in AVC spec, the specification of v is missing for some variables. Shall we add it and shorten syntax element names? Or is it better to keep names to be consistent with AVC?]

Table G-5 – Association between camera parameter variables and syntax elements.

x	s	e	n
focalLengthX[i]	sign_focal_length_x[i]	exponent_focal_length_x[i]	mantissa_focal_length_x[i]
focalLengthY[i]	sign_focal_length_y[i]	exponent_focal_length_y[i]	mantissa_focal_length_y[i]
principalPointX[i]	sign_principal_point_x[i]	exponent_principal_point_x[i]	mantissa_principal_point_x[i]
principalPointY[i]	sign_principal_point_y[i]	exponent_principal_point_y[i]	mantissa_principal_point_y[i]
skewFactor[i]	sign_skew_factor[i]	exponent_skew_factor[i]	mantissa_skew_factor[i]
rE[i][j][k]	sign_r[i][j][k]	exponent_r[i][j][k]	mantissa_r[i][j][k]
tE[i][j]	sign_t[i][j]	exponent_t[i][j]	mantissa_t[i][j]

G.14.2.2.4 Multiview view position SEI message semantics

The multiview view position SEI message specifies the relative view position along a single horizontal axis of views within a CVS. When present, the multiview view position SEI message shall be associated with an IRAP access unit. The information signalled in this SEI message applies to the entire CVS.

num_views_minus1 plus 1 shall be equal to NumViews derived from the active VPS for the CVS. The value of num_views_minus1 shall be in the range of 0 to 62, inclusive.

view_position[i] indicates the order of the view with ViewOrderIndex equal to i among all the views from left to right for the purpose of display, with the order for the left-most view being equal to 0 and the value of the order increasing by 1 for next view from left to right. The value of view_position[i] shall be in the range of 0 to 62, inclusive.

multiview_view_position_extension_flag equal to 0 indicates that no additional data follows within the multiview view position SEI message. The value of multiview_view_position_extension_flag shall be equal to 0. The value of 1 for multiview_view_position_extension_flag is reserved for future use by ITU-T | ISO/IEC. Decoders shall ignore all data that follows the value of 1 for multiview_view_position_extension_flag in a multiview view position SEI message.

G.15 Video usability information

The specifications in clause F.15 apply.